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Resistance welding — Vocabulary —

Part 1:

Spot, projection and seam welding

Soudage par résistance — Vocabulaire — L

(https:Partie 1:lards.iteh.ai)

Soudage par points, par bossages et à la molette

ISO 17677-1:2021

Widerstandsschweißen — Begriffe —

Teil 1:

Punkt-, Buckel- und Rollennahtschweißen



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ISO 17677-1:2021

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Contents			Page	
Forev	vord		iv	
1	Scop	oe	1	
2	Norr	Normative references		
3	Terms and definitions			
	3.1	Welding and testing procedures	1	
	3.2	Hardware and tools	3	
	3.3	Welding process and parameters	4	
	3.4	Measurements and values	9	
Biblio	ograph	hv	27	

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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This document was prepared by Technical Committee ISO/TC 44, *Welding and allied processes*, Subcommittee SC 6, *Resistance welding and allied mechanical joining*, in collaboration with the European Committee for Standardization (CEN) Technical Committee CEN/TC 121, *Welding and allied processes*, in accordance with the Agreement on technical cooperation between ISO and CEN (Vienna Agreement).

This third edition cancels and replaces the second edition (ISO 17677-1:2019), of which it constitutes a minor revision. The main changes compared to the previous edition are as follows:

- the terms and definitions of ISO 14329 have been implemented;
- editorial changes have been made.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Official interpretations of ISO/TC 44 documents, where they exist, are available from this page: https://committee.iso.org/sites/tc44/home/interpretation.html.

Resistance welding — Vocabulary —

Part 1:

Spot, projection and seam welding

1 Scope

This document establishes a vocabulary of terms and definitions for resistance spot welding, projection welding and seam welding.

NOTE In addition to terms used in English and French, two of the three official ISO languages, this document gives the equivalent terms in German; these are published under the responsibility of the member body for Germany (DIN). However, only the terms and definitions given in the official languages can be considered as ISO terms and definitions.

2 Normative references

There are no normative references in this document.

3 Terms and definitions

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at https://www.iso.org/obp
- IEC Electropedia: available at http://www.electropedia.org/

3.1 Welding and testing procedures af 1562-f176-458c-a392-1fc02eaaaeba/iso-17677-1-2021

3.1.1

chisel test

test in which a chisel is driven between the sheets near to adjacent welds until either fracture occurs or until the metal near the weld yields or bends

3.1.2

cross tension test

tensile test of a resistance welded specimen to determine the mechanical properties and failure mode of the weld

3.1.3

cross-wire welding

projection welding (3.1.11) of crossed wires or rods

3.1.4

direct welding

resistance welding secondary circuit variant in which welding current and *electrode force* (3.3.5) are applied to the workpieces by directly opposed *electrodes* (3.2.1) and only one weld is made by one welding operation

Note 1 to entry: See Figure 12 for typical arrangements.

3.1.5

indirect welding

resistance welding secondary circuit variant in which the welding current flows through the workpieces in locations away from, as well as at, the welds

Note 1 to entry: See Figure 13 for typical arrangements.

3.1.6

multiple impulse welding

welding with more than one impulse

Note 1 to entry: See Figures 4 to 7 for related time and *electrode force* (3.3.5) diagrams.

3.1.7

multiple spot welding

spot welding in which two or more welds are made simultaneously in one welding operation

Note 1 to entry: Examples are parallel spot welding (3.1.8) and series spot welding (3.1.14).

3.1.8

parallel spot welding

resistance welding secondary circuit variant in which the secondary current is divided in parallel electrical paths to make two or more welds simultaneously

Note 1 to entry: See Figure 11 a).

3.1.9

peel test

destructive test in which a resistance-welded lap joint is tested by applying a peel force which results in stresses mainly in the thickness direction of the weld

3.1.10

pillow test

destructive test in which internal pressure is applied in order to test for leaks and the strength of a seam weld

3.1.11

projection welding

resistance welding in which the resulting welds are localized at predetermined points by projections, embossments or intersections, concentrating force and current by their geometry

Note 1 to entry: The projections are raised on, or formed from, one or more of the *faying surfaces* (3.3.16) and collapse during welding.

3.1.12

resistance spot welding

resistance welding process producing a weld at the *faying surfaces* (3.3.16) between overlapping parts by the heat obtained from resistance to the flow of welding current through the workpieces from the *electrodes* (3.2.1) serving to concentrate the welding current and pressure at the weld area

3.1.13

seam welding

resistance welding in which force is applied continuously and current is applied continuously or intermittently to produce a linear weld, the workpieces being between two *electrode wheels* (3.2.5) or an electrode wheel and an electrode bar

3.1.14

series spot welding

resistance welding secondary circuit variant in which the secondary current is conducted through the workpieces and *electrodes* (3.2.1) in a series electrical path to simultaneously form multiple resistance spot, seam or projection welds

Note 1 to entry: See Figures 1 and 11 b).

3.1.15

roll spot welding

resistance welding process variant that produces intermittent spot welds using one or more rotating circular electrodes

Note 1 to entry: The rotation of the *electrodes* (3.2.1) may or may not be stopped during the making of a weld.

3.1.16

shunt weld

first weld on a series of spot welds, which acts as a shunt

3.1.17

tensile shear test

test in which a lap-welded specimen is subjected to a tensile force with the aim of determining the mechanical properties of the specimen

3.1.18

stitch welding

spot welding in which successive welds overlap and ards

3.2 Hardware and tools DS://standards.iteh.ai)

3.2.1

electrode

resistance welding electrode

component of the electrical circuit that supplies electrical power and applies electrode force (3.3.5) to https the workpiece h.ai/catalog/standards/iso/11af1562-f176-458c-a392-1fc02eaaaeba/iso-1767

EXAMPLE Rotating wheel, rotating roll, bar, cylinder, plate, clamp, chuck, variations thereof.

3.2.1.1

angled electrode

bent electrode

electrode for spot or stitch welding (3.1.18) whose electrode working face (3.2.6) is not normal to the mounting axis

3.2.1.2

contact electrode

resistance welding electrode (3.2.1) designed to conduct secondary current through a workpiece without making a weld

3.2.1.3

offset electrode

eccentric electrode

electrode for spot or stitch welding (3.1.18) whose electrode working face (3.2.6) is not concentric with the axis of the *electrode adaptor* (3.2.2)

3.2.2

electrode adaptor

shank

device used to attach an electrode (3.2.1) to an electrode holder (3.2.4)

3.2.3

electrode cap

replaceable electrode (3.2.1) tip used in resistance spot welding (3.1.12)

3.2.4

electrode holder

device holding a welding *electrode* (3.2.1)

3.2.5

electrode wheel

seam welding wheel

rotating resistance welding electrode (3.2.1) of ring or disc shape

3 2 6

electrode working face

<resistance spot welding and projection welding> end of a resistance welding electrode (3.2.1) in contact
with the workpiece

3.2.7

welding head

device comprising the force generation and guiding system, carrying an *electrode holder* (3.2.4), platen or *electrode wheel* (3.2.5)

3.3 Welding process and parameters

3.3.1 iTeh S

chill time

ciiii tiiile

quench time

period of time between the end of the weld current and the start of post-heat current during which no current flows and the weld is cooled by the *electrodes* (3.2.1)

Note 1 to entry: See Figure 5.

3.3.2

ISO 17677-1:202

cool time andards.iteh.ai/catalog/standards/iso/11af1562-f176-458c-a392-1fc02eaaaeba/iso-17677-1-2021 pause time

time interval between successive heat times in multiple impulse welding (3.1.6) or seam welding (3.1.13)

Note 1 to entry: See Figures 4 and 7.

3.3.3

current delay time

time interval between reaching set force and initiation of current flow

Note 1 to entry: See Figure 3.

3.3.4

current-off time

period of time between the cessation of current in one *welding cycle* (3.3.43) and the beginning of current in the next one

3.3.5

electrode force

force applied by the electrodes to the workpieces

Note 1 to entry: See welding force (3.3.44).

3.3.6

welding electrode force

electrode force applied during weld time (3.3.40)

3.3.7

forging electrode force

forge force

electrode force applied in the forge force time

3.3.8

dynamic electrode force

electrode force applied during the actual welding cycle (3.3.43)

3.3.9

static electrode force

electrode force with no current flowing and no movement in the welding machine

3.3.10

theoretical electrode force

force, neglecting friction and inertia, available at the electrodes of a resistance welding machine by virtue of the initial force and the theoretical mechanical properties of the system

3.3.11

electrode force programme

predetermined sequence of changes of force during welding

3.3.12

electrode force and current programme

predetermined sequence of changes of force and current during the welding cycle (3.3.43)

3.3.13

electrode movement during welding

physical displacement of *electrodes* (3.2.1) due to thermal expansion, shrinkage and indentation during welding

3.3.14

electrode skidding

lateral movement of the *electrodes* (3.2.1) relative to the surface of the workpieces during the welding process $\frac{3.2.1}{1.202}$ $\frac{3.2.1}{1.202}$ $\frac{3.2.1}{1.202}$

3.3.15

electrode stroke

physical movement of *electrodes* (3.2.1) in the electrode axis during the *welding cycle* (3.3.43)

3.3.16

faying surface

mating surface of a workpiece in contact with another workpiece to which it is to be joined

3.3.17

force application time

total time of the application of force by the *electrodes* (3.2.1) to the workpiece in a *welding cycle* (3.3.43)

Note 1 to entry: See Figures 3 to 7.

3.3.18

force fall time

time between the start of force decrease to zero force

Note 1 to entry: See Figures 3 to 7.

3.3.19

force maintenance time

time in the *welding cycle* (3.3.43) during which a force is maintained at a predetermined level, excluding the *force rise time* (3.3.20) and *force fall time* (3.3.18)

Note 1 to entry: See Figures 3 to 7.

3.3.20

force rise time

time between the start of a force increase and the application of the predetermined force

Note 1 to entry: See <u>Figures 3</u> to <u>7</u>.

3.3.21

electrode force time

force time

time during which the force is built up and applied

Note 1 to entry: See Figures 3 to 7.

3.3.22

forge time

<welding force programme> time of increased force applied during or after the passage of the welding current

Note 1 to entry: See Figure 6.

3.3.23

head approach time

time of movement of the *electrode* (3.2.1) from the rest position to contact with the workpiece

Note 1 to entry: See Figures 3 to 7.

3.3.24

head return time

time of electrode return from contact with the workpiece to the rest position

3.3.25

heat-affected zone

HAZ

portion of non-melted parent metal whose microstructure has been affected by the heat of welding

Note 1 to entry: See Figure 2. atalog/standards/iso/11af1562-f176-458c-a392-1fc02eaaaeba/iso-17677-1-2021

[SOURCE: ISO/TR 25901-1:2016, 2.1.2.2, modified — "by the heat of welding" has been added to the definition and Note 1 to entry has been added.]

3.3.26

heat time

duration of any one impulse in multiple impulse welding (3.1.6) or resistance seam welding (3.1.13)

Note 1 to entry: See Figures 4 to 7.

3.3.27

hold time

duration of *electrode force* (3.3.5) after cessation of current flow

Note 1 to entry: See Figures 3 to 7.

3.3.28

off-time

force set off-time

time after hold time until next start of working cycle

Note 1 to entry: See actual force off-time (3.3.29).

3.3.29

actual force off-time

actual off-time

measured period of time between two successive *welding cycles* (3.3.43) when no *electrode force* (3.3.5) is being applied to the workpiece

Note 1 to entry: See *off-time* (3.3.28).

Note 2 to entry: See Figures 3 to 7.

3.3.30

opposing forces

forces tending to separate the electrodes, such as from a mismatch of workpieces, spring back, sealants, etc.

Note 1 to entry: See welding force (3.3.44).

3.3.31

post-heat time

temper time

time following the *chill time* (3.3.1) during which a current is passed through the weld for heat treatment or improvement of weld microstructure

Note 1 to entry: See Figures 5 and 6.

3.3.32

preheat time

duration of preheating current flow applied before the welding current

Note 1 to entry: See Figures 5 and 6.

3.3.33

expulsion

splash

spatter

SO 17677-1:2021

flash dards iteh ai/catalog/standards/iso/11af1562-f176-458c-a392-1fc02eaaaeba/iso-17677-1-2021 metal particles expelled between the *faying surfaces* (3.3.16) of the components or between the components and electrodes during *resistance spot welding* (3.1.12), *projection welding* (3.1.11) or *seam welding* (3.1.13)

3.3.34

squeeze time

set time between the initiation of the welding cycle (3.3.43) and first application of current

Note 1 to entry: See actual squeeze time (3.3.35).

Note 2 to entry: See Figures 3 to 7.

3.3.35

actual squeeze time

actual time between the initiation of the *welding cycle* (3.3.43) and first application of current

Note 1 to entry: See squeeze time (3.3.34).

Note 2 to entry: The time and *electrode force* (3.3.5) diagrams of Figures 3 to 8 show squeeze time.

3.3.36

time base

time expressed in cycles of the power supply frequency or in milliseconds

3.3.37

upslope

controlled continuous increase of the current from a predetermined value or zero during a set time period

Note 1 to entry: See *down slope* (3.3.38).

3.3.38

down slope

controlled continuous decrease of the current until a predetermined value or zero is reached during a set time period

Note 1 to entry: See *upslope* (3.3.37).

3.3.39

weld contact area

area in the faying surface (3.3.16) through which welding current passes from one component to another during resistance welding

3.3.40

weld time

duration of continuous flow of welding current

Note 1 to entry: See Figures 3 to 7.

3.3.41

welding current programme

predetermined sequence of changes of current Standards

3.3.42

welding cycle time

time required to complete a welding cycle (3.3.43), excluding the time for positioning the electrodes (3.2.1)

Note 1 to entry: See Figures 3 to 7.

3.3.43

welding cycle ards.iteh.ai/catalog/standards/iso/11af1562-f176-458c-a392-1fc02eaaaeba/iso-17677-1-2021

<resistance welding> sequence of operations carried out by the machine to make a weld and return the electrodes (3.2.1) to their initial position

3.3.44

welding force

force acting on the faying surfaces (3.3.16), resulting from the electrode force (3.3.5) and any opposing forces (3.3.30), e.g. spring back of the workpieces, and the geometry of the parts

3.3.45

welding force programme

predetermined sequence of changes of force

3.3.46

work clearance stroke

physical displacement of *electrodes* (3.2.1), which allows them to move from one welding position to the next

Note 1 to entry: See Figure 8.

3.3.47

working cycle time

duration of a succession of operations carried out by a machine or gun for the making of a weld, including the return to the initial position

Note 1 to entry: See <u>Figures 3</u> to <u>7</u>.

3.3.48

working stroke

minimum movement of the *electrodes* (3.2.1) during the *welding cycle* (3.3.43)

Note 1 to entry: See Figure 8.

3.3.49

maximum stroke

high lift stroke

retract stroke

maximum electrode (3.2.1) stroke

3.4 Measurements and values

3.4.1

corona bond area

area surrounding the *nugget* (3.4.11) at the *faying surfaces* (3.3.16) in which only solid phase bonding has occurred

3.4.2

corona bond diameter

mean diameter of the corona bond area (3.4.1)

Note 1 to entry: See Figures 2 and 9. Teh Standards

3.4.3

current pass area (https://

area through which current passes from an electrode (3.2.1) to the workpiece, smaller than the electrode working face (3.2.6) and which varies during the welding operation

3.4.4

duty cycle

percentage of time during a specified period when a power source or its accessories can be operated at rated output without overheating

Note 1 to entry:
$$X_c = \frac{\sum (t_{on})}{t_{sn}} \times 100 \%$$

where $t_{\rm on}$ is the heat time, and $t_{\rm sp}$ is the specific period.

electrode indentation

spot or seam weld depression formed on the surface of workpieces by *electrodes* (3.2.1)

electrode indentation depth

maximum depth of the *electrode indentation* (3.4.5) measured in the direction of the *electrode force* (3.3.5)

Note 1 to entry: See Figure 2.

3.4.7

electrode indentation diameter

 $d_{\rm eu}$, $d_{\rm el}$

diameter of the *electrode indentation* (3.4.5)

Note 1 to entry: See Figure 2.

Note 2 to entry: If possible the mean value should be used.

3.4.8

electrode life

number of acceptable spot welds or length of weld seam that can be made with an electrode without any redressing or replacement of the electrode

3.4.9

electrode service life

electrode production life

number of acceptable spot welds or length of weld seam that can be made with an *electrode* (3.2.1) before the electrode is no longer useable

3.4.10

electrode misalignment

unintentional offset between the axes of the *electrodes* (3.2.1)

3.4.11

nugget

zone in spot, projection or seam weld where the metal has been melted

Note 1 to entry: See Figure 2.

3.4.12

nugget penetration

 $p_{\rm l}, p_{\rm l}$

maximum penetration of the nugget (3.4.11) into the upper or lower workpiece, measured perpendicular to the faying surface(s) (3.3.16) of the workpieces

Note 1 to entry: See Figure 2.

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3.4.13

nugget thickness

p

<spot, projection or seam weld> maximum thickness of the nugget (3.4.11) in two or more sheets
measured perpendicular to the faying surface(s) (3.3.16) of the workpieces

Note 1 to entry: For two sheets, $p = p_1 + p_0$; see Figure 2.

3.4.14

nugget overlap

0

<seam weld> length of common area between two adjacent overlapping seam weld nuggets (3.4.11)

Note 1 to entry: See Figure 14.

Note 2 to entry: The area contains the portion of the preceding weld nugget remolten by the succeeding weld.

3.4.15

seam weld width

width of the weld metal in the plane of the *faying surfaces* (3.3.16) in a direction normal to the longitudinal axis of the linear seam weld

3.4.16

seam weld nugget length

d,

length of individual weld nugget (3.4.11) in the seam welding (3.1.13) direction