

FINAL
DRAFT

INTERNATIONAL
STANDARD

ISO/FDIS
24132

ISO/TC 8/SC 2

Secretariat: ANSI

Voting begins on:
2023-01-26

Voting terminates on:
2023-03-23

Ships and marine technology — Design and testing of marine transfer arms for liquefied hydrogen

iTeh Standards
(<https://standards.iteh.ai>)
Document Preview

[ISO 24132](#)

<https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>

RECIPIENTS OF THIS DRAFT ARE INVITED TO SUBMIT, WITH THEIR COMMENTS, NOTIFICATION OF ANY RELEVANT PATENT RIGHTS OF WHICH THEY ARE AWARE AND TO PROVIDE SUPPORTING DOCUMENTATION.

IN ADDITION TO THEIR EVALUATION AS BEING ACCEPTABLE FOR INDUSTRIAL, TECHNOLOGICAL, COMMERCIAL AND USER PURPOSES, DRAFT INTERNATIONAL STANDARDS MAY ON OCCASION HAVE TO BE CONSIDERED IN THE LIGHT OF THEIR POTENTIAL TO BECOME STANDARDS TO WHICH REFERENCE MAY BE MADE IN NATIONAL REGULATIONS.



Reference number
ISO/FDIS 24132:2023(E)

© ISO 2023

iTeh Standards
(<https://standards.iteh.ai>)
Document Preview

ISO 24132

<https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>



COPYRIGHT PROTECTED DOCUMENT

© ISO 2023

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office
CP 401 • Ch. de Blandonnet 8
CH-1214 Vernier, Geneva
Phone: +41 22 749 01 11
Email: copyright@iso.org
Website: www.iso.org

Published in Switzerland

Contents

	Page
Foreword	vi
Introduction	vii
1 Scope	1
2 Normative references	1
3 Terms and definitions	2
4 Abbreviated terms	9
5 Design of the arms	10
5.1 Definition and description of the arms.....	10
5.1.1 General.....	10
5.1.2 Arms dimensions.....	11
5.2 Design basis.....	11
5.2.1 Product line diameter and product data.....	11
5.2.2 Material and grades.....	11
5.2.3 Stress analysis.....	12
5.2.4 Thermal analysis.....	14
5.3 Swivel joints.....	14
5.3.1 General.....	14
5.3.2 Product sealing arrangement.....	14
5.3.3 Bearing system.....	14
5.3.4 External sealing arrangement.....	14
5.3.5 Design.....	14
5.4 Structural bearings.....	15
5.4.1 Design.....	15
5.4.2 Protection of structural bearings.....	16
5.4.3 Grease sampling point.....	16
5.5 Accessories.....	16
5.5.1 Adjustable support (jack).....	16
5.5.2 Product purge gases injection line.....	17
5.5.3 Stowing locking device.....	17
5.5.4 Ladders and platforms.....	17
5.5.5 Vapour recovery lines.....	17
5.5.6 Liquid nitrogen line.....	17
5.5.7 Ice fall protection.....	17
5.5.8 Process connections.....	17
5.5.9 Drain connection.....	18
5.5.10 Vacuum insulation.....	18
5.6 Welding.....	18
5.7 Corrosion protection and embrittlement protection.....	18
5.7.1 Corrosion protection.....	18
5.7.2 Embrittlement protection.....	18
5.8 Maintenance.....	19
6 Safety systems	19
6.1 General.....	19
6.2 Two stage alarm and shutdown system.....	20
6.2.1 First stage.....	20
6.2.2 Second stage.....	20
6.3 Monitoring and alarm systems.....	20
6.3.1 Alarm envelopes.....	20
6.3.2 Arm positioning alarms system.....	20
6.3.3 Arm constant position monitoring system (CPMS).....	21
6.3.4 Pressure and hydraulic level alarm.....	21
6.4 ERS.....	21

6.4.1	General	21
6.4.2	Design of the ERS	21
6.4.3	Safety devices on the ERS	22
6.5	Safety devices	22
6.5.1	Fire safety requirements	22
6.5.2	Electrical safety requirements	23
6.5.3	Failure of power supply	23
6.5.4	Stray current protectors	24
6.5.5	Bonding	24
6.5.6	Safety for liquid oxygen	24
7	Connection with the ship	24
7.1	General	24
7.2	Design of QCDC	25
7.3	QCDC system	25
7.4	Flange cover	25
8	Hydraulic and electric control systems	26
8.1	General	26
8.2	Arms operations	26
8.3	Hydraulic components	27
8.4	Electric components	28
8.5	Testing of control systems	28
8.6	Remote control	28
8.7	Transfer arms jetty control console	29
9	Inspections and tests	29
9.1	General	29
9.2	Prototype test	29
9.2.1	General	29
9.2.2	Swivel joint	29
9.2.3	ERS	33
9.2.4	Insulation flange	35
9.2.5	QCDC	35
9.3	Manufacturing inspection and tests	37
9.3.1	General	37
9.3.2	Materials	37
9.3.3	Welding	37
9.3.4	Non-destructive test	37
9.3.5	Dimensional inspection	37
9.3.6	Pressure test	38
9.3.7	ERS	38
9.3.8	Insulating flange (stray current protector)	39
9.3.9	QCDC	39
9.3.10	Hydraulic circuit test	39
9.4	Factory acceptance tests	39
9.5	Site acceptance tests	41
9.5.1	General	41
9.5.2	Transfer arm assembly	41
9.5.3	Hydraulic circuit	42
10	Quality assurance and control	42
10.1	General	42
10.2	Quality plan	43
11	Required documentation	43
Annex A (informative) Design data sheets		44
Annex B (informative) Reference table and figures		57
Annex C (informative) Examples of documentation requirements		61

Annex D (informative) Method of gas displacement	67
Bibliography	68

iTeh Standards
(<https://standards.iteh.ai>)
Document Preview

[ISO 24132](https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132)

<https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 8, *Ships and marine technology*, Subcommittee SC 2, *Marine environment protection*.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

<https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>

Introduction

The twenty-first session of the Conference of the Parties (COP21) of the United Nations Framework Convention on Climate Change (UNFCCC) was held in Paris, France in December 2015 and finally adopted an agreement for the prevention of global warming, the Paris Agreement. The Agreement requires Parties' efforts to achieve zero net anthropogenic greenhouse gas (GHG) emissions during the second half of the 21st century. The International Maritime Organization (IMO) adopted a strategic plan to reduce GHG emissions from the maritime sector by 50 % in 2050 and finally to zero level within this century. Since the required reduction of GHG emissions is not attainable by a simple improvement in efficiency, the substitution of alternative fuels, including hydrogen, ammonia, and biofuels, for present fossil energies must be considered. Among them, hydrogen is one of the most present energy carriers, not only as fuel, but also as storage and transportation media.

A massive and long-distance transport of hydrogen by ships from production areas to consumption areas would be necessary because production plants are often constructed far from consumption areas, which are typically cities and industrial areas where hydrogen would be used in gas/steam turbine power plants and transportation systems such as railways, automobiles and ships.

In the marine transportation system of liquefied hydrogen, transfer from shore to ship would take place using transfer arms. A number of transfer arms are currently used for the loading and unloading of liquefied natural gas (LNG) at marine terminals. However, the temperature difference between LNG (-162 °C) and liquefied hydrogen (-253 °C) is critical and requires a significant change in the design of the transfer arms. Transfer systems minimize heat loss by applying high performance heat insulation technology. Liquid oxygen (-183 °C) formation on the outer surface of the system should be strictly prevented because some materials can detonate unpredictably from sources of ignition such as flames, sparks or impact from light blows if soaked in liquefied oxygen (LO₂). Leakage should also be prevented because the hydrogen molecule is small in size and hydrogen gas is flammable over a wide range of concentrations.

To ensure the safe and smooth transportation of liquefied hydrogen, well-qualified transfer arms that are compatible with the on-board equipment of hydrogen carriers should be installed at each terminal. This document is, therefore, developed to provide technical guidance and safety requirements for liquefied hydrogen marine transfer arms.

<https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>

Ships and marine technology — Design and testing of marine transfer arms for liquefied hydrogen

1 Scope

This document specifies the design, minimum safety requirements, and inspection and testing procedures for liquefied hydrogen (LH2) marine transfer arms intended for use at onshore LH2 terminals handling LH2 carriers. It also covers the minimum requirements for safe LH2 transfer between ship and shore.

Although the requirements for power/control systems are covered, this document does not include all of the details for the design and fabrication of standard parts and fittings associated with transfer arms. This document is mainly focused on hard pipe type transfer systems; hose type transfer systems are not described in detail in the general description of this document. However, hose type transfer systems can also be considered as reasonable vacuum insulated technology for the design of transfer arms for liquefied hydrogen.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3452-1, *Non-destructive testing — Penetrant testing — Part 1: General principles*

ISO 4406, *Hydraulic fluid power — Fluids — Method for coding the level of contamination by solid particles*

ISO 9934-1, *Non-destructive testing — Magnetic particle testing — Part 1: General principles*

ISO 10474, *Steel and steel products — Inspection documents*

ISO 10497, *Testing of valves — Fire type-testing requirements*

ISO 16904, *Petroleum and natural gas industries — Design and testing of LNG marine transfer arms for conventional onshore terminals*

ISO 17636-1, *Non-destructive testing of welds — Radiographic testing — Part 1: X- and gamma-ray techniques with film*

ISO 17636-2, *Non-destructive testing of welds — Radiographic testing — Part 2: X- and gamma-ray techniques with digital detectors*

IEC 60079-10-1, *Explosive atmospheres — Part 10-1: Classification of areas - Explosive gas atmospheres*

IEC 60079-0, *Explosive atmospheres — Part 0: Equipment - General requirements*

IEC 60079-1, *Explosive atmospheres — Part 1: Equipment protection by flameproof enclosures “d”*

IEC 60079-2, *Explosive atmospheres — Part 2: Equipment protection by pressurized enclosure “p”*

IEC 60079-5, *Explosive atmospheres — Part 5: Equipment protection by powder filling “q”*

IEC 60079-6, *Explosive atmospheres — Part 6: Equipment protection by liquid immersion “o”*

IEC 60079-7, *Explosive atmospheres — Part 7: Equipment protection by increased safety “e”*

IEC 60079-11, *Explosive atmospheres — Part 11: Equipment protection by intrinsic safety “i”*

IEC 60079-14, *Explosive atmospheres — Part 14: Electrical installations design, selection and erection*

IEC 60079-18, *Explosive atmospheres — Part 18: Equipment protection by encapsulation “m”*

IEC 60079-25, *Explosive atmospheres — Part 25: Intrinsically safe electrical systems*

IEC 60034-5, *Rotating electrical machines — Part 5: Degrees of protection provided by the integral design of rotating electrical machines (IP code) — Classification*

IEC 60529, *Degrees of protection provided by enclosures (IP Code)*

IEC 62305-3, *Protection against lightning — Part 3: Physical damage to structures and life hazard*

BOILER ASME, PRESSURE VESSEL CODE SECTION IX

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

3.1

apex swivel

articulated, fluid-carrying joint located between the *inboard arm* (3.19) and *outboard arm* (3.32)

Note 1 to entry: See [Figure B.2](#).

Note 2 to entry: It provides *luffing* (3.25) of the outboard arm relative to the inboard arm.

3.2

attitude

various modes of use and/or location of the *transfer arm* (3.58) (i.e. manoeuvring, stowed, connected, hydrostatic test, and maintenance)

Note 1 to entry: The transfer arm can take several positions for each attitude.

3.3

base riser **riser**

vertical assembly which bolts to the loading platform and supports the articulated assembly of the *transfer arm* (3.58)

Note 1 to entry: See [Figure B.2](#).

Note 2 to entry: Sometimes referred to as "standpost".

3.4

bottom swivel

swivel joint accommodates the *pitching* (3.34) motion of the *LH2 carrier* (3.24) and is located adjacent to *presentation flange* (3.36) in horizontal part of the *TSA* (3.59)

Note 1 to entry: See [Figure B.2](#).

3.5

brinelling

permanent indentation in the *swivel* (3.54) or *structural bearing* (3.49) raceways caused by excessive loading of balls or rollers

3.6**cargo manifold**

pipe assembly mounted on board a *LH2 carrier* (3.24) to which the *presentation flange* (3.36) or *QCDC* (3.38) of the *transfer arm* (3.58) is connected

Note 1 to entry: See [Figure B.2](#).

3.7**cavitation**

formation and collapse of bubbles in a liquid at or below the liquid saturated vapour pressure

Note 1 to entry: The collapse releases energy and may cause erosion at the cavitation sites, sometimes with an audible sound and vibration.

Note 2 to entry: Such low pressures occur in high velocity zones such as the inner radius of elbows, or at places with variations of diameters.

3.8**clash**

contact during design operational conditions, or as a result of an emergency separation

Note 1 to entry: This contact can occur between any part of a *transfer arm* (3.58) and:

- adjacent transfer arm while both arms are operating, or one arm is operating, and the other arm is stowed (e.g. the counterweights (3.10));
- adjacent section of the same transfer arm (e.g. triple swivel assembly (3.59) and the outboard arm (3.32));
- loading platform equipment (e.g. counterweight (3.10) and piping or valves).

3.9**contact angle**

α

angle between the plane of the *swivel joint* (3.54) or *structural bearing* (3.49) balls or rollers and the centre of contact at the ball or roller raceway interface

<https://standards.iteh.ai/catalog/standards/iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>

3.10 counterweight

system of weights used to balance the *inboard arm* (3.19) and *outboard arm* (3.32) assemblies

Note 1 to entry: Some *transfer arms* (3.58) have a single counterweight for this function and others have multiple counterweights.

3.11**design pressure**

pressure for which the *transfer arm* (3.58) is designed

Note 1 to entry: See [Table A.1](#).

3.12**design temperature**

range of temperatures for which the *transfer arm* (3.58) is designed

Note 1 to entry: See [Table A.1](#).

3.13**drift**

longitudinal and/or lateral displacement of the *LH2 carrier* (3.24) due to the influence of environmental forces

Note 1 to entry: See also *surge fore* (3.51) or *surge aft* (3.50) and *sway* (3.53).

3.14
emergency release system
ERS

system that provides a positive means of quick release of *transfer arms* (3.58) and safe isolation between the *LH2 carrier* (3.24) and shore, following a predefined procedure including an *emergency shutdown (ESD)* (3.15)

Note 1 to entry: This is also known as an *emergency release coupling* (ERC).

Note 2 to entry: See [Figure B.2](#).

3.15
emergency shutdown
ESD

method that safely and effectively stops the transfer of LH2 and vapour between the *LH2 carrier* (3.24) and shore

3.16
freeboard

vertical distance between the ship's deck and the water level at the manifold location

Note 1 to entry: See [Table A.3](#) and [Figure A.1](#).

3.17
free wheel

ability of a hydraulically operated *transfer arm* (3.58) when connected to a *LH2 carrier* (3.24) to follow freely, without hydraulic restraint, the vertical and horizontal motions of the LH2 carrier's manifold (draft changes and *sway* (3.53) and surge motions)

3.18
heave

vertical motion of the *LH2 carrier* (3.24) due to wave action

Note 1 to entry: See [Table A.4](#) and [Figure A.2](#).

3.19
inboard arm

product-carrying pipe and any structural members contained between the *apex swivel* (3.1) and the *trunnion swivel* (3.60)

Note 1 to entry: See [Figure B.2](#).

3.20
included angle

angle formed between *inboard arm* (3.19) and *outboard arm* (3.32)

Note 1 to entry: See [Figure B.2](#).

Note 2 to entry: The maximum and minimum included angles are left to the transfer arm manufacturer.

Note 3 to entry: The included angle in the stowed position of the *transfer arms* (3.58) is such, that the arms are parked with the *triple swivel assembly* (3.59) behind the berthing line.

3.21
insulating flange

electrical insulating system, usually dedicated, that is installed in the lower end of the *outboard arm* (3.32) or in the vertical part of the *triple swivel assembly* (3.59)

Note 1 to entry: Its purpose is to prevent stray currents from causing an arc at the *LH2 carrier's* (3.24) flange as the *transfer arm* (3.58) is connected or disconnected.

3.22**jack**

permanent, adjustable load-carrying mechanism potentially installed in the *triple swivel assembly* (3.59) to transfer a portion of the *transfer arm* (3.58) fluid weight to the deck instead of the *LH2 carrier's* (3.24) manifold

Note 1 to entry: See [Figure B.2](#).

3.23**jetty control centre**

control centre situated on or adjacent to the jetty primarily to control and/or monitor the *transfer arms* (3.58)

Note 1 to entry: Sometimes referred to as "jetty control room" or "local control room."

3.24**LH2 carrier****LH2C**

tank ship designed for the carriage of LH2

3.25**luffing**

rotary motions of the *inboard arm* (3.19) and *outboard arm* (3.32) in the vertical plane

Note 1 to entry: See [Figure B.2](#).

3.26**main hydraulic unit****MHU**

hydraulic unit that generates hydraulic power to ensure the normal operation and emergency release sequence of the arms

3.27**manifold setback**

horizontal distance between the board side of the *LH2 carrier* (3.24) and the face of the *cargo manifold* (3.6)

Note 1 to entry: See [Table A.3](#) and [Figure A.1](#).

3.28**manifold spacing**

horizontal distance between two adjacent *cargo manifold* (3.6) flange axes

Note 1 to entry: See [Table A.3](#) and [Figure A.1](#).

3.29**middle swivel**

swivel joint accommodates *yawing* (3.62) and surge of the *LH2 carrier* (3.24) and is located between the *top swivel* (3.56) and *bottom swivel* (3.4) in the vertical part of the *TSA* (3.59)

Note 1 to entry: See [Figure B.2](#).

3.30**onshore LH2 terminal**

LH2 exporting or receiving terminal that is located on shore and that has marine *transfer arms* (3.58) for the loading or unloading of *LH2 carriers* (3.24) in a harbour or other sheltered coastal location

3.31**operating envelope**

volume in which *presentation flange(s)* (3.36) of a (group of) *transfer arm(s)* (3.58) is (are) required to operate

3.32

outboard arm

product-carrying pipe and any structural members contained between the *apex swivel* (3.1) and the *triple swivel assembly* (3.59)

Note 1 to entry: See [Figure B.2](#).

3.33

owner

designated agent

company or group of companies for whose use the *transfer arms* (3.58) are installed, responsible for the safe design and construction of the installation

3.34

pitch

rotation of the *LH2 carrier* (3.24) around the transversal horizontal axis

Note 1 to entry: See [Table A.4](#) and [Figure A.2](#).

3.35

powered emergency release coupling

PERC

powered device to provide a means of quick release of the *transfer arms* (3.58) when such action is required only as an emergency measure

3.36

presentation flange

transfer arm (3.58) flange for connection to either the *cargo manifold* (3.6) or *spool piece* (3.46)

Note 1 to entry: See [Figure B.2](#).

3.37

product

fluid transferred using *transfer arms* (3.58)

ISO 24132

Note 1 to entry: Fluids are LH2 or GH2. <https://standards.iso/6e90ebce-548c-48e6-909b-6f6c761e97ad/iso-24132>

3.38

quick disconnect coupler

QCDC

coupler

manual or hydraulic mechanical device used to connect the *transfer arm* (3.58) to the *cargo manifold* (3.6) or *spool piece* (3.46) without employing bolts

Note 1 to entry: See [Figure B.2](#).

3.39

remote pendant control

remote control

device to facilitate the fine manoeuvring operation of the *transfer arms* (3.58) from a remote location [e.g. *LH2 carrier's* (3.24) *cargo manifold* (3.6) area]

Note 1 to entry: The system can use a trailing wire or radio-controlled system.

3.40

riser and trunnion swivel assembly

fluid carrying system consisting of a *riser swivel* (3.42), *trunnion swivel* (3.60) and elbows, and mounted on top of the *base riser* (3.3)

Note 1 to entry: See [Figure B.2](#).