INTERNATIONAL STANDARD

ISO 12003-2

Third edition
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Tractors for agriculture and forestry — Roll-over protective structures on narrow tractors —

Part 2: Rear-mounted ROPS

Tracteurs agricoles et forestiers — Structures de protection contre le retournement (ROPS) pour tracteurs à voie étroite — Partie 2: ROPS montées à l'arrière

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Foreword

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The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

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For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 23, *Tractors and machinery for agriculture and forestry*, Subcommittee SC 2, *Common tests*.

This third edition cancels and replaces the second edition (ISO 12003-2:2008), which has been technically revised.

The main changes compared to the previous edition are as follows:

- the main title has been changed, referencing type of tractor, from “Agricultural and forestry tractors” to “Tractors for agriculture and forestry”;
- the seat anchorage test procedures of OECD have been added as an optional test;
- the ergonomic folding ROPS test procedures of OECD have been added as an optional test;
- definitions for unballasted mass, plane, track width and maximum permissible mass have been added
- tractor mass limits for unballasted tractor has been specified;
- the allowable mass ratio (1,75) has been specified;
- reference mass limits have been added;
- tractor lashings method of lashing has been changed;
- seat position during test has been updated to include seats with adjustable backrest,
- clearance zone has been updated for clarity and information for reversible seat has been added;
- Figure 17 has been updated to be harmonize with OECD Code 6; specifically, the key “g” has been added to indicate failure at any stage when load drops below 0,8F_{max};
- cold weather embrittlement test has been added;

— reversible seat operator seat zones has been updated to harmonize with OECD code 7.

A list of all parts in the ISO 12003 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

Testing of roll-over protective structures (ROPS) for narrow tractors for agriculture and forestry intends to minimize the likelihood of driver injury resulting from accidental overturning during normal operation (e.g. field work) of the tractor. The strength of the roll-over protective structure is tested by applying loads to simulate actual loads which can be imposed on the cab or frame when the tractor overturns either to the rear or to the side without free fall. The tests allow observations to be made on the strength of the structure and the attachment brackets to the tractor and also of the tractor parts that may be affected by the load imposed on the structure. This document also includes optional testing for seat anchorage points and folding efforts of rear-mounted roll-over protective structure designed to fold.

The tests are made using special rigs that are intended to simulate such loads as are imposed on a protective structure, when the tractor overturns. These tests enable observations to be made on the strength of the protective structure and any brackets attaching it to the tractor and any parts of the tractor which transmit the test load.

Provision is made to cover both tractors with the conventional forward-facing driving position only and those with a reversible driving position, which is in agreement with the relevant OECD test code practice (see Reference[4]). For tractors with a reversible driving position, a clearance zone is defined to be the combined clearance zones for the two driving positions.

It is recognized that there can be designs of tractors, such as lawn-mowers, and certain forestry machines such as forwarders, for which this document is not appropriate.

NOTE For regular tractors, see ISO 3463[2] (dynamic test) and ISO 5700[3] (static test).

Tractors for agriculture and forestry — Roll-over protective structures on narrow tractors —

Part 2: Rear-mounted ROPS

1 Scope

This document specifies procedures for both the static and dynamic strength testing of roll-over protective structures (ROPS) rear-mounted on narrow tractors. It defines the clearance zone and acceptance conditions for rigid or tiltable, rear, two-post roll bar, frame and cab ROPS, and is applicable to tractors so equipped having the following characteristics:

— a ground clearance of not more than 600 mm beneath the lowest points of the front- and rear-axle housings (not considering lower points on the axle differential);

— a fixed or adjustable minimum track width of one of the two axles of less than 1 150 mm and with the overall width of the other axle being less than that of the first axle, including where the two axles are fitted with rims and tyres of the same size;

— a fixed driving position and a mass greater than 400 kg, unballasted, including the ROPS and tyres of the largest size recommended by the manufacturer;

— a reversible driving position (reversible seat and steering wheel), with a mass greater than 400 kg, unballasted, including the ROPS and tyres of the largest size recommended by the manufacturer and maximum unballasted mass less than 3 500 kg and maximum permissible mass less than 5 250 kg;

— a mass ratio less than 1,75;

— a ROPS of the rollbar, frame or cab type, mounted partly or entirely behind the seat index point and having a zone of clearance whose upper limit is (810 + a_v) mm above the seat index point in order to provide a sufficiently large area or unobstructed space for the protection of the driver.

This document also specifies optional testing procedures for both seat anchorage points and folding efforts of rear-mounted ROPS designed to fold.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 630-1, *Structural steels — Part 1: General technical delivery conditions for hot-rolled products*

ISO 630-2, *Structural steels — Part 2: Technical delivery conditions for structural steels for general purposes*

ISO 630-3, *Structural steels — Part 3: Technical delivery conditions for fine-grain structural steels*

ISO 630-4, *Structural steels — Part 4: Technical delivery conditions for high yield strength quenched and tempered structural steel plates and wide flats*

ISO 2408, *Steel wire ropes — Requirements*

ISO 5353, *Earth-moving machinery, and tractors and machinery for agriculture and forestry — Seat index point*

ISO 13854:2017, *Safety of machinery — Minimum gaps to avoid crushing of parts of the human body*

ISO 12003-1:2021, *Tractors for agriculture and forestry — Roll-over protective structures on narrow tractors — Part 1: Front-mounted ROPS*

ISO 12934, *Tractors and machinery for agriculture and forestry — Basic types — Vocabulary*

ISO 80000-1, *Quantities and units — Part 1: General*

ASTM A370, *Standard Test Methods and Definitions for Mechanical Testing of Steel Products*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 12934 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— ISO Online browsing platform: available at https://www.iso.org/obp

— IEC Electropedia: available at https://www.electropedia.org/

3.1
roll-over protective structure
ROPS
framework protecting drivers of *agricultural tractors* (3.15), which minimizes the likelihood of driver injury resulting from accidental overturning during normal field work

Note 1 to entry: The ROPS is characterized by the provision of space for a clearance zone, either inside the envelope of the structure or within a space bounded by a series of straight lines from the outer edges of the structure to any part of the tractor that might come into contact with the ground; it is capable of supporting the tractor in an overturned position.

3.2
rear-mounted ROPS
two-post, roll-bar-type, *roll-over protective structure* (3.1) mounted on the tractor rearwards of the driving seat, or a frame or cab

Note 1 to entry: Compare with front-mounted ROPS described in ISO 12003-1.

3.3
unballasted mass
mass of the tractor in working order with tanks and radiators full, *roll-over protective structure* (3.1) with cladding and any track equipment or additional front-wheel drive components required for normal use

Note 1 to entry: Not included are the operator, optional ballast weights, additional wheel equipment, special equipment and loads.

[SOURCE: ISO 5700:2013, 3.2]

3.4
maximum permissible mass
m_{max}
maximum mass of the tractor stated by the manufacturer to be technically permissible and declared on the vehicle's identification plate and/or in the operator's handbook

3.5
reference mass
m_t
mass, not less than the maximum *unballasted mass* (3.3), selected by the manufacturer for calculation of the energy inputs to be used in the tests

3.6
mass ratio
m_r
ratio of

$$m_r = \frac{m_{max}}{m_t}$$

3.7
reference plane
vertical plane, generally longitudinal to the tractor and passing through the seat index point and the steering-wheel centre

Note 1 to entry: Normally, this reference plane coincides with the *longitudinal median plane* (3.8) of the tractor.

3.8
longitudinal median plane
median longitudinal plane
symmetric longitudinal plane
vertical plane Y passing through the mid-points of AB, perpendicular to AB, A and B being such that

— for each wheel, the vertical plane passing through its axis cuts the mid-plane of the wheel following a straight line Δ which meets the supporting surface of the vehicle at one point, and

— A and B are two points thus defined which correspond to two wheels, both of which are either steering or powered wheels, situated respectively at the two ends of the same real or imaginary axle

Note 1 to entry: The mid-plane of the dual wheels being equidistant from the inner edge of one wheel and the outer edge of the other, the straight line Δ is, in this particular case, the intersection of the mid-plane of the dual wheels and the vertical plane passing through the axis of the axle pin.

Note 2 to entry: Adapted from ISO 612:1978, Clause 5[1].

Note 3 to entry: The longitudinal median plane may also be applied to track-laying tractors.

Note 4 to entry: See Figure 1.

[SOURCE: ISO 5700:2013, 3.8]

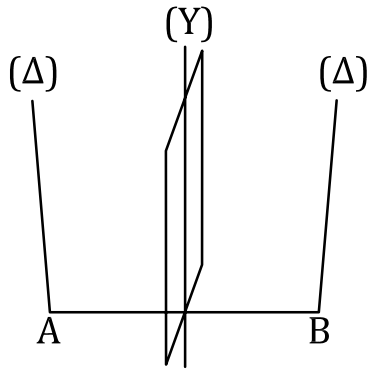


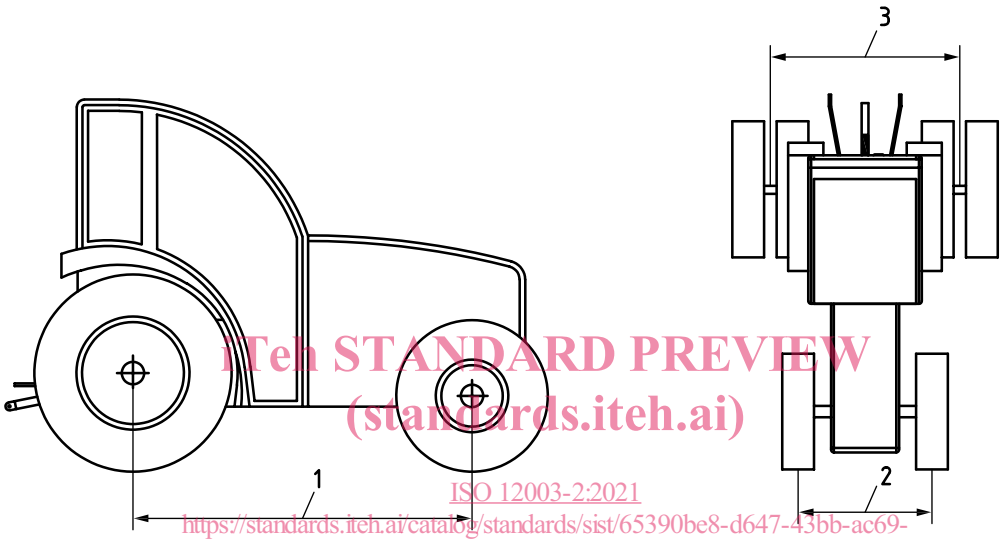
Figure 1 — Longitudinal median plane

3.9
track
tread
distance at ground level between two vertical planes passing through the centreline of ground contact of the tires parallel to the *longitudinal median plane* (3.8) of the tractor with the wheels in the straight-ahead position

Note 1 to entry: In the case of dual wheels, it is the distance at ground level between two planes passing through the centerline of the dual wheels. In the case of track-laying tractors, it is the distance between the two vertical planes passing through the centerline of ground contact of the tracks.

Note 2 to entry: See Figure 2.

[SOURCE: ISO 789-13:2018, 3.3]



Key
1 wheel base
2 track
3 track (dual wheels)

Figure 2 — Track and wheelbase of wheeled tractor

3.10
wheelbase
distance at ground level between two vertical planes passing through the centres of the front wheels and the rear wheels with tractor and wheels in the same straight ahead position

Note 1 to entry: See Figure 2.

[SOURCE: ISO 789-13:2018, 3.2]

3.11
horizontal loading test
application of a horizontal load to the rear, front and side of the *roll-over protective structure* (3.1)

3.12
crushing test
application of a vertical static load through a beam placed laterally across the uppermost members of the *rear-mounted ROPS* (3.2)

3.13
impact test
application of a dynamic load produced by a block acting as a pendulum

3.14
foldable ROPS
two-post *roll-over protective structure* (3.1) with hand raising/lowering directly managed by the operator (with or without partial assistance)

3.15
agricultural tractor
self-propelled agricultural vehicle having at least two axles and wheels, or endless tracks, particularly designed to pull agricultural trailers and pull, push, carry and operate implements used for agricultural work (including forestry work), which may be provided with a detachable loading platform

Note 1 to entry: The agricultural vehicle has a maximum design speed of not less than 6 km/h and may be equipped with one or more seats.

[SOURCE: ISO 12934:2013, 3.1]

3.16
hand-operated foldable ROPS
rear-mounted dual pillar protective structure with hand raising/lowering directly managed by the operator (with or without partial assistance)

3.17
automated foldable ROPS
rear-mounted dual pillar protective structure with full assisted raising/lowering operations

3.18
locking system
device fitted to lock, by hand or automatically, the ROPS in the raised or lowered positions

3.19
grasping area
portion of the ROPS and/or additional handle fitted to the ROPS where the operator is allowed to carry out the raising/lowering operations

3.20
accessible part of the grasping area
area where the ROPS is handled by the operator during the raising/lowering operations

Note 1 to entry: This area shall be defined with regard to the geometric centre of cross sections of the grasping area.

3.21
accessible zone
volume where a standing operator can apply a force in order to raise/lower the ROPS

3.22
pinching
dangerous point where parts move in relation to each other or to fixed parts in such a way as may cause persons or certain parts of their bodies to be pinched

3.23
shear
dangerous point where parts move along each other or along other parts in such a way as may cause persons or certain parts of their bodies to be pinched or shorn

3.24
place to stand
place on the tractor platform accessible from the driving position main access with sufficient space for a standing operator

3.25
static friction
force that resists initiation of movement of one surface sliding over another surface

Note 1 to entry: The force required to initiate movement is equal to that which resists initiation of movement.

[SOURCE: ISO 15359:1999, 3.2]

3.26
dynamic friction
force that resists maintained sliding of one surface over another surface

Note 1 to entry: The force required to maintain sliding is equal to that which resists the maintenance of sliding.

[SOURCE: ISO 15359:1999, 3.4, modified — The original term was "kinetic friction".]

4 Symbols

For the purposes of this document, the symbols in Table 1 apply.

Table 1 — Symbols

Symbol	Description	Unit
a_h	Half of the horizontal seat adjustment	mm
a_v	Half of the vertical seat adjustment	mm
B	Minimum overall width of the tractor	mm
B_b	Maximum outer width of the rear-mounted ROPS	mm
D	Deflection of the ROPS for the calculated basic energy at the point of impact (dynamic test) or at the point of, and in line with, the load application (static test)	mm
D_p	Permanent deformation	mm
D_e	Elastic deformation	mm
E_{il}	Energy to be absorbed during horizontal loading	J
E_{is}	Energy to be absorbed during side loading	J
F	Static load force	N
F_{max}	Maximum static load force occurring during loading, with the exception of overload	N
F_v	Vertical crushing force	N
H	Falling height of the pendulum block's centre of gravity	mm
I	Moment of inertia about rear axle, whatever the mass of the rear wheels may be	$kg{\cdot}m^2$
L	Tractor reference wheelbase	mm
m	Tractor unballasted mass (see 3.3)	kg
m_t	Reference mass (see 3.5)	kg
W	Overall width of the upper part of the protective structure	mm
m_{max}	Tractor maximum permissible mass	kg
m_r	Mass ratio of the maximum permissible mass (m_{max}) to the reference mass (m_t) (see 3.6)	Kg/kg

5 Test apparatus and equipment

5.1 Apparatus for both dynamic and static testing

5.1.1 Clearance zone framework

Means to prove that the clearance zone has not been entered during the test: a measuring rig conforming with Figures 11 and 12 may be used.

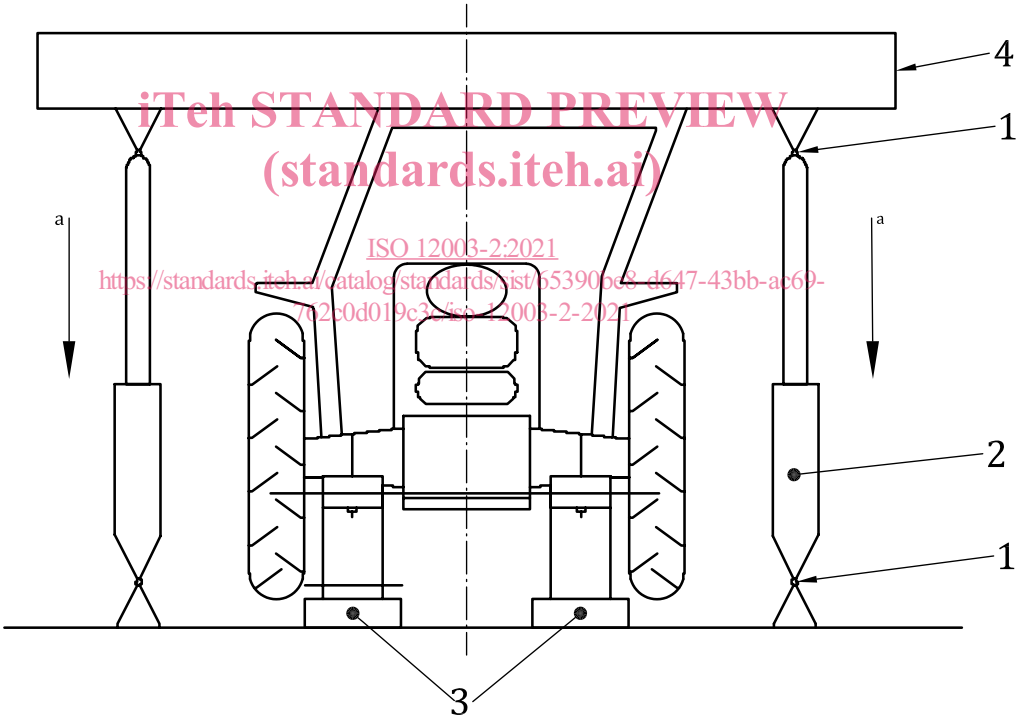
5.1.2 Apparatus for crushing tests

The crushing tests shall be carried out by means of the elements described in 5.1.2.1 and 5.1.2.3.

5.1.2.1 Means to apply downward force on the protective structure, such as that shown in Figure 3, including a stiff beam with a width of 250 mm.

5.1.2.2 Equipment to measure total vertical force applied.

5.1.2.3 Suitable axle supports shall be provided so that the tractor tyres do not bear the crushing force.



Key

1 universal pin joints
2 hydraulic cylinder
3 axle supports
4 stiff beam
[a] Direction of force.

Figure 3 — Crushing test — Example