

INTERNATIONAL
STANDARD

ISO
4580

First edition

**Aerospace — Drive, internal, TORX®
PARALOBE®, driver bit — Geometrical
definition, gaging and technical
requirements**

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Foreword

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The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 20, *Aircraft and space vehicles*, Subcommittee SC 4, *Aerospace fastener systems*. ISO/PRF 4580

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

The International Organization for Standardization (ISO) draws attention to the fact that it is claimed that compliance with this document may involve the use of a patent.

ISO takes no position concerning the evidence, validity and scope of this patent right.

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Aerospace — Drive, internal, TORX® PARALOBE®, driver bit — Geometrical definition, gaging and technical requirements

1 Scope

This document specifies basic dimensions, characteristics and engineering requirements for TORX® PARALOBE®¹⁾ driver bits used with aerospace fasteners.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 4579, *Aerospace — Drives, internal, TORX® PARALOBE® drive — Geometrical definition, gaging and technical requirements*

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <http://www.electropedia.org/>

3.1

driver bit

tool to induce a torque into a fastener's recess (3.2)

3.2

recess

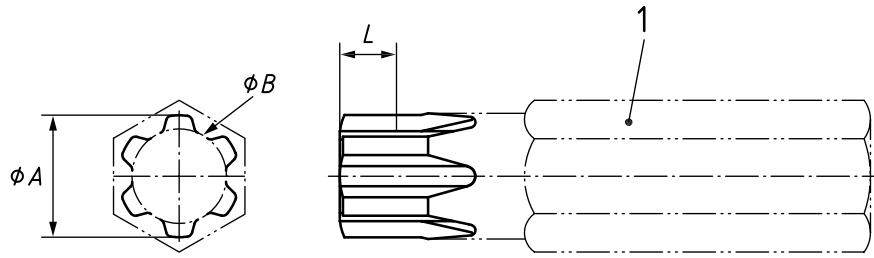
geometry in a fastener that allows attaching a tool in order to induce a torque to enable tightening and untightening of a fastener

4 Basic driver bit configuration

4.1 General

The basic driver bit configuration shall be in accordance with [Figure 1](#). Driver bits according to this document shall be used in conjunction with fasteners having an internal TORX® PARALOBE® drive according to ISO 4579.

1) TORX PARALOBE is the trademark of a product supplied by Acument Intellectual Properties, LLC, 6125 Eighteen Mile Road, Sterling Heights, MI 48314, USA. This information is given for the convenience of users of this document and does not constitute an endorsement by ISO of the products named. Equivalent products may be used if they can be shown to lead to the same results.



Key

- ϕA configuration diameter (see Tables 1 and 2)
- ϕB configuration inscribed diameter (see Tables 1 and 2)
- L configuration length (see Tables 1 and 2)
- 1 driver bit marking

Figure 1 — Basic driver bit configuration

The drive size descriptor shall appear on surface of driver bit. The manufacturer’s symbol shall also appear on the surface of driver bit.

EXAMPLE:

PARALOBE 25SI

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4.2 Basic driver bit configuration dimensions — metric

Table 1 — Driver bit dimensions — metric

Drive code	Drive size descriptor	Configuration diameter	Configuration inscribed diameter	Configuration length	Configuration torque
		mm	mm	min. mm	min. N · m
001	1SI	0,89	0,64	0,38	0,175
002	2SI	1,02	0,71	0,46	0,256
003	3SI	1,21	0,84	0,53	0,424
004	4SI	1,37	0,99	0,61	0,662
005	5SI	1,50	1,10	0,64	0,891
006	6SI	1,80	1,38	0,76	1,65
007	7SI	2,10	1,59	0,91	2,51
008	8SI	2,44	1,85	1,07	4,01
009	9SI	2,64	2,01	1,12	5,11
010	10SI	2,90	2,18	1,22	6,69
015	15SI	3,45	2,64	1,47	11,6
020	20SI	4,08	3,15	1,70	19,5
025	25SI	4,69	3,56	1,96	28,9
027	27SI	5,27	4,08	2,18	42,4
030	30SI	5,84	4,51	2,44	57,6
040	40SI	7,02	5,41	2,95	99,9
045	45SI	8,27	6,48	3,48	167
050	50SI	9,35	7,21	3,99	237

Table 1 (continued)

Drive code	Drive size descriptor	$\varnothing A$	$\varnothing B$	L	Configuration torque min. N · m
		Configuration diameter mm	Configuration inscribed diameter mm	Configuration length min. mm	
055	55SI	11,86	9,42	5,08	504
060	60SI	14,02	10,92	6,10	810
070	70SI	16,45	12,93	7,19	1 320
080	80SI	18,59	14,43	8,18	1 890
090	90SI	21,12	16,60	9,32	2 810
100	100SI	23,46	18,45	10,36	3 850
110	110SI	25,36	19,38	11,28	4 700

4.3 Basic driver bit configuration dimensions — inch

Table 2 — Driver bit dimensions — inch^a

Drive code	Drive size descriptor	$\varnothing A$	$\varnothing B$	L	Configuration torque min. lbf · in
		Configuration diameter inch	Configuration inscribed diameter inch	Configuration length min. inch	
001	1SI	0.035	0.025	0.015	1.55
002	2SI	0.040	0.028	0.018	2.27
003	3SI	0.048	0.033	0.021	3.75
004	4SI	0.054	0.039	0.024	5.86
005	5SI	0.059	0.044	0.025	7.89
006	6SI	0.071	0.055	0.030	14.6
007	7SI	0.083	0.063	0.036	22.2
008	8SI	0.096	0.073	0.042	35.5
009	9SI	0.104	0.079	0.044	45.2
010	10SI	0.114	0.086	0.048	59.2
015	15SI	0.136	0.104	0.058	103
020	20SI	0.161	0.124	0.067	173
025	25SI	0.185	0.140	0.077	256
027	27SI	0.208	0.161	0.086	375
030	30SI	0.230	0.178	0.096	510
040	40SI	0.277	0.213	0.116	884
045	45SI	0.326	0.255	0.137	1 480
050	50SI	0.368	0.284	0.157	2 100
055	55SI	0.467	0.371	0.200	4 460
060	60SI	0.552	0.430	0.240	7 170
070	70SI	0.648	0.509	0.283	11 700
080	80SI	0.732	0.568	0.322	16 700
090	90SI	0.832	0.654	0.367	24 900

^a The dimensions in this table are rounded. Therefore the general formula for converting inches into mm cannot be used.

Table 2 (continued)

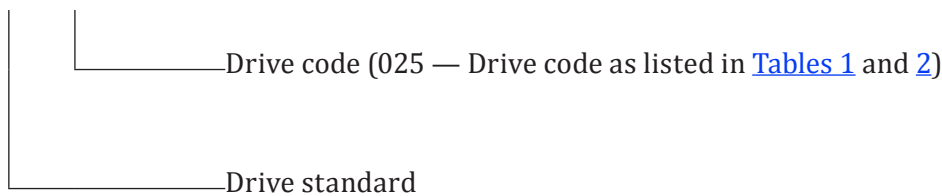
Drive code	Drive size descriptor	$\varnothing A$	$\varnothing B$	L	Configuration torque
		Configuration diameter inch	Configuration inscribed diameter inch	Configuration length min. inch	min. lbf · in
100	100SI	0.924	0.727	0.408	34 100
110	110SI	0.999	0.763	0.444	41 600

^a The dimensions in this table are rounded. Therefore the general formula for converting inches into mm cannot be used.

4.4 Driver bit designation

The driver bit designation shall be as shown in the following example:

ISO 4579-025

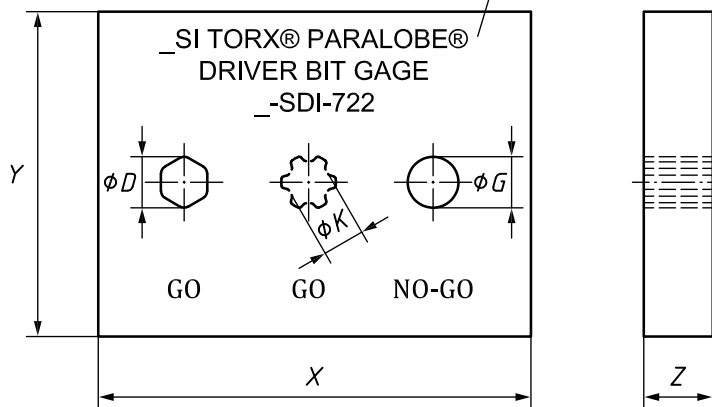


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5 Driver bit inspection

5.1 Driver bit gaging equipment

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Key

- X gage body length (see Tables 3 and 4)
- Y gage body width (see Tables 3 and 4)
- Z gage body thickness (see Tables 3 and 4)
- $\varnothing D$ configuration circumscribed diameter go gage (see Tables 3 and 4)
- $\varnothing K$ configuration inscribed diameter go gage (see Tables 3 and 4)
- $\varnothing G$ configuration circumscribed diameter no-go gage (see Tables 3 and 4)
- 1 gage identification marking

Figure 2 — Driver bit inspection gage