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Matériel forestier — Débusqueuses à roues — Termes, définitions et spécifications commerciales

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Foreword

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This second edition cancels and replaces the first edition (ISO 13861:2000), which has been technically revised.

The main changes compared to the previous edition are as follows:

— added a new terminological entry for skidder and moved ISO 6814 to Bibliography

— figures moved to a new informative Annex A

— editorial changes.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

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Machinery for forestry — Wheeled skidders — Terms, definitions and commercial specifications

1 Scope

This document specifies terminology and required information as a general framework for identifying and describing the main dimensions and features of wheeled skidders.

It is applicable to articulated wheeled cable and grapple skidders.

NOTE The terminology and requirements given in this document will not necessarily all apply to a specific machine. Machines can be characterized by the dimensions and features which are relevant to them.

2 Normative references

There are no normative references in this document.

3 Terms and definitions

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For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— ISO Online browsing platform: available at https://www.iso.org/obp

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— IEC Electropedia: available at http://www.electropedia.org/

3.1 General

3.1.1
skidder
self-propelled machine designed to transport trees or parts of trees by trailing or dragging

[SOURCE: ISO 6814:2009, 2.3.1.15]

3.1.2
right hand
operator's right-hand side when facing in the normal direction of travel and with the machine in its primary functional mode

3.1.3
left hand
operator's left-hand side when facing in the normal direction of travel and with the machine in its primary functional mode

3.1.4
front
front of the operator when facing in the normal direction of travel and with the machine in its primary functional mode

3.1.5
rear
rear of the operator when facing in the normal direction of travel and with the machine in its primary functional mode

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3.1.6
GRP
ground reference plane
hard, flat, horizontal surface on which the machine is placed for measurements

3.2 Terms for masses

3.2.1
normal operating mass
total mass of the machine as specified, fully serviced, with full fluid levels and a 75 kg operator

3.2.2
maximum operating mass
total mass of the machine as specified, fully serviced, with full fluid levels and a 75 kg operator, including all machine options with the largest tyre or hydro-inflation combination and the manufacturer's maximum specified load

3.2.3
load per axle
normal operating mass (3.2.1) and *maximum operating mass* (3.2.2) on both the front and rear axles

3.3 Terms for main machine dimensions

3.3.1
total frame length
l_1
horizontal distance between the vertical planes perpendicular to the longitudinal axis passing through the farthest points on the *front* (3.1.4) and *rear* (3.1.5) of the machine, including fenders, tow bars, butt plate, etc., but excluding the fairlead, blade, or grapple

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3.3.2
overall length
l_2
horizontal distance from a vertical plane touching the forwardmost point of the machine, blade positioned to give maximum forward reach, to a vertical plane touching the rearmost point of the machine

3.3.3
wheelbase
l_3
horizontal distance from the centre of the front axle or front bogie axle assembly to the centre of the rear axle or rear bogie axle assembly when both axles are perpendicular to the longitudinal axis

3.3.4
articulation joint to maximum blade arc
l_4
horizontal distance from the centreline of the articulation joint to a vertical line tangent to the arc of the blade's lower edge as it passes from its maximum height h_3 to the lowest blade position h_4

3.3.5
articulation joint to front of machine
l_5
horizontal distance from the centreline of the articulation joint to a vertical plane touching the farthest point forward, blade excluded

3.3.6
articulation joint to front axle
l_6
horizontal distance from the centreline of the articulation joint to the centre of the front axle or front bogie axle assembly

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3.3.7
overall height
h_1
vertical distance between the *GRP* (3.1.6) and a horizontal plane passing through the highest point of the machine

3.3.8
blade height
h_2
vertical distance from the lower edge, resting on the *GRP* (3.1.6), to the top of the blade, decking lugs excluded

3.3.9
maximum blade lift of lower edge
h_3
maximum vertical height to which the lower edge of the blade can be raised from the *GRP* (3.1.6)

3.3.10
lowest blade position
h_4
vertical distance from the *GRP* (3.1.6) to the blade's lower edge with blade at its lowest position

3.3.11
ground clearance
h_5
vertical distance from the *GRP* (3.1.6) to the lowest point of the machine centre portion, i.e. 25 % of the *tread* (3.3.19) to either side of the longitudinal centreline

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3.3.12
ground clearance at articulation joint
h_6
vertical distance from the *GRP* (3.1.6) to the lowest point at the articulation joint

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3.3.13
loaded tire radius
r_1
vertical distance from the *GRP* (3.1.6) to the horizontal centre of the axle with the machine at *normal operating mass* (3.2.1)

3.3.14
main fairlead roller height
h_7
vertical distance from the horizontal centre of the main fairlead roller to the horizontal centre of the axle

3.3.15
winch height
h_8
vertical distance from the horizontal centre of the winch drum to the horizontal centre of the axle

3.3.16
rear axle to main fairlead roller
l_7
horizontal distance from the vertical centre of the rear axle to the vertical centre of the main fairlead roller

3.3.17
main fairlead roller diameter
d_1
diameter of main fairlead roller at its mid-length position

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3.3.18
overall width
w_1
horizontal distance between two vertical planes parallel to the longitudinal axis of the machine and passing through the farthest points on the two sides of this axis

3.3.19
tread
w_2
horizontal distance between two parallel vertical planes passing through the centreline of the tires on an axle

3.3.20
frame oscillation
a_1
angle that one frame will rotate from a horizontal datum, in both directions, without rotating the other frame, measured in degrees

3.3.21
axle oscillation
a_2
angle that one axle will rotate from a horizontal datum, in both directions, without rotating either frame, measured in degrees

3.3.22
clearance circle
d_2
diameter of the smallest circle that the outermost point on the machine will describe when turning, brakes unapplied, blade in travel position, unloaded

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3.3.23
angle of articulation
a_3
maximum angle of frame steering movement from the straight-ahead position between longitudinal centrelines of the front and rear frames, measured in degrees

3.3.24
blade width
w_3
horizontal distance between the outer edges of the blade

3.4 Terms for grapple dimensions

3.4.1
grapple reach
ll_1, ll_2, ll_3, ll_4
horizontal distance from the vertical centre of the rear axle to the vertical centre of the grapple pivot under the following conditions:

— ll_1 with the pivot in the highest, fully extended position;

— ll_2 with the pivot in the lowest, fully extended position;

— ll_3 with the pivot in the highest, fully retracted position;

— ll_4 with the pivot in the lowest, fully retracted position

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3.4.2
grapple lift
hh_1, hh_2, hh_3, hh_4
vertical distance from the horizontal centre of the rear axle to the horizontal centre of the grapple pivot under the following conditions:

— hh_1 with the pivot in the highest, fully retracted position;

— hh_2 with the pivot in the highest, fully extended position;

— hh_3 with the pivot in the lowest, fully retracted position;

— hh_4 with the pivot in the lowest, fully extended position

3.4.3
boom rotation
aa_1
angle in degrees from the longitudinal axis of the machine to the longitudinal centre of the boom at maximum swing position

3.4.4
rear axle to main swing boom pivot
ll_5
horizontal distance from the vertical centre of the rear axle to the vertical centre of the main swing boom pivot

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3.4.5
grapple height
hh_5, hh_6, hh_7
vertical distance from the centre of the upper pivot to the lowest point of the grapple arms under the following conditions:

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— hh_5 with the grapple fully open;

— hh_6 with the grapple in tip-to-tip position;

— hh_7 with the grapple fully closed

3.4.6
maximum grapple opening
ll_6
horizontal distance between the tips of the grapple arms the grapple fully open

3.4.7
area of grapple opening
A
cross-sectional area of the grapple opening in the tip-to-tip position

3.4.8
minimum log size
dd_1
smallest diameter of log which the grapple can hold in a fully closed position

3.4.9
grapple rotation
number of degrees through which the grapple can rotate

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3.5 Terms for grapple configurations

3.5.1
single function
configuration in which the grapple support assembly consists of a single arch and a pair of hydraulic cylinders allowing the grapple pivot to move through a fixed arc

3.5.2
dual function
configuration in which the grapple support assembly consists of a boom, arch, and two sets of hydraulic cylinders allowing the grapple pivot to describe a range of motion in a vertical longitudinal plane

3.5.3
swing boom
configuration in which the grapple support consists of a boom assembly which allows both horizontal and vertical grapple movement

3.6 Terms for butt plate dimensions

3.6.1
rear axle to butt plate
ll_7
horizontal distance from the centre of the rear axle to the rearward face of the butt plate

3.6.2
length of load support
ll_8
horizontal distance from the rearward face of the butt plate to the rearmost edge of the load support

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3.6.3
lowest butt plate position
hh_8
vertical distance from the *GRP* (3.1.6) to the lowest edge of the butt plate with the butt plate fully lowered

4 Required information

In addition to the identification of relevant dimensions and features as defined in Clause 3 (see also examples in Annex A), the following information shall be supplied where appropriate:

— tyre size;

— ply rating;

— inflation pressure;

— possible hydro-inflation;

— maximum and minimum for adjustable dimensions, e.g. *main fairlead roller height* (3.3.14) and *rear axle to main fairlead roller* (3.3.16);

— unequal front/rear or left/right for asymmetrical dimensions, e.g. *tread* (3.3.19), *angle of articulation* (3.3.23), *boom rotation* (3.4.3).

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