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**Synchronous belt drives — Automotive  
belts and pulleys**

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## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see [www.iso.org/directives](http://www.iso.org/directives)).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see [www.iso.org/patents](http://www.iso.org/patents)).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see [www.iso.org/iso/foreword.html](http://www.iso.org/iso/foreword.html).

This document was prepared by Technical Committee ISO/TC 41, *Pulleys and belts (including vee belts)*, Subcommittee SC 4, *Synchronous belt drives*.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at [www.iso.org/members.html](http://www.iso.org/members.html).

This first edition of ISO 21342 cancels and replaces ISO 9010:1997 and ISO 9011:1997.

# Synchronous belt drives — Automotive belts and pulleys

## 1 Scope

This document specifies the characteristics of synchronous endless belts and their related pulleys for use in automotive applications such as engine camshaft drives.

The characteristics include:

- belt pitch spacing;
- belt nominal tooth dimensions;
- belt width and width tolerance;
- belt pitch length and pitch length tolerance;
- pulley groove dimensions and tolerances;
- pulley tolerances and quality specifications.

Test methods for measuring belt pitch length and lateral runout are also included.

## 2 Normative reference

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 254, *Belt drives — Pulleys — Quality, finish and balance*

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## 3 Terms and definitions

No terms and definitions are listed in this document.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>.
- IEC Electropedia: available at <http://www.electropedia.org/>

## 4 Profiles

The following profiles for synchronous drives for automotive applications are standardized:

- type ZA: trapezoidal tooth;
- type ZB: trapezoidal tooth;
- type ZH: curvilinear tooth, "H" system;
- type YH: curvilinear tooth, "H" system;
- type ZR: curvilinear tooth, "R" system;
- type YR: curvilinear tooth, "R" system;

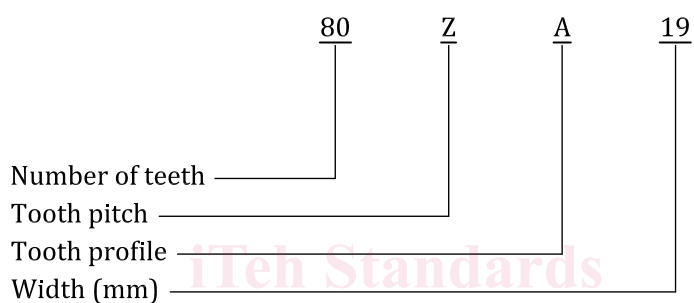
- type ZS: curvilinear tooth, "S" system;
- type YS: curvilinear tooth, "S" system.

## 5 Belt designation

A belt is designated by a series of numbers and letters as follows:

- the first set of numbers indicates the number of teeth;
- the first letter indicates tooth pitch;
- the second letter indicates tooth profile;
- The second set of numbers indicates the width in millimetres.

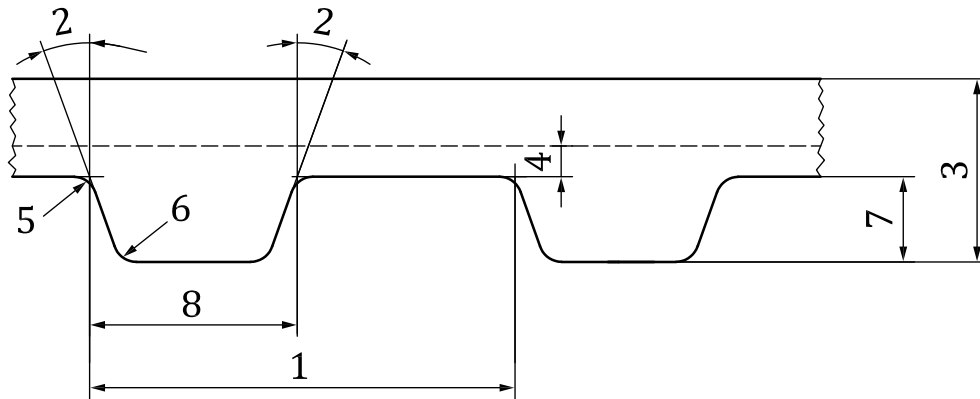
EXAMPLE



## 6 Belt dimensions and tolerances

### 6.1 Belt tooth dimensions — Trapezoidal tooth belts of types ZA and ZB

The nominal belt tooth dimensions for trapezoidal tooth belts of types ZA and ZB are shown in [Figure 1](#) and given in [Table 1](#).

**Key**

- 1 tooth pitch ( $p_b$ )
- 2 tooth angle ( $2\beta$ )
- 3 height ( $h_s$ )
- 4 pitch line differential ( $a$ )
- 5 root radius ( $r_r$ )
- 6 tip radius ( $r_a$ )
- 7 tooth height ( $h_t$ )
- 8 tooth width ( $S$ )

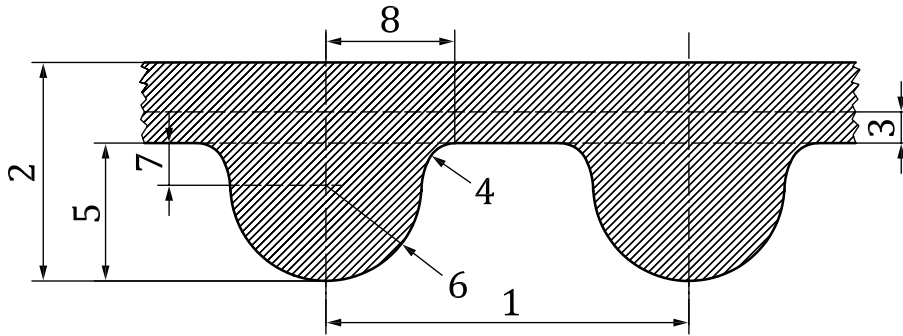
**Figure 1 — Nominal tooth dimensions (profile) for types ZA and ZB**

**Table 1 — Nominal tooth dimensions for types ZA and ZB**

Key number	Symbol	Nominal profile	
		Type ZA	Type ZB
1	$p_b$	9,525	9,525
2	$2\beta$	40	40
3	$h_s$	4,1	4,5
4	$a$	0,686	0,686
5	$r_r$	0,51	1,02
6	$r_a$	0,51	1,02
7	$h_t$	1,91	2,29
8	$S$	4,65	6,12

## 6.2 Belt tooth dimensions — Curvilinear tooth belts of types ZH and YH

The nominal belt tooth dimensions for curvilinear tooth belts of types ZH and YH are shown in [Figure 2](#) and given in [Table 2](#).



**Key**

- 1 tooth pitch ( $p_b$ )
- 2 height ( $h_s$ )
- 3 pitch line differential ( $a$ )
- 4 root radius ( $r_r$ )
- 5 tooth height ( $h_t$ )
- 6 tooth radius ( $R$ )
- 7 vertical offset ( $Y$ )
- 8 root radius distance ( $S_r$ )

**Figure 2 — Nominal tooth dimensions (profile) for types ZH and YH**

**Table 2 — Nominal tooth dimensions for types YH and ZH**

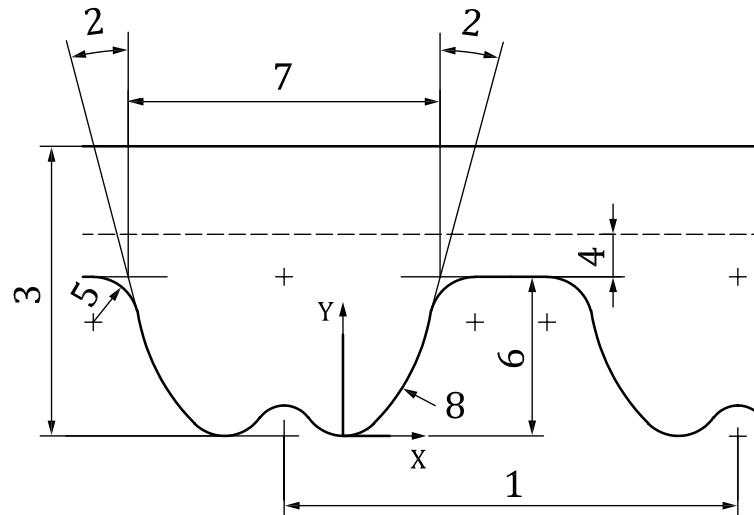
Dimensions in millimetres  
Angles in degrees

Key number	Symbol	Nominal profile	
		Type YH	Type ZH
1	$p_b$	8	9,525
2	$h_s$	5,2	5,5
3	$a$	0,686	0,686
4	$r_r$	0,64	0,76
5	$h_t$	3,04	3,5
6	$R$	2,11	2,45
7	$Y$	0,93	1,05
8	$S_r$	2,84	3,27

**6.3 Belt tooth dimensions — Curvilinear tooth belts of types YR and ZR**

The nominal tooth dimensions for curvilinear tooth belts of types YR and ZR are shown in [Figure 3](#) and given in [Table 3](#).



**Key**

- 1 tooth pitch ( $p_b$ )
- 2 tooth angle ( $2\beta$ )
- 3 height ( $h_s$ )
- 4 pitch line differential ( $a$ )
- 5 root radius ( $r_r$ )
- 6 tooth height ( $h_t$ )
- 7 tooth width ( $S$ )
- 8  $Y = kX^2$

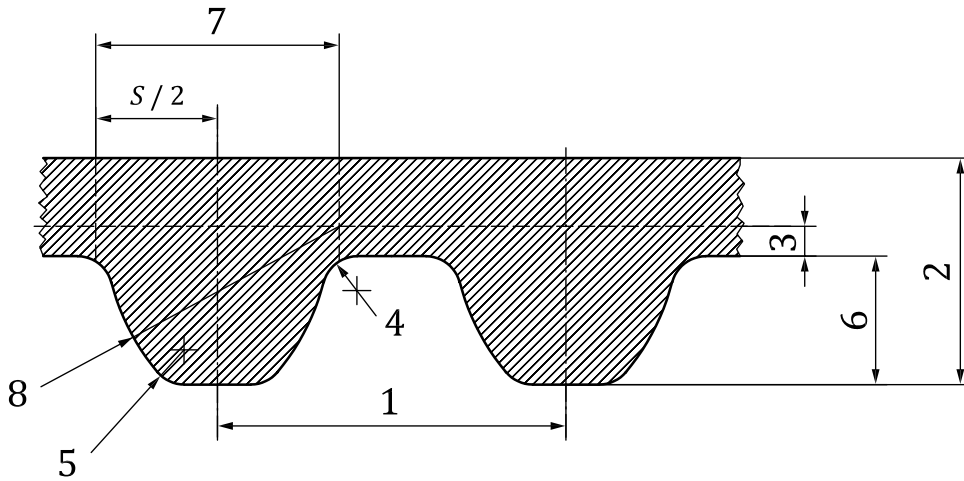
**Figure 3 — Nominal tooth dimensions (profile) for YR and ZR****Table 3 — Nominal tooth dimensions for types YR and ZR**

Dimensions in millimetres  
Angles in degrees

Key number	Symbol	Nominal profile	
		Type YR	Type ZR
1	$p_b$	8	9,525
2	$2\beta$	30	32
3	$h_s$	5,1	5,4
4	$a$	0,75	0,75
5	$r_r$	0,8	1,00
6	$h_t$	2,8	3,2
7	$S$	5,3	5,5
Tooth form parameter		$k$	1,228

**6.4 Belt tooth dimensions — Curvilinear tooth belts of types YS and ZS**

The nominal tooth dimensions for curvilinear tooth belts of types YS and ZS are shown in [Figure 4](#) and given in [Table 4](#).



**Key**

- 1 tooth pitch ( $p_b$ )
- 2 height ( $h_s$ )
- 3 pitch line differential ( $a$ )
- 4 root radius ( $r_r$ )
- 5 tip radius ( $r_a$ )
- 6 tooth height ( $h_t$ )
- 7 tooth width ( $S$ )
- 8 tooth radius ( $R$ )

**Figure 4 — Nominal tooth dimensions (profile) for types YS and ZS**

**Table 4 — Nominal tooth dimensions for types YS and ZS**

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Dimensions in millimetres

Angles in degrees

<https://standards.iteh.ai/catalog/standards/iso/e4af0952-6055-281f70b1/iso-21342-2019>

Key number	Symbol	Nominal profile	
		Type YS	Type ZS
1	$p_b$	8	9,525
2	$h_s$	5,2	5,7
3	$a$	0,686	0,686
4	$r_r$	0,8	0,95
5	$r_a$	0,8	0,95
6	$h_t$	2,95	3,53
7	$S$	5,2	6,19
8	$R$	5,2	6,19

**6.5 Belt pitch length and tolerances**

Belt pitch length is defined by the number of teeth multiplied by tooth pitch,  $p_b$ . The belt pitch length,  $L_p$ , shall be agreed between the parties concerned. Pitch length tolerances are given in [Table 5](#).