
**Multimedijski sistemi in oprema za vozila - Sistem prostorskega pogleda - 3. del:
Merilne metode**

Multimedia Systems and equipment for vehicle - Surround view system - Part 3:
Measurement methods

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Systèmes et équipements multimédias pour véhicules - Système de vision panoramique
- Partie 3: Méthodes de mesurage

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43.040.15	Avtomobilska informatika. Vgrajeni računalniški sistemi	Car informatics. On board computer systems

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100/3586/CDV

COMMITTEE DRAFT FOR VOTE (CDV)

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CLOSING DATE FOR VOTING:

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IEC TA 17 : MULTIMEDIA SYSTEMS AND EQUIPMENT FOR VEHICLES

SECRETARIAT:

Korea, Republic of

SECRETARY:

Mr Ock-Woo Nam

OF INTEREST TO THE FOLLOWING COMMITTEES:

PROPOSED HORIZONTAL STANDARD:



Other TC/SCs are requested to indicate their interest, if any, in this CDV to the secretary.

FUNCTIONS CONCERNED:

☐ EMC☐ ENVIRONMENT☐ QUALITY ASSURANCE☐ SAFETY☒ SUBMITTED FOR CENELEC PARALLEL VOTING☐ NOT SUBMITTED FOR CENELEC PARALLEL VOTING

Attention IEC-CENELEC parallel voting

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The CENELEC members are invited to vote through the CENELEC online voting system.

This document is still under study and subject to change. It should not be used for reference purposes.

Recipients of this document are invited to submit, with their comments, notification of any relevant patent rights of which they are aware and to provide supporting documentation.

TITLE:

Multimedia Systems and equipment for vehicle - Surround view system - Part 3: Measurement methods

PROPOSED STABILITY DATE: 2024

NOTE FROM TC/SC OFFICERS:

In the voting for the maintenance of 63033-1,2,3 and 4, the 63033-1 and 4 received comments.

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CONTENTS

FOREWORD	3
INTRODUCTION	5
1 Scope	6
2 Normative references	6
3 Terms, definitions and abbreviated terms	6
3.1 Terms and definitions	6
3.2 Abbreviated terms	6
4 System model	6
5 Camera image quality	7
5.1 Camera resolution	7
5.2 Camera image quality	7
6 Camera calibration	7
6.1 General	7
6.2 Verification	7
7 Field of view	9
8 Time behaviour	9
8.1 Start-up time	9
8.2 Frame rate	9
8.3 Latency	10
Annex A (informative) Field of view (FOV)	11
Bibliography	17
Figure 1 – System model of surround view system	7
Figure 2 – Orthogonal Reference	8
Figure 3 – Reference Guideline	9
Figure A.1 – Example view for Class I FOV	11
Figure A.2 – Example view for Class II FOV	12
Figure A.3 – Example view for Class III FOV	13
Figure A.4 – Example view for Class IV FOV	13
Figure A.5 – Example view for Class V FOV	14
Figure A.6 – Example view for Larger FOV on the passenger side	14
Figure A.7 – Example view for Class VI FOV	15
Figure A.8 – Example view for FOV of 5.4.1 defined in UN REGULATION No. 125	16

INTERNATIONAL ELECTROTECHNICAL COMMISSION

**MULTIMEDIA SYSTEMS AND EQUIPMENT FOR VEHICLES–
SURROUND VIEW SYSTEM****Part 3: Measurement methods****FOREWORD**

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International Standard IEC 63033-3 has been prepared by technical area 17: Multimedia systems and equipment for vehicles of IEC technical committee 100: Audio, video and multimedia systems and equipment.

The text of this International Standard is based on the following documents:

FDIS	Report on voting
XX/XX/FDIS	XX/XX/RVD

Full information on the voting for the approval of this International Standard can be found in the report on voting indicated in the above table.

This document has been drafted in accordance with the ISO/IEC Directives, Part 2.

88 The committee has decided that the contents of this document will remain unchanged until the
89 stability date indicated on the IEC website under "http://webstore.iec.ch" in the data related to
90 the specific document. At this date, the document will be

- 91 • reconfirmed,
- 92 • withdrawn,
- 93 • replaced by a revised edition, or
- 94 • amended.

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99

INTRODUCTION

100 This document specifies measurement methods for the surround view system that is specified
101 in IEC International Specification 63033-1. IEC 63033-1 specifies the model for generating the
102 surrounding visual image of a surround view system. The system allows drivers to monitor the
103 car's perimeter in real time by using "free eye point" technology, which allows drivers to
104 dynamically change the viewing perspective to obtain the most appropriate views according to
105 the driving situation.

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MULTIMEDIA SYSTEMS AND EQUIPMENT FOR VEHICLES– SURROUND VIEW SYSTEM

Part 3: Measurement methods

1 Scope

This document specifies measurement methods for the surround view system that is specified in IEC 63033-1.

2 Normative references

The following documents are referred to in the text in such a way that any of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 63033-1:2020, *Multimedia systems and equipment for vehicles– Surround view system – Part 1: General*

ISO 16505:2019, *Road vehicles- Ergonomic and performance aspects of Camera Monitor Systems – Requirements and test procedures*

UN Regulation No. 46, *Uniform provisions concerning the approval of devices for indirect vision and of motor vehicles with regards to the installation of these devices*

UN Regulation No. 125, *Uniform provisions concerning the approval of motor vehicles with regards to the forward field of vision of the motor vehicle driver*

3 Terms, definitions and abbreviated terms

3.1 Terms and definitions

No terms and definitions are listed in this document.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at <http://www.electropedia.org/>
- ISO Online browsing platform: available at <http://www.iso.org/obp>

3.2 Abbreviated terms

FOV field of view

4 System model

A surround view system shall generate multiple camera composite images and/or single camera images, using cameras that are mounted on the outside the car. The views to be generated by this system shall capture the fields of view specified in Clause 7. This system shall generate multiple views according to the fields of view to be secured. For measurement methods, the system shall refer to ISO 16505 and UN REGULATION No. 46. However, the system does not need to fully comply with ISO 16505 and UN REGULATION No. 46.

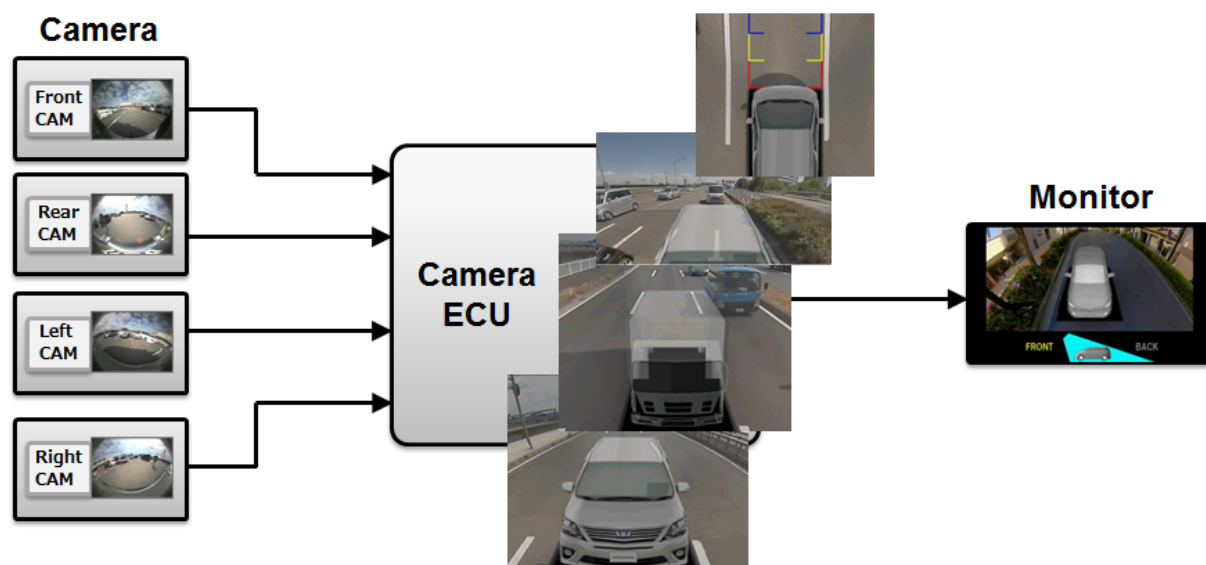


Figure 1 – System model of surround view system

5 Camera image quality

5.1 Camera resolution

The resolution of the camera shall be 300 000 pixels or more.

5.2 Camera image quality

The camera's image quality shall comply with ISO 6505, 6.7, and shall be measured as specified in ISO 16505, 7.8. The monitor image quality shall comply with ISO 16505, 6.7, and shall be measured as specified in ISO 16505, 7.8, as well. For the measurement of the camera's image quality, the monitor mentioned above shall be used.

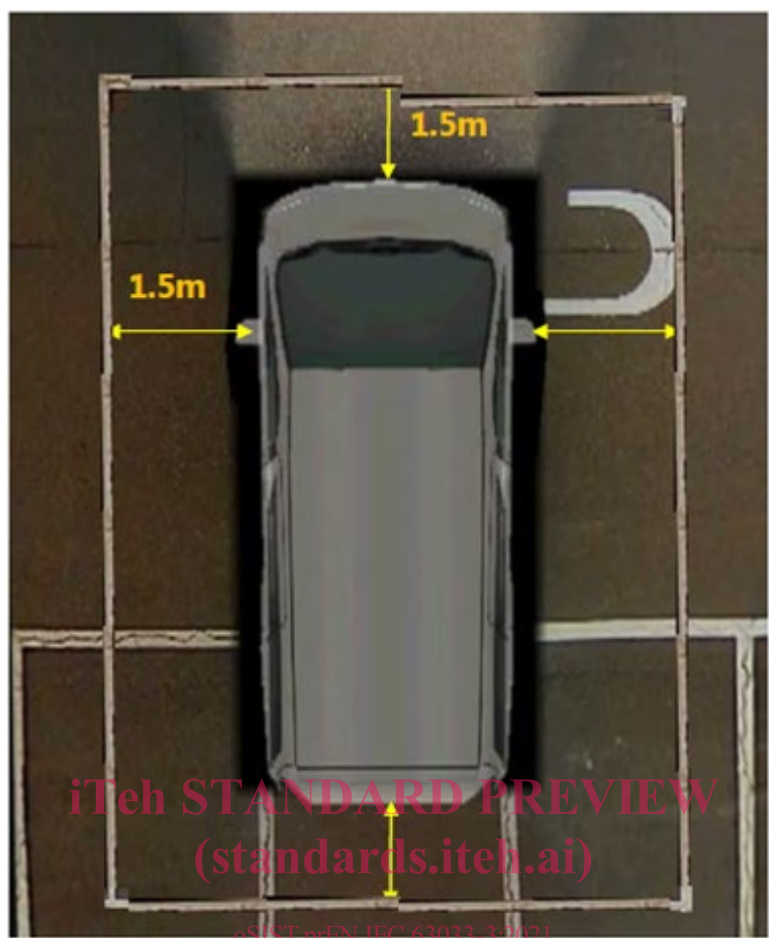
6 Camera calibration

6.1 General

The calibration of the camera shall be performed as specified in Annex C of IEC 63033-1:2020.

6.2 Verification

Draw an orthogonal frame at a distance of 1,5 m from the outline of the vehicle; this frame is to be captured within the camera's image. This frame is shown in Figure 2 and can be seen on the captured camera image. The guideline shown in Figure 3 representing the frame 1,5 m around the car's body that is later drawn on the composite video shall match up within a tolerance of 10 cm.



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<https://standards.iteh.ai/catalog/standards/sist/336ba23d-d0e7-4778-b498-f1d179b2e50a/iec-63033-3-2021>**Figure 2 – Orthogonal reference**