# TECHNICAL SPECIFICATION

Second edition 2019-06

## Intelligent transport systems — Cooperative ITS — Using V2I and I2V communications for applications related to signalized intersections

Systèmes intelligents de transport — Coopérative ITS — Utilisation de communications V2I et I2V pour des applications relatives aux **iTeh STintersections signalées REVIEW** 

## (standards.iteh.ai)

ISO/TS 19091:2019 https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dcae77e8bb4546/iso-ts-19091-2019



Reference number ISO/TS 19091:2019(E)

ISO/TS 19091:2019 https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dcae77e8bb4546/iso-ts-19091-2019



### **COPYRIGHT PROTECTED DOCUMENT**

#### © ISO 2019

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office CP 401 • Ch. de Blandonnet 8 CH-1214 Vernier, Geneva Phone: +41 22 749 01 11 Fax: +41 22 749 09 47 Email: copyright@iso.org Website: www.iso.org

Published in Switzerland

ISO/TS 19091:2019 https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dcae77e8bb4546/iso-ts-19091-2019

## Contents

## Page

Forew	ord	vi
Introd	uction	vii
1	Scope	1
2	Normative references	1
3	Terms and definitions	2
4	Abbreviated terms	10
5	General description (informative)	
5.1	Overview	
5.2	Functional model	12
5.2.1	Description	12
5.2.2	Architecture	14
5.2.3	Message interactions	16
5.2.4	Common operational assumptions	16
5.3	Safety use cases.	18
5.3.1	Intent (standards.iteh.ai)	18
5.3.2	Additional assumptions	18
5.3.3	Architecture implications	
5.4	Mobility/sustainability/use/casesai/catalog/standards/sist/a6d32fbd-72a7-4ac6-86do	
5.4.1	Intent	19
5.4.2	Additional assumptions	19
5.4.3	Architecture implications	
5.5	Priority/pre-emption use cases	20
5.5.1	Intent	20
5.5.2	Additional assumptions	
5.5.3	Architecture implications	21
5.5.4	Public transport signal priority application	22
5.5.5	Freight vehicle signal priority application	23
5.5.6	Emergency (public safety) vehicle pre-emption application	25
6	Function description (informative)	
6.1	Public safety vehicle	
6.1.1	Broadcast public safety vehicle information	
6.1.2	Broadcast emergency response indication	26
6.2	Signal pre-emption	
6.2.1	Signal pre-empt request (normal power)	26
6.2.2	Signal pre-empt request (high power)	
6.2.3	Request signal pre-empt — Message identifier	
6.2.4	Request signal pre-empt — Intersection identifier	
6.2.5	Request signal pre-empt — Approach lane	
6.2.6	Request signal pre-empt — Egress lane	
6.2.7	Request signal pre-empt — Vehicle class	
6.2.8	Request signal pre-empt — Time of service	
6.2.9	Request signal pre-empt — Vehicle identity	28

6.2.10	Request signal pre-empt — Vehicle location and speed	28
	Request signal pre-empt — Cancellation	
6.2.12	Request signal pre-empt — Transaction identifier	
	Request signal pre-empt — Duration	
6.3	Public transport and commercial vehicle	28
6.3.1	Broadcast priority requesting vehicle information	
6.4	Signal priority requirements	29
6.4.1	Signal priority request	29
6.4.2	Request signal priority — Message identifier	29
6.4.3	Request signal priority — Intersection identifier	29
6.4.4	Request signal priority — Approach lane	
6.4.5	Request signal priority — Egress lane	29
6.4.6	Request signal priority — Vehicle class	
6.4.7	Request signal priority — Time of service	
6.4.8	Request signal priority — Vehicle identity	
6.4.9	Request signal priority — Vehicle location and speed	
6.4.10	Request signal priority — Service information	
	Request signal priority cancellation	
	Request signal priority — Priority request level	
6.4.13	Request signal priority — Transaction identifier	
	Request signal priority — Duration	
	Request signal priority — Transit schedule	
6.5	Broadcast area's geometrics	
6.5.1	Broadcast area's geometrics	
6.5.2	Broadcast roadway geometrics + Messageridentifier	
6.5.3	Broadcast roadway geometrics – Message identifier Broadcast intersection – Identifier	
6.5.4	Broadcast intersection — Reference point	
6.5.5	Broadcast intersection — Lane/approach default width	
6.5.6	Broadcast intersection — Egress lanes/approach	
6.5.7	Broadcast intersection — Ingress lanes/approach	
6.5.8	Broadcast intersection — Lane/approach number	
6.5.9	Broadcast intersection — Lane/approach centerline coordinates	
	Broadcast intersection — Vehicle lane/approach manoeuvres	
	Broadcast intersection — Pedestrian crossing lane/approach manoeuvres	
	Broadcast intersection — Special lane/approach manoeuvres	
	Broadcast intersection — Version identifier	
	Broadcast intersection — Crossings	
	Broadcast intersection — Lane/approach width	
	Broadcast intersection — Node lane/approach width	
	Broadcast intersection — Egress connection	
6.5.18	Broadcast intersection — Traffic control	
	Broadcast intersection — Traffic control by lane/approach	
	Broadcast road conditions	
	Broadcast intersection — Signal group	
6.6	Broadcast GNSS augmentation details	
6.6.1	Broadcast GNSS augmentations	
6.6.2	Broadcast GNSS augmentation detail — NMEA	
6.6.3	Broadcast GNSS augmentation detail — RTCM	
6.7	Signalized intersection requirements	
6.7.1	Broadcast signal phase and timing information	
6.7.2	Broadcast signal phase and timing – Message identifier	
6.7.3	Broadcast signal phase and timing — Intersection identifier	
	-	

6.7.4	Broadcast signal phase and timing — Intersection status	36
6.7.5	Broadcast signal phase and timing — Timestamp	37
6.7.6	Broadcast manoeuvre — Signal group	
6.7.7	Broadcast manoeuvre – Manoeuvre state	
6.7.8	Broadcast manoeuvre — Vehicular state	
6.7.9	Broadcast manoeuvre – Pedestrian state	
	Broadcast manoeuvre — Special state	
6711	Broadcast manoeuvre — Time of change — Minimum	
6712	Broadcast manoeuvre — Time of change — Maximum	20
	Broadcast manoeuvre — Succeeding signal indications	
	Broadcast manoeuvre — Succeeding signal indication time of change	
	Broadcast manoeuvre pending manoeuvre start time	
	Broadcast manoeuvre – Pedestrian detect	
	Broadcast manoeuvre — Pedestrian detect Broadcast manoeuvre — Pedestrian call	
	Broadcast manoeuvre — Optimal speed information	
	Broadcast manoeuvre — Signal progression information	
6.7.20	Broadcast manoeuvre – Egress lane queue	39
6.7.21	Broadcast manoeuvre – Egress lane storage availability	40
	Broadcast manoeuvre — Wait indication	
6.8	Broadcast cross traffic sensor information	
6.9	Broadcast vulnerable road user sensor information	
6.10	Broadcast dilemma zone violation warning	
6.11	Broadcast signal preferential treatment status Broadcast preferential treatment — Signal status message	40
6.11.1	Broadcast preferential treatment - Signal status message	40
6.11.2	Broadcast preferential treatment — Message identifier	41
	Broadcast preferential treatment — Intersection identifier	
6.11.4	Broadcast preferential treatment — Intersection status	41
6.11.5	Broadcast preferential treatment — Prioritization request status Broadcast preferential treatment — Venicle source Broadcast preferential treatment — Transaction identifier	41
6.11.6	Broadcast preferential treatment — Venicle source	41
6.11.7	Broadcast preferential treatment — Transaction identifier	41
6.12	Message identifier	41
6.13	System performance requirements	42
6.13.1	Broadcast intersection — Computed lane/approach	42
6.14	Transmission rates — Signal preferential treatment	
6.14.1	Maximum transmission rate — Request signal preferential treatment	42
	Maximum response time — Request signal preferential treatment	
	Minimum transmission rate — Signal status message	
	Minimum transmission period — Signal status message	
6.15	Transmission rate requirements — Broadcast roadway geometrics information	
	Minimum transmission rate — Broadcast roadway geometrics information	
	Maximum transmission rate — Broadcast roadway geometrics information	
	Default transmission rate — Broadcast roadway geometrics information	
6.16	Transmission rate requirements — GNSS augmentations detail broadcasts	
	Minimum transmission rate — GNSS augmentation details broadcasts	
	Default transmission rate — GNSS augmentation details broadcasts	
6.17	Transmission rate requirements — Broadcast signal phase and timing information	
	Minimum transmission rate — Broadcast signal phase and timing information	
	Maximum transmission rate — Broadcast signal phase and timing information	
	Default transmission rate — Broadcast signal phase and timing information	
6.18	Transmission rate requirements — Broadcast cross traffic sensor information	
	Minimum transmission rate — Broadcast cross traffic sensor information	
	Maximum transmission rate — Broadcast cross traffic sensor information	
	Default transmission rate — Broadcast cross traffic sensor information	
0.10.3	Default if alisillissivili fate — Di vautast ti vss traffit sellsvi fillvrillativili	44

6.19	Transmission rate requirements — Broadcast vulnerable road user sensor	
	information	44
6.19.1	Transmission rate — Broadcast vulnerable road user sensor information	44
6.19.2	Maximum transmission rate — Broadcast vulnerable road user sensor information	44
6.19.3	Default transmission rate — Broadcast vulnerable road user sensor information	44
7	Messages	44
8	Conformance	45
Annex	A (informative) Use cases	46
Annex	B (informative) Use case to requirements traceability	110
Annex	C (informative) Requirements traceability matrix	127
Annex	D (normative) Extension procedures	143
	E (normative) Profile A for J2735 <sup>™</sup>	
Annex	F (normative) Profile B for J2735 <sup>™</sup>	148
Annex	G (normative) Profile C for J2735 <sup>™</sup>	173
Bibliog	graphy	233

ISO/TS 19091:2019 https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dcae77e8bb4546/iso-ts-19091-2019

### Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see <a href="https://www.iso.org/directives">www.iso.org/directives</a>).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see <a href="https://www.iso.org/patents">www.iso.org/patents</a>).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement. **iTeh STANDARD PREVIEW** 

For an explanation of the voluntary **nature of standards; the meaning** of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see <u>www.iso.org/iso/foreword.html</u>tandards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dc-

ae77e8bb4546/iso-ts-19091-2019 This document was prepared by Technical Committee ISO/TC 204, *Intelligent transport systems*.

This second edition cancels and replaces the first edition (ISO/TS 19091:2017), which has been technically revised.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at <u>www.iso.org/members.html</u>.

### Introduction

Cooperative-ITS (C-ITS) is a promising and remarkable advancement of intelligent transport systems (ITS). Numerous cooperative applications are specified that open up new possibilities to make traffic safer, more efficient, and smarter. Technologies are developed and improved to realize and support those new services and applications. To enable those applications, information needs to be reliably communicated between the stationary infrastructure and mobile vehicles.

This document describes the use cases for several applications that address safety, mobility, and ecological sustainability. Each use case has information needs that communication between vehicles and the infrastructure facilitate. It then identifies the information needs for the applications and the requirements to satisfy them. In turn, it maps the requirements into data frames and data elements to fulfil the requirements within the specified message set.

ISO 22951 has a relationship to this document. PRESTO addresses its user needs through the implementation of a specific system architecture similar to that described in NTCIP 1211. This architecture includes traffic signals, message signs, routing systems, human machine interfaces, and fixed detection locations. Many of PRESTO's data value details are "left undefined to allow for discretional definition by each country." The PRESTO architecture detects priority requesting vehicles by installing specific detection equipment at these locations.

This document uses a similar set of user needs to develop the message set between vehicles and the roadside equipment they interface. This document does not address the system architecture other than data needed to fulfil the user needs that will be managed elsewhere in the architecture. It details data values and structures in order to define the interface between these two devices. Routing information is supported in the architecture through other mechanisms and is not a need supported by the vehicle to roadside equipment information flows. The user needs also provide for priority by approach, a preconfigured strategy, and ingress/egress lane requests. This document is based on vehicles periodically broadcasting their location and trajectory information to other vehicle location and request information directly from connected vehicles rather than the detection of the vehicles from other fixed sensing equipment. It does not address the architecture data flows and operations that are detailed within ISO 22951. In other terms, this document provides a connected vehicle alternative for request and status communication without impacting the back office or local intersection operations of priority management.

ISO/TS 19091:2019 https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dcae77e8bb4546/iso-ts-19091-2019

## Intelligent transport systems — Cooperative ITS — Using V2I and I2V communications for applications related to signalized intersections

### 1 Scope

This document defines the message, data structures, and data elements to support exchanges between the roadside equipment and vehicles to address applications to improve safety, mobility and environmental efficiency. In order to verify that the defined messages will satisfy these applications, a systems engineering process has been employed that traces use cases to requirements and requirements to messages and data concepts.

This document consists of a single document that contains the base specification and a series of annexes. The base specification lists the derived information requirements (labelled informative) and references to other standards for message definitions where available. Annex A contains descriptions of the use cases addressed by this document. Annexes B and C contain traceability matrices that relate use cases to requirements and requirements to the message definitions (i.e. data frames and data elements). The next annexes list the base message requirements and application-oriented specific requirements (requirements traceability matrix) that map to the message and data concepts to be implemented. As such, an implementation consists of the base plus an additional group of extensions within this document.

Details on information requirements, for other than SPaT, MAP, SSM, and SRM messages are provided in other International Standards. The focus of this document is to specify the details of the SPaT, MAP, SSM, and SRM supporting the use cases defined in this document. Adoption of these messages varies by region and their adoption can occur over a significant time period.<sup>4</sup>

This document covers the interface between roadside equipment and vehicles. Applications, their internal algorithms, and the logical distribution of application functionality over any specific system architecture are outside the scope of this document.

### 2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE As this document contains multiple profiles, the reference's associated profile(s) are listed within braces.

ISO 22951, Data dictionary and message sets for preemption and prioritization signal systems for emergency and public transport vehicles (PRESTO) {A, B}

ISO 26684, Intelligent transport systems (ITS) — Cooperative intersection signal information and violation warning systems (CIWS) — Performance requirements and test procedures {B}

SAE J2735:2016, Dedicated Short Range Communications (DSRC) Message Set Dictionary {A, B, C}

ARIB STD-T109, 700 MHz Band Intelligent Transport Systems {B}

ITS FORUM RC-010, 700 MHz Band Intelligent Transport Systems — Extended Functions Guideline, published on March 15, 2012 {B}

ETSI/TS 102 894-2 V1.3.1, Intelligent Transport Systems (ITS); Users and applications requirements; Part 2: Applications and facilities layer; common data dictionary {C}

### 3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— IEC Electropedia: available at http://www.electropedia.org/

ISO Online browsing platform: available at <u>http://www.iso.org/obp</u>

NOTE This document requires the understanding of the terminology used in the context of C-ITS and the various devices involved in its implementation. As a result, the following terms contain important information to set the context of the discussions which follow in the remaining sections of this document.

#### 3.1

#### active manoeuvre

traveller paths (vehicles, pedestrians, bicyclists, etc.) that are allowed and have the right of way to enter and move through the path

Note 1 to entry: This term supersedes allowed movements which means, in the context of this document, the directions of manoeuvre that are legally allowed at a specific point in time based upon the state of the intersection signals.

Note 2 to entry: Formerly known as active movements. 19091:2019

https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dcae77e8bb4546/iso-ts-19091-2019

### 3.2

# aftermarket safety device ASD

*connected device* (3.8) in a *vehicle* (3.50) that operates while the vehicle is mobile, but which is not fully integrated into the vehicle systems (as opposed to an OEM device that is pre-installed into the vehicle systems)

#### 3.3

#### allowed manoeuvre

traveller paths, e.g. vehicles, pedestrians, bicyclists, legally permitted to be performed when moving from/into a *lane* (3.21) or between lanes

#### 3.4

#### application

software designed to help users perform particular tasks or handle particular types of problems, as distinct from software that controls the computer itself

Note 1 to entry: In the context of this document, it is a software program that provides functionality to realize safety, mobility, and environmental benefits.

[SOURCE: ISO/IEC 26514:2008, 4.5, modified – Term 'application software' changed to 'application' and Note 1 to entry added.]

### 3.5

#### **Barnes dance**

signal phase that stops vehicular manoeuvres and allows pedestrian manoeuvres to exclusively occur across the *intersection* (3.17) including diagonally moving between corners

Note 1 to entry: Also referred to as a scramble, or "X" crossing. The term refers to Henry Barnes, a deceased traffic engineer.

#### 3.6

#### commercial motor vehicle

self-propelled or towed motor *vehicle* (3.50) used on a highway in commerce to transport passengers or property when that vehicle is subject to regulations determined by the jurisdiction as to its use on the road system of the jurisdiction in regulated circumstances and

- a) has a gross vehicle weight rating or gross combination weight rating, or gross vehicle weight or gross combination weight, of 4 536 kg (10 001 pounds) or more, whichever is greater,
- b) is designed or used to transport more than 8 passengers (including the driver) for compensation,
- c) is designed or used to transport more than 15 passengers, including the driver, and is not used to transport passengers for compensation

#### 3.7

#### commercial motor vehicle on board equipment **D PREVIEW**

*OBE* (3.29) or *ASD* (3.2) mounted or in a *vehicle* (3.50) moving goods, heavy equipment, or people (standards.iteh.ai)

ISO/TS 19091:2019

Note 1 to entry: Vehicles include tractor-trailer combinations, panel trucks, and motor coaches.

#### 3.8

3.8 https://standards.iteh.ai/catalog/standards/sist/a6d32fbd-72a7-4ae6-86dc-

connected device ae77e8bb4546/iso-ts-19091-2019

device used to transmit to or receive messages from another device

Note 1 to entry: A connected device can be sub-categorized as an OBE (3.29), ASD (3.2), or RSE (3.39).

Note 2 to entry: In many cases, the connected device will be a DSRC (3.10) device, but other types of communications could be supported.

#### 3.9

#### connected vehicle

vehicle that contains a *connected device* (3.8)

#### 3.10

# dedicated short range communications DSRC

technology for the transmission of information between multiple *vehicles* (3.50) (V2V) and between vehicles and the transportation infrastructure (V2I and I2V) using wireless technologies

Note 1 to entry: It is characterized as having a limited distance (approximately 300 m) but is assumed to be low latency to establish a connection and exchange information.

Note 2 to entry: Alternative definition - means of effecting (short-range) transactions between fixed equipment and OBE(s) using an "air interface" comprising inductive or propagated signals between the fixed equipment and OBE(s).

#### 3.11

#### eco-driving

practice of driving in such a way as to minimize fuel consumption and emissions

#### 3.12

#### eco-lane

dedicated *lane(s)* (3.21) optimized for *eco-driving* (3.11) similar to high-occupancy vehicle lanes

Note 1 to entry: However, these lanes are optimized for the environment using connected vehicle data.

Note 2 to entry: These lanes would be targeted toward low-emission, high-occupancy freight, public transport, and alternative-fuel vehicles (AFV).

Note 3 to entry: Drivers would be able to opt-in to these dedicated eco-lanes to take advantage of eco-friendly applications such as eco-speed limits, eco-cooperative adaptive cruise control, and connected eco-driving applications.

#### 3.13

#### electronic on-board recorder

device on-board a commercial *vehicle* (3.50) used to record driver information such as hours of service

#### 3.14

#### inactive manoeuvre

traveller paths, e.g. vehicles, pedestrians, bicyclists, that are allowed and do not have the right of way to enter and move through the path en Standard PREVER

#### 3.15

## (standards.iteh.ai)

#### intelligent transportation system ITS

#### ISO/TS 19091:2019

transport system in which advanced information, communication, sensor, and control technologies, including the Internet, are applied to increase safety, sustainability, efficiency, and comfort

Note 1 to entry: Another appropriate meaning of the ITS acronym is integrated transportation systems, which stresses that ITS systems will often integrate components and users from many domains, both public and private.

[SOURCE: ISO/TR 17465-1:2014, 2.3, modified – Note 1 to entry added.]

#### 3.16

#### interoperability

ability of two or more systems or components to exchange information and to use the information that has been exchanged

[SOURCE: IEEE 610.12-1990]

#### 3.17

#### intersection

nexus where two or more approaches (*links*) (3.26) meet and *vehicles* (3.50) and other type of users may travel between the connecting links

Note 1 to entry: Typically, this is a signalized intersection when considered by this document, and as such, the modes of allowed manoeuvre are reflected in the signal phases, the geometry of the intersection, and the local regulatory environment.

Note 2 to entry: The messages of  $J2735^{\text{TM}}$  convey some of this intersection information to the travelling public. Specifically, the *MAP message* (3.28) conveys the relevant road geometry, while the *SPaT* (3.44) message conveys the current allowed manoeuvres and timing which control movements within the intersection.

Note 3 to entry: Alternative definition - GDF level 2 representation of a crossing which bounds a road or a ferry as a complex feature composed of one or more GDF level 1 junctions, road elements and enclosed traffic areas.

### 3.18

#### interval

part of a traffic signal cycle during which signal indications (3.43) are stable and do not change

Note 1 to entry: In the *SPaT* (3.44) message, the current timing value for the remaining interval time estimate, as well as the anticipated interval for yellow change (clearance) interval, is provided for each lane.

Note 2 to entry: Because signal interval times commonly change based on triggering events in many types of signalling systems, the value provided in the SPaT message may represent a minimal value that is extended and updated as the message is re-transmitted in real time.

#### 3.19

#### interval sequence

order of appearance of *signal indications* (3.43) during successive periods of a traffic signal cycle

#### 3.20

#### international traveller information system

standard for incident phrases developed by the SAE ATIS Committee in conjunction with ITE TMDD and other standards

Note 1 to entry: The ITIS documentation contains a Wide Variety of standard phrases to describe incidents and is expected to be used throughout the *ITS* (315) industry. The codes found there can be used for sorting and classifying types of incident events, as well as 4 creating 000 inform human readable phrases. In the capacity of classifying incident types, ITIS phrases are used in many areas. ITIS phrases can also be freely mixed with text and used to describe many incidents.

#### 3.21

#### lane

portion of the transportation network (typically a section of roadway geometry) which is being described (its paths and various attributes about it) or referred to

Note 1 to entry: In the DSRC message set, the lane object is widely used. Lanes consist not only of sections of drivable roadway traversed by motor vehicles, but other types of lanes including pedestrian and bicycle walkways, trains and public transport lanes, and certain types of dividers and barriers.

Note 2 to entry: When used in describing an intersection, a lane is defined for each possible path into and out of the intersection (in the MAP message). The current allowed manoeuvres applicable to the lane or its approach are provided in the *SPaT* (3.44) message.

#### 3.22

#### lane-use control signal

signal face displaying *signal indications* (3.43) to permit or prohibit the use of specific *lanes* (3.21) of a roadway or to indicate the impending prohibition of such use

Note 1 to entry: Typically, these are arrow displays of varying colours.