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Električni rotacijski stroji - 30-1. del: Razredi izkoristka enohitrostnih trifaznih motorjev s kratkostično kletko (koda IE)

Rotating electrical machines - Part 30-1: Efficiency classes of line operated AC motors (IE code)

Drehende elektrische Maschinen - Teil 30-1: Wirkungsrad-Klassifizierung von netzgespeisten Drehstrommotoren (IE-Code)

Machines électriques tournantes - Partie 30-1: Classes de rendement pour les moteurs à courant alternatif alimentés par le réseau (code IE)

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TITLE:

Rotating electrical machines - Part 30-1: Efficiency classes of line operated AC motors (IE code)

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49 INTERNATIONAL ELECTROTECHNICAL COMMISSION

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ROTATING ELECTRICAL MACHINES –

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Part 30-1: Efficiency classes of line operated AC motors (IE code)

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FOREWORD

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This second edition of IEC 60034-30-1 cancels and replaces the first edition of IEC 60034-30-1 (2014).

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The text of this standard is based on the following documents:

FDIS	Report on voting

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Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

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This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

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NOTE A table of cross-references of all IEC TC 2 publications can be found on the IEC TC 2 dashboard on the IEC website.

100 The committee has decided that the contents of this publication will remain unchanged until the
101 stability date indicated on the IEC web site under "<http://webstore.iec.ch>" in the data related to
102 the specific publication. At this date, the publication will be

- 103 • reconfirmed,
- 104 • withdrawn,
- 105 • replaced by a revised edition, or
- 106 • amended.

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INTRODUCTION

110 This first part of the IEC standard series, 60034-30, provides for the global harmonization of
111 energy-efficiency classes of electric motors. It deals with all kinds of electric motors that are
112 rated for line operation (including starting at reduced voltage). This includes 50 Hz and/or 60
113 Hz single- and three-phase low voltage induction motors, regardless of their rated voltage, as
114 well as line-start synchronous motors.

115 The second part of this standard series (IEC 60034-30-2) is prepared for motors rated for
116 variable voltage and frequency supply.

117 This second edition of the first part introduces a new efficiency class, IE5. It should be noted
118 that IE class definition is generally independent of the output power – frame size assignment.
119 As standardized dimensions and outputs in the standard IEC 60072 is based on today's
120 technology (up to IE4), it may be challenging to implement highest IE classes according to IEC
121 60072 standardized frame sizes.

122 Especially motors with lower output power ratings may need to be designed and manufactured
123 in one frame size bigger than frame size assigned in IEC 60072-1 to reach IE4 and IE5 efficiency
124 levels.

125 For a given power and frame size it is generally easier to achieve a higher motor efficiency
126 when the motor is designed for and operated directly on-line with a 60 Hz supply frequency
127 rather than on 50 Hz as explained in Note 1.

128 NOTE 1 As the utilization and size of motors are related to torque rather than power the theoretical power of single-
129 speed motors increases linearly with supply frequency (and hence with speed), i.e. by 20 % from 50 Hz to 60 Hz.

130 I²R winding-losses are dominant especially in small and medium sized induction motors. They basically remain
131 constant at 50 Hz and 60 Hz as long as the torque is kept constant. Although windage, friction and iron losses
132 increase with frequency, they play a minor role especially in motors with a number of poles of four and higher.
133 Therefore, at 60 Hz, the losses increase less than the 20 % power increase when compared to 50 Hz and
134 consequently, the efficiency is improved.

135 In practice, both 60 Hz and 50 Hz power designations of single-speed motors usually conform to standard power
136 levels in accordance with IEC 60072-1. Therefore, an increased rating of motor power by 20 % is not always possible.
137 However, the general advantage of 60 Hz still applies when the motor design is optimized for the respective supply
138 frequency rather than just re-rated.

139 The difference in efficiency between 50 Hz and 60 Hz varies with the number of poles and the size of the motor. In
140 general, the 60 Hz efficiency of three-phase, cage-induction motors in the power range from 0,75 kW up to 375 kW
141 is between 2,5 percentage points to less than 0,5 percentage points greater when compared to the 50 Hz efficiency.
142 Only large 2-pole motors may experience a reduced efficiency at 60 Hz due to their high share of iron, windage and
143 friction losses.

144 It is not expected that all manufacturers will produce motors for all efficiency classes, nor all
145 ratings of a given class.

146 Users should dimension motors in their applications correctly based on the load profile,
147 operating hours in order to maximize energy savings considering most energy efficient solutions
148 in addition that all other requirements set by the application are covered. It may not be energy
149 efficient to select motors of a high efficiency class for intermittent or short time duty due to
150 increased inertia and start-up losses.

151 NOTE 2 The application guide IEC/TS 60034-31:2021 gives further information on useful applications of high-
152 efficient electric motors.

153 In order to achieve a significant market share it is essential for high-efficiency motors to meet
154 national/regional standards for assigned powers in relation to mechanical dimensions (such as
155 frame-size, flanges). Standard IEC 60072-1:2022 defines the relationship between mechanical
156 dimensions and rated output as well there are several national/regional frame assignment
157 standards (JIS C 4212, NBR 17094, NEMA MG13, SANS 1804 and others). As this standard
158 (IEC 60034-30-1) defines energy-efficiency classes independent of dimensional constraints it
159 may not be possible in all markets to produce motors with higher efficiency classes and maintain
160 the mechanical dimensions of the national/regional standards.
161

162 Together with demands to create higher energy efficiency classes, components and equipment
163 also material efficiency should not be forgotten. Based on physics there will be a need to use
164 more materials like electric steel, copper, and aluminium to be able to design and manufacture
165 higher and higher efficient motors. Consequently, it may not be possible to design for example
166 IE5 class motors utilizing same frame sizes as IE4 class motors as well as motors will be heavier
167 requiring most probably redesigning the application.

168
169 IE codes are not limited only to motors and are used to classify other components such as
170 frequency converters (IEC 61800-9-2). The same standard defines also IES classes to
171 combinations of components (such as power drive systems).

172 However, it is anticipated that other components are rated with a comparable system: IE1
173 meaning low efficiency up to IE5 meaning the highest efficiency.

174 The efficiency levels in this standard for 50 Hz and 60 Hz are not always entirely consistent
175 across all numbers of poles and over the whole power range.

176 NOTE 3 The efficiency levels for 60 Hz motors were assigned for compatibility with U.S. and North American legal
177 requirements.

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ROTATING ELECTRICAL MACHINES –

Part 30-1: Efficiency classes of line operated AC motors (IE code)

185 1 Scope

186 This part of IEC 60034 specifies efficiency classes for single-speed electric motors that are
187 rated according to IEC 60034-1 or IEC 60079-0 and are rated for operation on a sinusoidal 50
188 Hz, 60 Hz and/or 50/60 Hz voltage supply and:

- 189 • have a rated power P_N from 0,12 kW to 1 000 kW
- 190 • have a rated voltage U_N from 50 V up to and including 1 000 V
- 191 • have 2, 4, 6 or 8 poles
- 192 • are capable of continuous operation at their rated power with a temperature rise within the
193 specified insulation temperature class

194 NOTE 1 Most motors covered by this standard are rated for duty type S1 (continuous duty). However, some
195 motors that are rated for other duty cycles are still capable of continuous operation at their rated power and
196 these motors are also covered.

- 197 • are marked with any ambient temperature within the range of -20 °C to $+60\text{ °C}$

198 NOTE 2 The rated efficiency and efficiency classes are based on 25 °C ambient temperature according to
199 IEC 60034-2-1.

200 NOTE 3 Motors exclusively rated for temperatures outside the range -20 °C and $+60\text{ °C}$ are considered to be
201 of special construction and are consequently excluded from this standard.

202 NOTE 4 Smoke extraction motors with a temperature class of up to and including 400 °C are covered by this
203 standard.

- 204 • are marked with an altitude up to 4 000 m above sea level.

205 NOTE 5 The rated efficiency and efficiency class are based on a rating for altitudes up to 1 000 m above sea
206 level.

207 This standard establishes a set of nominal efficiency values based on supply frequency, number
208 of poles and motor output power. No distinction is made between motor technologies, supply
209 voltage or motors with increased insulation designed specifically for converter operation even
210 though these motor technologies may not all be capable of reaching the higher efficiency
211 classes (see Table 1). This makes different motor technologies fully comparable with respect
212 to their energy efficiency potential.

213 NOTE 6 Regulators should consider the above constraints when assigning national minimum energy-efficiency
214 performance standards (MEPS) with respect to any particular type of motor.

215 The efficiency of power-drive systems is not covered by this standard. Motor losses due to
216 harmonic content of the supply voltage, losses in cables, filters and frequency-converters, are
217 not covered.

218 Motors with flanges, feet and/or shafts with mechanical dimensions different from IEC 60072-1
219 are covered by this standard.

220 Geared motors are covered by this standard including those incorporating non-standard shafts
221 and flanges.

222 Excluded are:

- 223 • Single-speed motors with 10 or more poles or multi-speed motors.
- 224 • Motors with mechanical commutators (such as DC motors).

225 • Motors completely integrated into a machine (for example pump, fan and compressor) that
 226 cannot be practically tested separately from the machine even with provision of a temporary
 227 end-shield and drive-end bearing. This means the motor shall: a) share common
 228 components (apart from connectors such as bolts) with the driven unit (for example, a shaft
 229 or housing) and b) not be designed in such a way as to enable the motor to be separated
 230 from the driven unit as an entire motor that can operate independently of the driven unit.
 231 That is, for a motor to be excluded from this standard, the process of separation shall render
 232 the motor inoperative.

233 (TEAO, IC418) Totally enclosed air-over machines, i.e. totally enclosed frame-surface
 234 cooled machines intended for exterior cooling by a ventilating means external to the
 235 machine, are covered by this standard. Efficiency testing of such motors may be performed
 236 with the fan removed and the cooling provided by an external blower with a similar airflow
 237 rate as the original fan.

238 • Motors with integrated frequency-converters (compact drives) when the motor cannot be
 239 tested separately from the converter. Energy efficiency classification of compact drives shall
 240 be based on the complete product (PDS ie. Power Drive System) and is defined in IEC
 241 61800-9-2.

242 NOTE 7 A motor is not excluded when the motor and frequency-converter can be separated, and the motor can
 243 be tested independently of the converter.

244 • Brake motors when the brake is an integral part of the inner motor construction and can
 245 neither be removed nor supplied by a separate power source during the testing of motor
 246 efficiency.

247 NOTE 8 Brake motors with a brake coil that is integrated into the flange of the motor are covered as long as it
 248 is possible to test motor efficiency without the losses of the brake (for example by dismantling the brake or by
 249 energizing the brake coil from a separate power source).

250 When the manufacturer offers a motor of the same design with and without a brake the test
 251 of motor efficiency may be done on a motor without the brake. The determined efficiency
 252 may then be used as the rating of both motor and brake motor.

253 • Submersible motors specifically designed to operate wholly immersed in a liquid.

254 • Smoke extraction motors with a temperature class above 400 °C.

255 2 Normative references

256 The following documents, in whole or in part, are normatively referenced in this document and
 257 are indispensable for its application. For dated references, only the edition cited applies. For
 258 undated references, the latest edition of the referenced document (including any amendments)
 259 applies.

260 IEC 60034-1, *Rotating electrical machines – Part 1: Rating and performance*

261 IEC 60034-2-1, *Rotating electrical machines – Part 2-1: Standard methods for determining
 262 losses and efficiency from tests (excluding machines for traction vehicles)*

263 IEC 60034-2-3, *Rotating electrical machines – Part 2-3: Specific test methods for determining
 264 losses and efficiency of converter-fed AC induction motors*

265 IEC 60034-6, *Rotating electrical machines – Part 6: Methods of cooling (IC Code)*

266 IEC/TS 60034-25, *Rotating electrical machines – Part 25: Guidance for the design and
 267 performance of a.c. motors specifically designed for converter supply*

268 IEC 60038, *IEC standard voltages*

269 IEC 60079-0, *Explosive atmospheres – Part 0: Equipment – General requirements*