
**Traktorji ter kmetijski in gozdarski stroji - Varnostni deli krmilnih sistemov - 2. del:
Faza koncepta (ISO 25119-2:2019)**

Tractors and machinery for agriculture and forestry - Safety-related parts of control systems - Part 2: Concept phase (ISO 25119-2:2019)

Traktoren und Maschinen für die Land- und Forstwirtschaft - Sicherheitsbezogene Teile von Steuerungen - Teil 2: Konzeptphase (ISO 25119-2:2019)

Tracteurs et matériels agricoles et forestiers - Parties des systèmes de commande relatives à la sécurité - Partie 2: Phase de projet (ISO 25119-2:2019)

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Tracteurs et matériels agricoles et forestiers - Parties
des systèmes de commande relatives à la sécurité -
Partie 2: Phase de projet (ISO 25119-2:2019)

Traktoren und Maschinen für die Land- und
Forstwirtschaft - Sicherheitsbezogene Teile von
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This draft European Standard is submitted to CEN members for enquiry. It has been drawn up by the Technical Committee CEN/TC 144.

If this draft becomes a European Standard, CEN members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

This draft European Standard was established by CEN in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CEN member into its own language and notified to the CEN-CENELEC Management Centre has the same status as the official versions.

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Recipients of this draft are invited to submit, with their comments, notification of any relevant patent rights of which they are aware and to provide supporting documentation.

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European foreword

The text of ISO 25119-2:2019 has been prepared by Technical Committee ISO/TC 23 “Tractors and machinery for agriculture and forestry” of the International Organization for Standardization (ISO) and has been taken over as prEN ISO 25119-2:2021 by Technical Committee CEN/TC 144 “Tractors and machinery for agriculture and forestry” the secretariat of which is held by AFNOR.

This document is currently submitted to the CEN Enquiry.

This document has been prepared under a mandate given to CEN by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive.

For relationship with EU Directive, see informative Annex ZA, which is an integral part of this document.

Endorsement notice

The text of ISO 25119-2:2019 has been approved by CEN as prEN ISO 25119-2:2021 without any modification.

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Annex ZA (informative)

Relationship between this European Standard and the essential requirements of Directive 2006/42/EC aimed to be covered

This European Standard has been prepared under a Commission's standardization request "M/396 Mandate to CEN and CENELEC for Standardisation in the field of machinery" to provide one voluntary means of conforming to essential requirements of Directive 2006/42/EC of the European Parliament and of the Council of 17 May 2006 on machinery, and amending Directive 95/16/EC (recast).

Once this standard is cited in the Official Journal of the European Union under that Directive, compliance with the normative clauses of this standard given in Table ZA.1 confers, within the limits of the scope of this standard, a presumption of conformity with the corresponding essential requirements of that Directive, and associated EFTA regulations.

Table ZA.1— Correspondence between this European Standard and Annex I of Directive 2006/42/EC

The relevant Essential Requirements of Directive 2006/42/EC	Clauses/sub-clauses of EN ISO 25119-2	Remarks/Notes
1.1.2. Principles of safety integration		
1.1.2 (a)	5.3, 6.3, 7.3, A.1, A.2, A.3, A.4, A.5, A.6, H.2, H.3, H.4, H.5	
1.1.2 (c)	5.3, 6.3, 7.3, A.1, A.2, A.3, A.4, A.5, A.6, H.2, H.3, H.4, H.5	
1.2.1. Safety and reliability of control systems	5.3, 6.3.2, 7.3.2, 7.3.5, A.1, A.2, A.3, A.4, A.5, A.6	
1.2.3. Starting	6.3.2, 7.3, A.5, A.6	
1.2.4.1. Normal stop	6.3.2, 7.3	
1.2.4.2. Operational stop	6.3.2, 7.3	
1.2.4.3. Emergency stop	6.3.2, 7.3	
1.2.5. Selection of control or operating modes	5.3.3, 6.3.2, 7.3	
1.2.6. Failure of the power supply	6.3.2, 7.3	
1.6.3. Isolation of energy sources	6.3.2, 7.3	

WARNING 1 — Presumption of conformity stays valid only as long as a reference to this European Standard is maintained in the list published in the Official Journal of the European Union. Users of this standard should consult frequently the latest list published in the Official Journal of the European Union.

WARNING 2 — Other Union legislation may be applicable to the product(s) falling within the scope of this standard.

INTERNATIONAL
STANDARD

ISO
25119-2

Third edition
2019-08

**Tractors and machinery for
agriculture and forestry — Safety-
related parts of control systems —**

**Part 2:
Concept phase**

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CP 401 • Ch. de Blandonnet 8
CH-1214 Vernier, Geneva
Phone: +41 22 749 01 11
Fax: +41 22 749 09 47
Email: copyright@iso.org
Website: www.iso.org

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 23, *Tractors and machinery for agriculture and forestry*, Subcommittee SC 19, *Agricultural electronics*.

This third edition cancels and replaces the second edition (ISO 25119-2:2018), of which it constitutes a minor revision. The changes compared to the previous edition are as follows.

- A minor revision was made to [Annex H](#) to improve the clarity and understanding of the requirements to be followed by the end user about subsystems, elements, or components designed according to ISO 26262.

A list of all parts in the ISO 25119 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

ISO 25119-2:2019(E)

Introduction

ISO 25119 (all parts) sets out an approach to the assessment, design and verification, for all safety life cycle activities, of safety-related parts comprising electrical and/or electronic and/or programmable electronic systems (E/E/PES) on tractors used in agriculture and forestry, and on self-propelled ride-on machines and mounted, semi-mounted and trailed machines used in agriculture. It is also applicable to mobile municipal equipment.

A prerequisite to the application of ISO 25119 (all parts) is the completion of a suitable hazard identification and risk analysis (such as ISO 12100) for the entire machine. As a result, an E/E/PES is frequently assigned to provide safety-related functions that create safety-related parts of control systems (SRP/CS). These can consist of hardware or software, can be separate or integrated parts of a control system, and can either perform solely safety-related functions or form part of an operational function.

In general, the designer (and to some extent, the user) will combine the design and validation of these SRP/CS as part of the risk assessment. The objective is to reduce the risk associated with a given hazard (or hazardous situation) under all conditions of use of the machine. This can be achieved by applying various measures (both SRP/CS and non-SRP/CS) with the end result of achieving a safe condition.

ISO 25119 (all parts) allocates the ability of safety-related parts to perform a safety-related function under foreseeable conditions into five performance levels. The performance level of a controlled channel depends on several factors, including system structure (category), the extent of fault detection mechanisms (diagnostic coverage), the reliability of components (mean time to dangerous failure, common-cause failure), design processes, operating stress, environmental conditions and operation procedures. Three types of failures that can cause E/E/PES malfunctions leading to potential hazardous situations are considered: systematic, common-cause and random.

In order to guide the designer during design, verification, and to facilitate the assessment of the achieved performance level, ISO 25119 (all parts) defines an approach based on a classification of architecture with different design features and specific behaviour in case of a fault.

The performance levels and categories can be applied to the control systems of all kinds of mobile machines: from simple systems (such as auxiliary valves) to complex systems (such as steer by wire), as well as to the control systems of protective equipment (such as interlocking devices, pressure sensitive devices).

ISO 25119 (all parts) adopts a risk-based approach for the determination of the risks, while providing a means of specifying the required performance level for the safety-related functions to be implemented by E/E/PES safety-related channels. It gives requirements for the whole safety life-cycle of E/E/PES (design, validation, production, operation, maintenance, decommissioning), necessary for achieving the required functional safety for E/E/PES that are linked to the performance levels.

The structure of safety standards in the field of machinery is as follows.

- a) Type-A standards (basic safety standards) give basic concepts, principles for design and general aspects that can be applied to machinery.
- b) Type-B standards (generic safety standards) deal with one or more safety aspect(s), or one or more type(s) of safeguards that can be used across a wide range of machinery:
 - type-B1 standards on particular safety aspects (e.g. safety distances, surface temperature, noise);
 - type-B2 standards on safeguards (e.g. two-hand controls, interlocking devices, pressure sensitive devices, guards).
- c) Type-C standards (machinery safety standards) deal with detailed safety requirements for a particular machine or group of machines.

This document is a type-B1 standard as stated in ISO 12100.

This document is of relevance, in particular, for the following stakeholder groups representing the market players with regard to machinery safety:

- machine manufacturers (small, medium and large enterprises);
- health and safety bodies (regulators, accident prevention organizations, market surveillance, etc.).

Others can be affected by the level of machinery safety achieved with the means of the document by the above-mentioned stakeholder groups:

- machine users/employers (small, medium and large enterprises);
- machine users/employees (e.g. trade unions, organizations for people with special needs);
- service providers, e.g. for maintenance (small, medium and large enterprises);
- consumers (in case of machinery intended for use by consumers).

The above-mentioned stakeholder groups have been given the possibility to participate at the drafting process of this document.

In addition, this document is intended for standardization bodies elaborating type-C standards.

The requirements of this document can be supplemented or modified by a type-C standard.

For machines which are covered by the scope of a type-C standard and which have been designed and built according to the requirements of that standard, the requirements of that type-C standard take precedence.

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Tractors and machinery for agriculture and forestry — Safety-related parts of control systems —

Part 2: Concept phase

1 Scope

This document specifies the concept phase of the development of safety-related parts of control systems (SRP/CS) on tractors used in agriculture and forestry and on self-propelled ride-on machines and mounted, semi-mounted and trailed machines used in agriculture. It can also be applied to mobile municipal equipment (such as street-sweeping machines).

This document is not applicable to:

- aircraft and air-cushion vehicles used in agriculture;
- lawn and garden equipment.

This document specifies the characteristics and categories required of SRP/CS for carrying out their safety-related functions. It does not identify performance levels for specific applications.

NOTE 1 Machine specific type-C standards can specify performance levels (AgPL) for safety-related functions in machines within their scope. Otherwise, the specification of AgPL is the responsibility of the manufacturer.

This document is applicable to the safety-related parts of electrical/electronic/programmable electronic systems (E/E/PES), as these relate to mechatronic systems. It covers the possible hazards caused by malfunctioning behaviour of E/E/PES safety-related systems, including interaction of these systems. It does not address hazards related to electric shock, fire, smoke, heat, radiation, toxicity, flammability, reactivity, corrosion, release of energy, and similar hazards, unless directly caused by malfunctioning behaviour of E/E/PES safety-related systems. It also covers malfunctioning behaviour of E/E/PES safety-related systems involved in protection measures, safeguards, or safety-related functions in response to non-E/E/PES hazards.

Examples included within the scope of this document:

- SRP/CS's limiting current flow in electric hybrids to prevent insulation failure/shock hazards;
- electromagnetic interference with the SRP/CS;
- SRP/CS's designed to prevent fire.

Examples not included within the scope of this document:

- insulation failure due to friction that leads to electric shock hazards;
- nominal electromagnetic radiation impacting nearby machine control systems;
- corrosion causing electric cables to overheat.

This document is not applicable to non-E/E/PES systems (such as hydraulic, mechanic or pneumatic).

NOTE 2 See also ISO 12100 for design principles related to the safety of machinery.

This document is not applicable to safety-related parts of control systems manufactured before the date of its publication.