
Sistemi za upravljanje industrijskih procesov - 2. del: Postopki za ocenjevanje lastnosti inteligentnih pozicionirnikov z ventili s pnevmatskimi izhodi, nameščenimi na sklop ventila aktuatorja

Industrial process control systems - Part 2: Methods of evaluating the performance of intelligent valve positioners with pneumatic outputs mounted on an actuator valve assembly

Systeme der industriellen Prozessleittechnik – Teil 2: Verfahren zur Bewertung des Betriebsverhaltens von intelligenten Ventilstellungsreglern mit pneumatischem Ausgang, die an Ventil-Stellantrieben montiert sind

Systèmes de commande des processus industriels - Partie 2: Méthodes d'évaluation des performances des positionneurs de vanne intelligents à sorties pneumatiques montés sur un ensemble actionneur/vanne

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TITLE:

Industrial process control systems - Part 2: Methods of evaluating the performance of intelligent valve positioners with pneumatic outputs mounted on an actuator valve assembly

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INDUSTRIAL PROCESS CONTROL SYSTEMS –

72

73 **Part 2: Methods of evaluating the performance of intelligent**74 **valve positioners with pneumatic outputs mounted**75 **on an actuator valve assembly**

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FOREWORD

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110 International Standard IEC 61514-2 has been prepared by subcommittee 65B: Measurement
111 and control devices, of IEC technical committee 65: Industrial-process measurement, control
112 and automation.

113 This part of IEC 61514-2 is to be used in conjunction with IEC 61514:202X.

114 This second edition cancels and replaces the first edition published in 2004. This edition
115 constitutes a technical revision.

116 The significant changes with respect to the previous edition are as follows:

117 – The standard has been optimized for usability.

118 – The test procedures have been reviewed regarding applicability for use in test facilities.
119 Impractical test procedures were removed or modified.

120 The text of this standard is based on the following documents:

FDIS	Report on voting
65B/868/FDIS	65B/872/RVD

121
122 Full information on the voting for the approval of this standard can be found in the report on
123 voting indicated in the above table.

124 This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

125 A list of all parts of the IEC 61514 series, published under the general title *Industrial process*
126 *control systems*, can be found on the IEC website.

127 The committee has decided that the contents of this publication will remain unchanged until the
128 stability date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to
129 the specific publication. At this date, the publication will be

- 130 • reconfirmed,
131 • withdrawn,
132 • replaced by a revised edition, or
133 • amended.

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136

INTRODUCTION

137 New instruments for process control and measurement including valve positioners are mainly
138 equipped with microprocessors, thereby utilising digital data processing and communication
139 methods and/or artificial intelligence, making them more complex and giving them a consider-
140 able added value.

141 Modern intelligent valve positioners are no longer only controlling the valve position, but they
142 are in many cases also equipped with various facilities for self-testing, actuator/valve condition
143 monitoring and alarming. The variety of added functionalities is large. They can no longer be
144 compared with the single function "cam-type" positioners. Therefore, accuracy related
145 performance testing, although still very important, is no longer sufficient to demonstrate their
146 flexibility, capabilities and other features with respect to engineering, installation, maintain-
147 ability, reliability and operability.

148 In this standard the evaluation considers performance testing and a design review of both
149 hardware and software. The layout of this document follows to some extent the framework of
150 IEC/TS 62098. A number of performance tests described in IEC 61514 are still valid for
151 intelligent valve positioners. Further reading of IEC 61069 is recommended.

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INDUSTRIAL PROCESS CONTROL SYSTEMS –

Part 2: Methods of evaluating the performance of intelligent valve positioners with pneumatic outputs mounted on an actuator valve assembly

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161 **1 Scope**

162 This part of IEC 61514 specifies design reviews and tests intended to measure and determine
163 the static and dynamic performance, the degree of intelligence and the communication
164 capabilities of single-acting or double-acting intelligent valve positioners. The tests may be
165 applied to positioners which receive standard analogue electrical input signals (as specified in
166 IEC 60381) and/or digital signals via a data communication link (for example Fieldbus) and
167 have a pneumatic output. An intelligent valve positioner as defined in Clause 3 is an instrument
168 that uses for performing its functions digital techniques for data processing, decision-making
169 and bi-directional communication. It may be equipped with additional sensors and additional
170 functionality supporting the main function.

171 The performance testing of an intelligent valve positioner needs to be conducted with the
172 positioner mounted on and connected to the actuator/valve assembly the positioner is to be
173 used on. The specific characteristic parameters of these combinations such as size, stroke,
174 friction, type of packing, spring package and supply pressure for the pneumatic part, should be
175 carefully chosen and reported, since the performance of a positioner is greatly dependent on
176 the used actuator.

177 The methods of evaluation given in this standard are intended for testing laboratories to verify
178 equipment performance specifications. The manufacturers of intelligent positioners are urged
179 to apply this standard at an early stage of development.

180 This standard is intended to provide guidance for designing evaluations of intelligent valve
181 positioners by providing:

- 182 – a checklist for reviewing their hardware and software design in a structured way;
- 183 – test methods for measuring and qualifying their performance under various environmental
184 and operational conditions;
- 185 – methods for reporting the data obtained.

186 When a full evaluation, in accordance with this standard, is not required or possible, the tests
187 which are required should be performed and the results should be reported in accordance with
188 the relevant parts of this standard. In such cases, the test report should state that it does not
189 cover the full number of tests specified herein. Furthermore, the items omitted should be
190 mentioned, to give the reader of the report a clear overview.

191 The standard is also applicable for non-intelligent microprocessor-based valve positioners
192 without means for bi-directional communication. In that case an evaluation should be reduced
193 to a limited programme of performance testing and a short review of the construction.

194 **2 Normative references**

195 The following documents, in whole or in part, are normatively referenced in this document and
196 are indispensable for its application. For dated references, only the edition cited applies. For
197 undated references, the latest edition of the referenced document (including any amendments)
198 applies.

- 199 IEC 60050, *International Electrotechnical Vocabulary (IEV):*
- 200 - *Part 311: Electrical and electronic measurements - General terms relating to electrical*
201 *measurements*
- 202 - *Part 351: Control technology*
- 203 IEC 60068-2-1, *Environmental testing – Part 2-1: Tests. Tests A: Cold*
- 204 IEC 60068-2-2, *Environmental testing – Part 2-2: Tests. Tests B: Dry heat*
- 205 IEC 60068-2-6, *Environmental testing – Part 2-6: Tests. Test Fc: Vibration (sinusoidal)*
- 206 IEC 60068-2-31, *Environmental testing – Part 2-31: Tests. Test Ec: Drop and topple, primarily*
207 *for equipment-type specimens*
- 208 IEC 60068-2-78, *Environmental testing – Part 2-78: Tests. Test Cab: Damp heat, steady state*
- 209 IEC 60079 (all parts), *Electrical apparatus for explosive gas atmospheres*
- 210 IEC 60381-1, *Analogue signals for process control systems – Part 1: Direct current signals*
- 211 IEC 60381-2, *Analogue signals for process control systems – Part 2: Direct voltage signals*
- 212 IEC 60529, *Degrees of protection provided by enclosures (IP Code)*
- 213 IEC 60534-1, *Industrial-process control valves – Part 1: Control valve terminology and general*
214 *considerations*
- 215 IEC 60654 (all parts), *Operating conditions for industrial-process measurement and control*
216 *equipment*
- 217 IEC 60721-3, *Classification of environmental conditions – Part 3 Classification of groups of*
218 *environmental parameters and their severities*
- 219 IEC 61010-1, *Safety requirements for electrical equipment for measurement, control, and*
220 *laboratory use – Part 1: General requirements*
- 221 IEC 61032, *Protection of persons and equipment by enclosures – Probes for verification*
- 222 IEC 61069 (all parts), *Industrial-process measurement and control – Evaluation of system*
223 *properties for the purpose of system assessment*
- 224 IEC 61158 (all parts), *Digital data communications for measurement and control – Fieldbus for*
225 *use in industrial control systems*
- 226 IEC 61326-1:2020, *Electrical equipment for measurement, control and laboratory use – EMC*
227 *requirements*
- 228 IEC 61499 (all parts), *Function blocks for industrial-process measurement and control systems*
- 229 IEC 61508 Part 1 and 7, *Functional safety of electrical/electronic/programmable electronic*
230 *safety-related systems*
- 231 IEC 61511-Part 1 and 3, *Functional safety - Safety instrumented systems for the process*
232 *industry sector*

233 IEC 61514:202X, *Industrial-process control systems – Methods of evaluating the performance*
 234 *of valve positioners with pneumatic outputs*

235 IEC 62061, *Safety of machinery - Functional safety of safety-related control systems*

236 IEC 62828-1:2017, *Reference conditions and procedures for testing industrial and process*
 237 *measurement transmitters – Part 1: General procedures for all types of transmitters*

238 **3 Terms and definitions**

239 For the purposes of this standard, the terms and definitions given in IEC 60050 and IEC 61514,
 240 as well as the following apply.

241 **3.1**

242 **intelligent valve positioner**

243 position controller based on microprocessor technology, and utilising digital techniques for data
 244 processing, decision-making and bi-directional communication

245 Note 1 to entry: It may be equipped with additional sensors and additional functionality supporting the main function.

246 Note 2 to entry: In this standard, only positioners with pneumatic output signals are considered, as defined in 3.1
 247 of IEC 61514:202X. The input signal may be an electric current or voltage, or a digital signal via a fieldbus.

248 Note 3 to entry: For non-intelligent microprocessor-based position controllers without bi-directional communication
 249 an evaluation is reduced to a limited amount of performance testing and an abridged design review of the
 250 construction.

251 **3.2**

252 **configuring**

253 process of implementing the functionality required for a certain application

254 **3.3**

255 **configurability**

256 extent to which an intelligent positioner can be provided with functions to control various
 257 applications

258 **3.4**

259 **calibration**

260 process of adjusting the range of travel to the required value for acquiring a defined input-to-
 261 travel characteristic

262 Note 1 to entry: The adjusted travel can either be from stop to stop or to a value in between as defined by the valve
 263 manufacturer.

264 Note 2 to entry: Instruments may exist that are provided with an automatic procedure for travel range adjustment,
 265 which may then be addressed with the term auto-calibration.

266 [SOURCE: IEC 60050-311, 311-01-09, modified]

267 **3.5**

268 **tuning**

269 process of adjusting the various control parameters for a certain application

270 Note 1 to entry: The stem position tuning procedure can range from "trial and error" to an automatic proprietary
 271 procedure provided by the manufacturer and often addressed as auto-tuning.

272 **3.6**

273 **set-up**

274 process of configuring, calibrating and tuning a positioner for optimal controlling of a specific
 275 actuator/valve assembly

276 **3.7**
277 **travel cut-off**
278 point close to the extreme end (low or high) of the characteristic curve at which the positioner
279 forces the valve to the corresponding mechanical stop (fully closed or fully open)

280 **3.8**
281 **stroke time**
282 time required to travel between two different positions under a defined set of conditions

283 **3.9**
284 **dead band**
285 finite range of values of the input variable within which a variation of the input variable does not
286 produce any measurable change in the output variable

287 [SOURCE: IEC 60050-351, 351-45-15]

288 **3.10**
289 **operating mode**
290 selected method of operation of the positioner

291 [SOURCE: IEC 60050-351, 351-55-01, modified]

292 **3.11**
293 **setpoint**
294 input variable, which sets the desired value of the controlled variable (travel)

295 Note 1 to entry: The input variable may originate from an analogue source (mA or voltage) or from a digital source
296 (fieldbus) or local keyboard).

297 **3.12**
298 **balance pressure**
299 average of the pressures on the opposite chambers of a double acting actuator in steady state
300 condition

301 Note 1 to entry: The balance pressure shall be expressed as a percentage of the positioner supply pressure to
302 evaluate the stiffness of the double acting system.

303 **4 Design review**

304 **4.1 General**

305 The observations of Clause 4 shall be based on open literature (manuals, instruction leaflets,
306 etc.) provided to a user on delivery of the instruments and whatever the manufacturer is willing
307 to disclose. They shall not contain confidential information.

308 The design review is meant to identify and make explicit the functionality and capabilities of the
309 intelligent valve positioner under consideration in a structured way. As intelligent positioners
310 appear in a great variety of designs a review has to show in a structured way the details of

- 311 – their physical structure;
- 312 – their functional structure.

313 Subclause 4.2 guides the evaluator in the process of describing the physical structure of
314 intelligent positioners through identifying the hardware modules and the I/Os to the operational
315 and environmental domains.

316 Thereafter the functional structure is described using the checklist of 4.3. The checklist gives a
317 structured framework of the relevant issues, which have to be addressed by the evaluator
318 through adequate qualitative and quantitative experiments.