ISO /DIS/PRF 7856:2024(en)

ISO/TC 20

Secretariat: ANSI

ISO TC 204/WG 14

Date: 2024-12-252025-04-

Intelligent transport systems — Remote support for low speed automated driving systems (RS-LSADS) — Performance requirements, system requirements and performance test procedures

<u>Systèmes de transport intelligents — Téléassistance pour les systèmes de conduite automatisée à basse vitesse</u> (RS-LSADS) — Exigences de performance, exigences du système et procédures d'essai de performance

tps://standards.itehlai)

 $https://standards.iteh.ai/o \underbrace{PRO0F}_{so/9dcb26d4-ac3b-4423-b665-aec19ec03d6c/iso-prf-7856}$ 

**Edited DIS** -MUST BE USED FOR FINAL

### ISO-CD/PRF 7856: 20XX(E2025(en)

© ISO <del>2024</del>2025

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office CP 401 • Ch. Dede Blandonnet 8 CH-1214 Vernier, Geneva Phone: + 41 22 749 01 11 EmailE-mail: copyright@iso.org Website: www.iso.org

Published in Switzerland

## iTeh Standards (https://standards.iteh.ai) Document Preview

ISO/PRF 7856

https://standards.iteh.ai/catalog/standards/iso/9dch26d4-ac3h-4423-h666-aec19ec03d6c/iso-prf-7856

### ISO/<del>DIS</del>PRF 7856:<del>2024</del>2025(en)

### Contents

Forew	ord	iv
Introd	uction	v
1	Scope	1
2	Normative references	1
3	Terms and definitions	1
4	Symbols and abbreviated terms	3
4.1	Symbols	
4.2	Abbreviated terms	3
5	RS-LSADS architecture	4
6	Functions of RS-LSADS	8
6.1	General	8
6.2	Remote monitoring	8
6.3	Remote assistance	
6.4	Remote driving	8
7	RS-LSADS functional scenarios	9
7.1	Remote support scenarios	9
8	System requirements	15
8.1	General	
8.2	RS-LSADS state transition diagram	
	Communication performance for remote support	
9 9.1	GeneralGeneral	
9.1 9.2	Latency in remote support	
9.3	End-to-end information latency	
9.4	Information update rate	
9.5	Distance error due to latency	
9.6	Communication messages for remote support	23
10	RS-LSADS performance requirements	26
10.1	Remote monitoring performance	
10.2	Remote assistance performance	
10.3	Remote driving performance	
11	Scenario evaluation test procedures	21
11.1	General	
11.2	Test conditions	
11.3	Test procedures	
Annex	A (informative) An Example of RS-LSADS Implementation	
	B (informative) An example of the interaction between the control centre and the vehi	
Annex	for LSADS equipped vehicle mobility service	59
_		
Annex	C (informative) Examples of remote support required scenarios and specific operation	
	by RS-LSADS	61
Biblio	graphy	71
	FOR FINAL	



### ISO-CD/PRF 7856: 20XX(E2025(en)

#### **Foreword**

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those <a href="Intendedintended">Intended</a> for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO <a href="documentsdocument">document</a> should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see <a href="www.iso.org/directives">www.iso.org/directives</a>).

Attention is drawnISO draws attention to the possibility that some of the elements implementation of this document may be involve the subjectuse of (a) patent(s). ISO takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, ISO had not received notice of (a) patent(s) which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at www.iso.org/patents. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see ).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see <a href="https://www.iso.org/iso/foreword.html">www.iso.org/iso/foreword.html</a>.

This document was prepared by Technical Committee ISO/TC 204, Intelligent Transport Systems transport systems.

Any feedback or questions on this document should be directed to the user's national standards body. A \_aec19ec03d6c/iso-prf-7856 complete listing of these bodies can be found at <a href="https://www.iso.org/members.html">www.iso.org/members.html</a>.

ISO/<del>DISPRF</del> 7856:<del>2024</del>2025(en)

### Introduction

For the sustainable operation of mobility services using automated driving systems (ADS), it can be necessary to provide additional support for the functioning of the ADS in order to enable mobility services to continue beyond the constraints of the operational design domain (ODD). Such additional support can include human remote support, i.e. actions by humans outside the vehicle. The low speed of low speed automated driving systems (LSADS) equipped vehicles simplifies the provision of remote support.

In this document, remote support is defined as a combination of remote assistance and remote driving.

Currently, individual development and demonstration projects for remote support of LSADS are implemented in several regions and countries, including UK, US, CA, DE, FR, AU, KR, and JP, amongst others. One example of such an implementation is given in Annex A

This document indicates the technical requirements of remote support for LSADS (RS-LSADS) and is intended to provide a common basis for RS-LSADS development.

ISO/SAE PAS 22736 (SAE J3016) defines remote assistance and remote driving. In addition, in ISO 22737 external entity input is described. This document is intended to complement ISO 22737 by defining scenarios and requirements for remote assistance and remote driving.

## iTeh Standards (https://standards.iteh.ai) Document Preview

ISO/PRF 7856

https://standards.iteh.ai/catalog/standards/iso/9dch26d4-ac3h-4423-h666-aec19ec03d6c/iso-prf-7856



© ISO 2024-2025 – All rights reserved

# iTeh Standards (https://standards.iteh.ai) Document Preview

ISO/PRF 7856

https://standards.iteh.ai/catalog/standards/iso/9dcb26d4-ac3b-4423-b666-aec19ec03d6c/iso-prf-7856

# Intelligent transport systems — Remote support for low speed automated driving systems (RS-LSADS) — Performance requirements, system requirements and performance test procedures

#### 1 Scope

This document describes remote support provided to LSADS operated at Level 4 automation on predefined routes by a remotely located human in order to facilitate safe trip continuation. "Remote support" refers to the provision of information, or temporary performance of the dynamic driving task (DDT), and remote monitoring required for these functions.

This document is applicable to RS-LSADS in vehicles that provide passenger transport or logistics services on predefined routes.

This document specifies:

- the terms and definitions related to RS-LSADS and the system architecture of RS-LSADS;
- functions of RS-LSADS, which are: remote monitoring, remote assistance and remote driving that is operated under very limited conditions, and conditions under which they need to be activated;
- the performance requirements, system requirements and performance test procedures of RS-LSADS;
- the data to be communicated between vehicles and the remote support facility (but not protocols of other aspects of communication system).

This document is applicable to remote support of operational and tactical functions during continuous operations, but does not apply to strategic functions or to RS-LSADS daily startup or shutdown.

### 2 Normative references eh.ai/catalog/standards/iso/9dcb26d4-ac3b-4423-b666-aec19ec03d6c/iso-prf-7856

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO/SAE PAS 22736, Taxonomy and definitions for terms related to driving automation systems for on-road motor vehicles

ISO 22737, Intelligent transport systems — Low-speed automated driving (LSAD) systems for predefined routes — Performance requirements, system requirements and performance test procedures

ISO/SAE 21434, Road vehicles — Cybersecurity engineering

#### 3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO/SAE PAS 22736 (2021), ISO 22737 (2021) and the followings apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses: