INTERNATIONAL STANDARD

ISO 16283-2

Second edition 2018-05

Acoustics — Field measurement of sound insulation in buildings and of building elements —

Part 2: **Impact sound insulation**

iTeh STAcoustique — Mesurage in situ de l'isolation acoustique des bâtiments et des éléments de construction — Partie 2: Isolation des bruits d'impacts

ISO 16283-2:2018 https://standards.iteh.ai/catalog/standards/sist/240a67c0-4c94-4bf1-a5a0-4608a0ec2830/iso-16283-2-2018



iTeh STANDARD PREVIEW (standards.iteh.ai)

ISO 16283-2:2018 https://standards.iteh.ai/catalog/standards/sist/240a67c0-4c94-4bf1-a5a0-4608a0ec2830/iso-16283-2-2018



COPYRIGHT PROTECTED DOCUMENT

© ISO 2018

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office CP 401 • Ch. de Blandonnet 8 CH-1214 Vernier, Geneva Phone: +41 22 749 01 11 Fax: +41 22 749 09 47 Email: copyright@iso.org Website: www.iso.org

Published in Switzerland

Contents				
Fore	word		v	
Intr	oductio	n	vi	
1	Scon	e	1	
	•			
2		native references		
3	Tern	ns and definitions	1	
4	Instr	rumentation		
	4.1	General		
	4.2	Calibration		
	4.3	Verification		
5	_	uency range		
	5.1 5.2	Tapping machine as the impact source		
		Rubber ball as the impact source		
6		eral		
7	Defa	ult procedure for sound pressure level measurement	7	
	7.1	General		
	7.2	Generation of sound field		
		7.2.1 General 7.2.2 Impact source positions for the tapping machine as impact source		
		7.2.3 Impact source positions for the rubber ball as impact source	<i>7</i>	
	7.3	Fixed microphone positions for the tapping machine or rubber ball as impact source 7.3.1 General	8	
		7.3.2 Number of measurements		
		7.3.3 Tapping machine operated at more than one position	8 0	
	7.4	Mechanized continuously moving microphone for the tapping machine as impact sou	9 1rce 9	
	7.1	7.4.1 General		
		7.4.2 Number of measurements	10	
		7.4.3 Tapping machine operated at more than one position		
	7.5	Manually scanned microphone for the tapping machine as impact source		
		7.5.1 General 7.5.2 Number of measurements		
		7.5.3 Tapping machine operated at more than one position		
		7.5.4 Circle		
		7.5.5 Helix		
		7.5.6 Cylindrical-type		
	7.6	7.5.7 Three semicircles		
	7.6 7.7	Minimum distances for microphone positions Averaging times for the tapping machine as impact source		
	7.7	7.7.1 Fixed microphone positions		
		7.7.2 Mechanized continuously moving microphone		
		7.7.3 Manually scanned microphone		
	7.8	Calculation of energy-average sound pressure levels		
		7.8.1 Fixed microphone positions for the tapping machine as impact source	13	
		7.8.2 Mechanized continuously moving microphone and manually scanned microphone for the tapping machine as impact source	13	
		7.8.3 Fixed microphone positions for the rubber ball as impact source		
8	I ou	frequency procedure for sound pressure level measurement for the tapping		
O		hine as impact source	14	
	8.1	General		
	8.2	Generation of sound field		
		8.2.1 General	14	

ISO 16283-2:2018(E)

	8.2.2 Impact source positions	14	
	8.3 Microphone positions	14	
	8.4 Averaging time		
	8.5 Calculation of low-frequency energy-average impact sound pressure levels	15	
9	Background noise (default and low-frequency procedure)		
	9.1 General		
	9.2 Correction to the signal level for background noise	17	
10	Reverberation time in the receiving room (default and low-frequency procedure)		
	10.1 General	18	
	10.2 Generation of sound field		
	10.3 Default procedure		
	10.4 Low-frequency procedure		
	10.5 Interrupted noise method		
	10.6 Integrated impulse response method	19	
11	Conversion to octave bands	19	
12	Expression of results	20	
13	Uncertainty	20	
14	Test report	20	
Annex	A (normative) Impact sources	22	
Annex	B (normative) Requirements for loudspeakers used for reverberation time		
	measurements iTeh STANDARD PREVIEW	28	
Annex	C (informative) Forms for the expression of results	29	
Annex	C (informative) Forms for the expression of results (Standards.iteh.ai) D (informative) Additional guidance	33	
	E (informative) Horizontal measurements + Examples of suitable impact source		
	and microphone positions: lards, itel. ai/catalog/standards/sist/240a67c0-4c94-4bfl-a5a0-	37	
Annex	F (informative) Vertical measurements = Examples of suitable impact source and		
	microphone positions	41	
Biblio	graphy	44	

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html. www.iso.org/iso/foreword.html. www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 43, *Acoustics*, Subcommittee SC 2, *Building acoustics*.

https://standards.iteh.ai/catalog/standards/sist/240a67c0-4c94-4bf1-a5a0-

This second edition cancels and feeplaces the first-edition (ISO 16283-2:2015), which has been technically revised.

The main changes compared to the previous edition are as follows:

— amended text in <u>7.3.2</u> so that the choice of microphone positions applies to any impact source.

A list of all parts in the ISO 16283 series can be found on the ISO website.

Introduction

ISO 16283 (all parts) describes procedures for field measurements of sound insulation in buildings. Airborne, impact and façade sound insulation are described in ISO 16283-1, this document (ISO 16283-2) and ISO 16283-3, respectively.

Field sound insulation measurements that were described previously in ISO 140-4¹⁾, ISO 140-5²⁾, and ISO 140-7³⁾ were a) primarily intended for measurements where the sound field could be considered to be diffuse, and b) not explicit as to whether operators could be present in the rooms during the measurement. ISO 16283 (all parts) differs from ISO 140-4, ISO 140-5, and ISO 140-7 in that:

- a) it applies to rooms in which the sound field may or may not approximate to a diffuse field;
- b) it clarifies how operators can measure the sound field using a hand-held microphone or sound level meter;
- c) it includes additional guidance that was previously contained in ISO 140-14⁴).

NOTE Survey test methods for field measurements of airborne and impact sound insulation are dealt with in ISO 10052.

Two impact sources are described: the tapping machine and the rubber ball. These impact sources do not exactly replicate all possible types of real impacts on floors or stairs in buildings.

The tapping machine can be used to assess a variety of light, hard impacts such as footsteps from walkers wearing hard-heeled footwear or dropped objects. A single number quantity can be calculated using the rating procedures in ISO 717-2. This single number quantity links the measured impact sound insulation using the tapping machine to subjective assessment of general impacts in dwellings that occur on floors or stairs in a building. The tapping machine is also well-suited to the prediction of impact sound insulation using ISO 12354-2. These two aspects facilitate the specification of impact sound insulation in national building requirements using only measurements with the tapping machine as an impact source.

4608a0ec2830/iso-16283-2-2018

The rubber ball can be used to assess heavy, soft impacts such as from walkers in bare feet or children jumping, as well as quantifying absolute values that can be related to human disturbance in terms of a Fast time-weighted maximum sound pressure level. Calculation procedures for a single number quantity do not currently exist in an International Standard.

¹⁾ Withdrawn.

²⁾ Withdrawn.

³⁾ Withdrawn.

⁴⁾ Withdrawn.

Acoustics — Field measurement of sound insulation in buildings and of building elements —

Part 2:

Impact sound insulation

1 Scope

This document specifies procedures to determine the impact sound insulation using sound pressure measurements with an impact source operating on a floor or stairs in a building. These procedures are intended for room volumes in the range from 10 m³ to 250 m³ in the frequency range from 50 Hz to 5 000 Hz. The test results can be used to quantify, assess and compare the impact sound insulation in unfurnished or furnished rooms where the sound field can approximate to a diffuse field.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3382-2, Acoustics — Measurement of room acoustic parameters — Part 2: Reverberation time in ordinary rooms

ISO 16283-2:2018

ISO 12999-1, Acoustics/standDetermination/andarapplication/of4measurement uncertainties in building acoustics — Part 1: Sound insulation608a0ec2830/iso-16283-2-2018

ISO 17025, General requirements for the competence of testing and calibration laboratories

ISO 18233, Acoustics — Application of new measurement methods in building and room acoustics

IEC 60942, Electroacoustics — Sound calibrators

IEC 61183, Electroacoustics — Random-incidence and diffuse-field calibration of sound level meters

IEC 61260 (all parts), Electroacoustics — Octave-band and fractional-octave-band filters

IEC 61672-1, Electroacoustics — Sound level meters — Part 1: Specifications

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at https://www.iso.org/obp
- IEC Electropedia: available at http://www.electropedia.org/

3.1

energy-average impact sound pressure level in a room

Li

ten times the common logarithm of the ratio of the space and time average of the squared sound pressure to the square of the reference sound pressure where the impact source is the tapping machine and the space average is taken over the central zone of the room where nearfield radiation from the room boundaries has negligible influence

Note 1 to entry: L_i is expressed in decibels (dB).

3.2

corner impact sound pressure level in a room

 $L_{i,Corner}$

ten times the common logarithm of the ratio of the highest time average squared sound pressure from the set of corner measurements to the square of the reference sound pressure for the low-frequency range (50 Hz, 63 Hz and 80 Hz one-third octave bands) where the impact source is the tapping machine

Note 1 to entry: $L_{i,Corner}$ is expressed in decibels (dB).

3.3

low-frequency energy-average impact sound pressure level in a room

 $L_{i,LF}$

ten times the common logarithm of the ratio of the space and time average of the squared sound pressure to the square of the reference sound pressure in the low-frequency range (50 Hz, 63 Hz and 80 Hz one-third octave bands) where the impact source is the tapping machine and the space average is a weighted average that is calculated using the room corners where the sound pressure levels are highest and the central zone of the room where nearfield radiation from the room boundaries has negligible influence (standards.iten.al)

Note 1 to entry: $L_{i,LF}$ is expressed in decibels (dB).

Note 2 to entry: $L_{i,LF}$ is an estimate of the energy-average sound pressure level for the entire room volume.

3.4

energy-average maximum impact sound pressure level in a room

 $L_{i,Fmax}$

ten times the common logarithm of the ratio of the space average of the squared maximum sound pressure with Fast time weighting to the square of the reference sound pressure where the impact source is the rubber ball and the space average is taken over the central zone of the room where nearfield radiation from the room boundaries has negligible influence

Note 1 to entry: $L_{i,Fmax}$ is expressed in decibels (dB).

3.5

reverberation time

T

time required for the sound pressure level in a room to decrease by 60 dB after the sound source has stopped

Note 1 to entry: *T* is expressed in seconds (s).

3.6

background noise level

measured sound pressure level in the receiving room from all sources except the impact source

3.7

fixed microphone

microphone that is fixed in space by using a device such as a tripod so that it is stationary

mechanized continuously moving microphone

microphone that is mechanically moved with approximately constant angular speed in a circle, or is mechanically swept along a circular path where the angle of rotation about a fixed axis is between 270° and 360°

3.9

manually scanned microphone

microphone attached to a hand-held sound level meter or an extension rod that is moved by a human operator along a prescribed path

3.10

manually held microphone

microphone attached to a hand-held sound level meter or a rod that is hand-held at a fixed position by a human operator at a distance of at least an arm's length from the trunk of the operator's body

3.11

partition

total surface of the floor or stair which is excited by the impact source

Note 1 to entry: For two rooms which are staggered vertically or horizontally, the total surface of the separating partition is not visible from both sides of the partition; hence it is necessary to define the partition as the total surface.

3.12

common partition part of the floor or stair that is common to both the room in which the impact source is used and the receiving room (standards.iteh.ai)

standardized impact sound pressure level 6283-2:2018

https://standards.iteh.ai/catalog/standards/sist/240a67c0-4c94-4bf1-a5a0-

energy-average impact sound pressure level Up (311) reduced by a correction term that is given in decibels, being ten times the common logarithm of the ratio of the measured reverberation time, T(3.5), to the reference reverberation time, T_0 , which is calculated using Formula (1) when the impact source is the tapping machine:

$$L'_{nT} = L_{i} - 10\lg \frac{T}{T_{0}}$$
 (1)

where

is the reverberation time in the receiving room, in s;

 T_0 is the reference reverberation time, in s (for dwellings, $T_0 = 0.5$ s).

Note 1 to entry: L'_{nT} is expressed in decibels (dB).

Note 2 to entry: The impact sound pressure level is referenced to a reverberation time (3.5) of 0,5 s because, in dwellings with furniture, the reverberation time has been found to be reasonably independent of volume and frequency and to be approximately equal to 0,5 s.

Note 3 to entry: L'_{nT} provides a straightforward link to the subjective impression of impact sound insulation.

3.14

equivalent absorption area

A

hypothetical area of a totally absorbing surface without diffraction effects which, if it were the only absorbing element in the room, would give the same *reverberation time* (3.5) as the room under consideration and is calculated using Sabine's formula in Formula (2):

$$A = \frac{0.16V}{T} \tag{2}$$

where

V is the receiving room volume, in m^3 ;

T is the reverberation time in the receiving room, in s.

Note 1 to entry: A is expressed in square metres (m²).

3.15

normalized impact sound pressure level

 $L'_{\rm n}$

energy-average impact sound pressure level, $L_{\rm i}$ (3.1), increased by a correction term that is given in decibels, being ten times the common logarithm of the ratio between the measured equivalent absorption area, A (3.14), of the receiving room and the reference equivalent absorption area, A_0 , which is calculated using Formula (3) when the impact source is the tapping machine:

$$L'_{n} = L_{i} + 10 \lg \frac{A}{A_{0}}$$
 (standards.iteh.ai)

where

ISO 16283-2:2018

https://standards.iteh.ai/catalog/standards/sist/240a67c0-4c94-4bfl-a5a0-

A is the equivalent absorption area in the receiving room, in in 2;

 A_0 is the reference equivalent absorption area, in m² (for dwellings, $A_0 = 10$ m²).

Note 1 to entry: L'_n is expressed in decibels (dB).

3.16

standardized maximum impact sound pressure level

 $L'_{i,Fmax,V,T}$

energy-average maximum impact sound pressure level, $L_{i,Fmax}$ (3.4), increased by a correction term for room volume and reduced by a correction term for reverberation time and Fast time weighting, which is calculated using Formulae (4), (5) and (6) when the impact source is the rubber ball:

$$L'_{i,\text{Fm ax},V,T} = L_{i,\text{Fmax}} + 10 \lg \frac{V}{V_0} - 10 \lg \left[\frac{1 - C_0^{-1}}{1 - C^{-1}} \left(\frac{C^{(1-C)^{-1}} - C^{-(1-C^{-1})^{-1}}}{C_0^{(1-C_0)^{-1}} - C_0^{-(1-C_0^{-1})^{-1}}} \right) \right]$$

$$(4)$$

$$C_0 = \frac{T_0}{1.7275} \tag{5}$$

$$C = \frac{T}{1,7275} \tag{6}$$

where

- *T* is the reverberation time in the receiving room, in s;
- T_0 is the reference reverberation time, in s (for dwellings, T_0 = 0,5 s);
- V is the receiving room volume, in m³;
- V_0 is the reference receiving room volume, in m³ (for dwellings, $V_0 = 50$ m³).

Note 1 to entry: $L'_{i,Fmax,V,T}$ is expressed in decibels (dB).

Note 2 to entry: Background information can be found in Reference [18].

4 Instrumentation

4.1 General

The instruments for measuring sound pressure levels, including microphone(s) as well as cable(s), windscreen(s), recording devices and other accessories, if used, shall meet the requirements for a class 0 or 1 instrument in accordance with IEC 61672-1 for random incidence application.

Filters shall meet the requirements for a class 0 or 1 instrument in accordance with IEC 61260.

The reverberation time measurement equipment shall comply with the requirements defined in ISO 3382-2.

The impact sources shall meet the requirements given in Annex A. (standards.iteh.ai)

4.2 Calibration

At the beginning and at the end of every measurement session and at least at the beginning and the end of each measurement day, the entire sound pressure level measuring system shall be checked at one or more frequencies by means of a sound calibrator meeting the requirements for a class 0 or 1 instrument in accordance with IEC 60942. Each time the calibrator is used, the sound pressure level measured with the calibrator should be noted in the field documentation of the operator. Without any further adjustment, the difference between the readings of two consecutive checks shall be less than or equal to 0,5 dB. If this value is exceeded, the results of measurements obtained after the previous satisfactory check shall be discarded.

4.3 Verification

Conformance of the sound pressure level measuring instrument, the filters and the sound calibrator with the relevant requirements shall be verified by the existence of a valid certificate of conformance. If applicable, random incidence response of the microphone shall be verified by a procedure from IEC 61183. All conformance testing shall be conducted by a laboratory meeting the requirements of ISO/IEC 17025 and ensuring metrological traceability to the appropriate measurement standards.

The sound calibrator should be calibrated at intervals not exceeding one year, the conformance of the instrumentation system with the requirements of IEC 61672–1 should be verified at intervals not exceeding two years, and the conformance of the filter set with the requirements of IEC 61260 should be verified at intervals not exceeding two years.

5 Frequency range

5.1 Tapping machine as the impact source

All quantities shall be measured using one-third octave band filters having at least the following centre frequencies, in hertz: 100, 125, 160, 200, 250, 315, 400, 500, 630, 800, 1 000, 1 250, 1 600, 2 000, 2 500, 3 150.

If additional information in the low-frequency range is required, use one-third octave band filters with the following centre frequencies, in hertz: 50, 63, 80.

If additional information in the high-frequency range is required, use one-third octave band filters with the following centre frequencies, in hertz: 4 000, 5 000.

NOTE Measurement of additional information in the low- and high-frequency ranges is optional.

5.2 Rubber ball as the impact source

All quantities shall be measured using one-third octave or octave band filters.

One-third octave band filters shall have at least the following centre frequencies, in hertz: 50, 63, 80, 100, 125, 160, 200, 250, 315, 400, 500, 630.

6 General iTeh STANDARD PREVIEW

To determine the impact sound insulation, one room shall be chosen as the receiving room into which sound is radiated due to an impact source operating on a partition. The room or space in which the impact source is operated is referred to as the source room.

The measurements that shall be performed include the sound pressure levels in the receiving room with the impact source operating, the background noise levels in the receiving room when the impact source is switched off and the reverberation times in the receiving room.

Two impact sources are described: the tapping machine and the rubber ball.

Two measurement procedures are described that shall be used for the sound pressure level, the reverberation time and the background noise: a default procedure and an additional low-frequency procedure.

For the sound pressure level and the background noise, the default procedure requires measurements to be taken in the central zone of a room at positions away from the room boundaries. With the tapping machine as the impact source, the default procedure for all frequencies is to obtain the energy-average sound pressure level using a fixed microphone or a manually held microphone moved from one position to another, an array of fixed microphones, a mechanized continuously moving microphone or a manually scanned microphone. With the rubber ball as the impact source, the default procedure for all frequencies is to obtain the energy-average sound pressure level using a fixed microphone or a manually held microphone moved from one position to another or an array of fixed microphones.

For the sound pressure level and the background noise with the tapping machine as the impact source, the low-frequency procedure shall be used for the 50 Hz, 63 Hz and 80 Hz one-third octave bands in the receiving room when its volume is smaller than $25~\text{m}^3$ (calculated to the nearest cubic metre). This procedure should be carried out in addition to the default procedure and requires additional measurements of the sound pressure level in the corners of the receiving room using either a fixed microphone or a manually held microphone.

NOTE 1 The low-frequency procedure is necessary in small rooms due to large spatial variations in the sound pressure level of the modal sound field. In these situations, corner measurements are used to improve the repeatability, reproducibility and relevance to room occupants.

NOTE 2 The low-frequency procedure is not used with the rubber ball because no link has yet been shown between any combination of measurements from the corners and central zone of a room for the maximum Fast time-weighted sound pressure level and the maximum Fast time-weighted sound pressure level that is spatially averaged over the entire room volume.

NOTE 3 If necessary to avoid hearing damage, hearing protection is worn by the operator when measuring the sound pressure level in the source room and, if needed, when measuring reverberation times in the receiving room. When measuring sound pressure levels in the receiving room that do not cause hearing damage, it is advisable to remove any hearing protection so that the operator is aware of short external noise events that can invalidate the measurement; it also helps the operator to minimize self-generated noise.

For the reverberation time, the low-frequency procedure shall be used for the 50 Hz, 63 Hz and 80 Hz one-third octave bands in the receiving room when its volume is smaller than 25 m^3 (calculated to the nearest cubic metre).

If the methods of signal processing for reverberation times described in ISO 18233 are applied, the measurements shall be carried out using fixed microphones and shall not use a mechanized continuously moving microphone, a manually held microphone or a manually scanned microphone.

The sound fields in typical rooms rarely approximate to a diffuse sound field over the entire frequency range from 50 Hz to 5 000 Hz. The default and low-frequency procedures allow for measurements to be taken without any knowledge as to whether the sound field can be considered as diffuse or non-diffuse. For this reason, the sound field should not be modified for the purpose of the test by temporarily introducing additional furniture or diffusers into the receiving room.

NOTE 4 If measurements with additional diffusion are required, for example due to regulatory requirements or because the test result is to be compared with a laboratory measurement on a similar test element, the introduction of three diffusers, each with an area of at least 1,0 m², is usually sufficient.

All measurement methods for the default procedure or the low-frequency procedure are equivalent. In case of dispute, the impact sound insulation determined using measurement methods without an operator inside the receiving room shall be taken to be the reference result.

NOTE 5 A reference result is defined because the background noise level with manual scanning is prone to variation in the self-generated noise from the operator. Significant variation does not tend to occur with fixed microphones or a mechanized continuously moving microphone.

7 Default procedure for sound pressure level measurement

7.1 General

Sound pressure level measurements shall be used to determine the average level in the central zone of the receiving room with the impact source in operation and the background noise level in the receiving room when the impact source is not operational.

7.2 Generation of sound field

7.2.1 General

The impact sound shall be generated using the tapping machine or the rubber ball as the impact source.

7.2.2 Impact source positions for the tapping machine as impact source

The tapping machine shall be placed in at least four different positions randomly distributed on the floor under test. The distance of the tapping machine from the edges of the floor shall be at least 0,5 m. In the case of anisotropic floor constructions with beams, ribs, etc., more positions can be necessary. The hammer connecting line should be orientated at 45° to the direction of the beams or ribs.

The impact sound pressure levels can reveal a time dependency after the tapping is started. In such a case, the measurements should not begin until the noise level has become steady. If stable conditions are

ISO 16283-2:2018(E)

not reached after 5 min, then the measurements should be carried out over a well-defined measurement period. The measurement period shall be reported.

NOTE Time dependency sometimes occurs with soft or fragile floor surfaces as, during each impact, the hammers can change the contact stiffness or damage the surface directly underneath the hammers.

When floors with soft coverings are under test, the tapping machine shall fulfil the special requirements given in <u>Annex A</u>. Advice regarding the mounting of the tapping machine on soft floor coverings is given in <u>Annex A</u>.

7.2.3 Impact source positions for the rubber ball as impact source

The impact sound shall be generated by dropping the rubber ball vertically in a free fall from a height of $100 \text{ cm} \pm 1 \text{ cm}$ measured from the bottom of the rubber ball to the surface of the floor under test.

The excitation by the rubber ball shall be made at four or more different positions on the floor or stairs under test. For a lightweight floor with joists, one of these positions should be above the joists and one position should be at the centre point of the floor.

7.3 Fixed microphone positions for the tapping machine or rubber ball as impact source

7.3.1 General

With the tapping machine or the rubber ball as the impact source, fixed microphones may be used without an operator in the room using a microphone fixed on a tripod. Alternatively, the operator may be present in the room with the microphone fixed on a tripod, or with the operator using a manually held microphone at a fixed position; in both cases, the trunk of the operator's body shall remain at a distance of at least an arm's length from the microphone. For the tapping machine as the impact source, the averaging times shall satisfy the requirements in 7.7.1.

Microphone positions shall be distributed within the maximum permitted space throughout each room. No two microphone positions shall lie in the same plane relative to the room boundaries, and the positions shall not be in a regular grid.

7.3.2 Number of measurements

The number of microphone positions shall equal the number of source positions or integer multiples of the number of source positions.

The same number of microphone positions shall be used for each source position.

If four or five source positions are used, at least two measurements of impact sound pressure level shall be made for each source position. Measurements shall be made in at least two different microphone positions for each source position.

If six or more source positions are used, at least one measurement of impact sound pressure level shall be made for each source position. Measurements shall be carried out at a different microphone position for each source position.

7.3.3 Tapping machine operated at more than one position

Measure the sound pressure level in the receiving room for the first impact source position. Calculate the energy-average sound pressure level according to <u>7.8.1</u> then make any required correction for background noise according to <u>9.2</u>. Calculate the standardized impact sound pressure level using <u>Formula (1)</u> or the normalized impact sound pressure level using <u>Formula (3)</u>. Repeat this process for

the other impact source position(s) then calculate the standardized impact sound pressure level using <u>Formula (7)</u> or the normalized impact sound pressure level using <u>Formula (8)</u>:

$$L'_{nT} = 10 \lg \left(\frac{1}{m} \sum_{j=1}^{m} 10^{\frac{L'_{nT,j}}{10}} \right)$$

$$L'_{n} = 10 \lg \left(\frac{1}{m} \sum_{j=1}^{m} 10^{\frac{L'_{n,j}}{10}} \right)$$
(8)

$$L'_{n} = 10 \lg \left(\frac{1}{m} \sum_{j=1}^{m} 10^{\frac{L'_{n,j}}{10}} \right)$$
 (8)

where

is the number of tapping machine positions;

 $L'_{nT,i}$ is the standardized impact sound pressure level for tapping machine position j;

is the normalized impact sound pressure level for tapping machine position *j*.

7.3.4 Rubber ball operated at more than one position

Measure the sound pressure level in the receiving room for the first impact source position. Calculate the energy-average maximum impact sound pressure level according to 7.8.3, then make any required correction for background noise according to Clause 2. Repeat this process for the other impact source position(s), then calculate the energy-average maximum impact sound pressure level using Formula (9):

where

is the number of rubber ball positions; m

is the maximum impact sound pressure level for rubber ball position *j*.

Calculate the standardized maximum impact sound pressure level using Formulae (4), (5) and (6).

7.4 Mechanized continuously moving microphone for the tapping machine as impact source

7.4.1 General

With the tapping machine as the impact source, the microphone shall be mechanically moved with approximately constant angular speed in a circle or shall be mechanically swept along a circular path where the angle of rotation about a fixed axis is between 270° and 360°. The sweep radius for the circular traverse shall be at least 0,7 m. The plane of the traverse shall be inclined in order to cover a large proportion of the permitted room space and shall not lie in any plane that is less than 10° from any room surface (wall, floor or ceiling).

The duration of a single traverse shall be at least 15 s. Each complete traverse may need to be repeated to satisfy the requirements on the averaging time in 7.7.2.

When using at least six tapping machine positions, the location of the fixed point about which the continuously moving microphone moves may be changed.