

FINAL
DRAFT

INTERNATIONAL
STANDARD

ISO/FDIS
8092-5

ISO/TC 22/SC 32

Secretariat: JISC

Voting begins on:
2020-10-21

Voting terminates on:
2020-12-16

Road vehicles — Connections for on-board electrical wiring harnesses —

Part 5: Test methods and general performance requirements for wiring harness connector operation

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Véhicules routiers — Connexions pour faisceaux de câblage électrique embarqués —

Partie 5: Méthodes d'essai et exigences générales de performance pour le raccordement du connecteur du faisceau de câblage

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Reference number
ISO/FDIS 8092-5:2020(E)

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Published in Switzerland

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 32, *Electrical and electronic components and general system aspects*.

A list of all parts in the ISO 8092 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

Along with the increase of electrical components mounted on a road vehicle, the types and numbers of connectors mounted on the automobile increase and the connector mating work becomes harder in such circumstances. Especially from the viewpoint of ergonomics, this problem is addressed seriously. To comprehend the characteristics of connector mate/unmate operation, their test procedures are specified in this document.

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Road vehicles — Connections for on-board electrical wiring harnesses —

Part 5: Test methods and general performance requirements for wiring harness connector operation

1 Scope

This document defines terms and specifies test methods and general performance requirements for single-pole and multi-pole connections used with on-board electrical wiring harnesses of road vehicles. This document is applicable to connectors designed to be disconnected after mounting in the vehicle for repair and maintenance only. It does not cover one-part connections, i.e. where one part of the connection has direct contact to the pattern of the printed circuit board. This document is not applicable to internal connections of electronic devices.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 19642 (all parts), *Road vehicles — Automotive cables*
IEC 61672-1, *Electroacoustics — Sound level meters — Part 1: Specifications*

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <http://www.electropedia.org/>

3.1

male connector

assembly of male *terminal* (3.3) and housing that terminates conductors for the purpose of providing connection and disconnection to a suitable mating connector

3.2

female connector

assembly of female *terminal* (3.3) and housing that terminates conductors for the purpose of providing connection and disconnection to a suitable mating connector

3.3

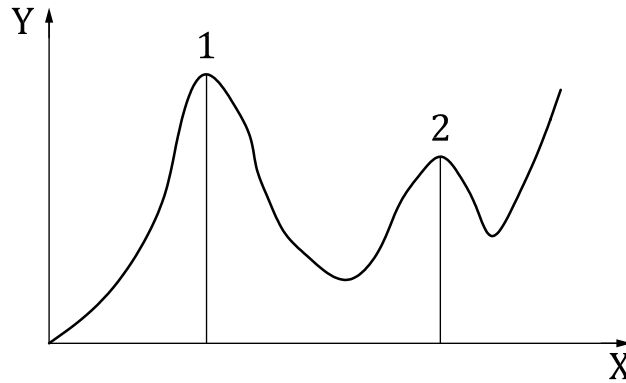
terminal

connector contact connected with a corresponding element of the same purpose, used to form an electric circuit (including wiring parts)

3.4 inertial lock

connector locking mechanism designed so that the lock peak comes before contact is established between male and female *terminal* (3.3) and becomes higher than the terminal connection peak in the connector mating process

Note 1 to entry: It is applicable only to connectors without lever/slider. See [Figure 1](#).



- Key**
- 1 lock peak
 - 2 terminal connection peak
 - X mating stroke
 - Y mating force

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Figure 1 — Inertial lock

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4 Tests and requirements

4.1 General

4.1.1 Preconditioning

All test samples shall be preconditioned at (23 ± 5) °C and 45 % to 75 % relative humidity for 24 h before the start of any test sequence.

4.1.2 Measurement condition

All measurements shall be performed with unused samples at (23 ± 5) °C and 45 % to 75 % relative humidity unless otherwise specified. Cables shall be in compliance with applicable part of the ISO 19642 series and cables used shall be noted in the test report.

The cable attachment shall be performed in accordance with the terminal manufacturer's specifications, or as agreed between customer and supplier.

4.2 Mating force measurement and classification

4.2.1 Sample preparation

Prepare a minimum of 10 samples consisting of fully populated male connectors and female connectors.

If a mating connector is not available, a device interface may be used to carry out tests. This shall represent the intended device's interface.

4.2.2 Test procedure

Test procedure is as follows.

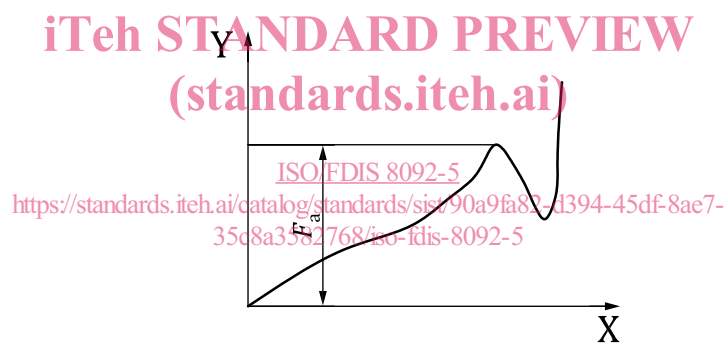
- Mate the connectors at constant speed of 50 ± 10 mm/min, and then record the mating force diagram. (Refer to [Figures 2](#) to [4](#).)
- Write the applied mating speed on the measurement report.
- Repeat steps a) and b) for the samples.

4.2.3 Classification

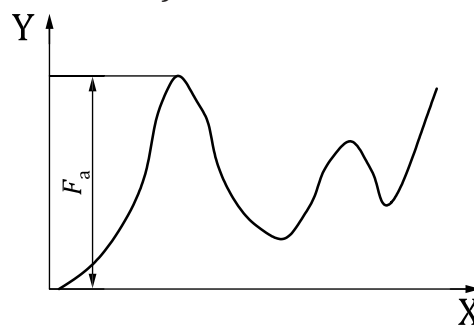
- For the mating force, use the maximum mating force (F_a), which is defined in [Figure 2](#) a) and b), and classify it in accordance with [Table 1](#).

Table 1 — Mating force

Class	Value of F_a (N)
1	$F_a \leq 45$
2	$45 < F_a \leq 70$
3	$F_a > 70$



a) Normal lock



b) Inertial lock

Key

- X stroke (mm)
Y mating force (N)

Figure 2 — Maximum mating force (F_a)

- For the mating stroke, use the stroke (S), which is defined in [Figure 3a](#)) and b), and classify it in accordance with [Table 2](#).