



Designation: E 1685 – 00

## Standard Practice for Measuring the Change in Length of Fasteners Using the Ultrasonic Pulse-Echo Technique<sup>1</sup>

This standard is issued under the fixed designation E 1685; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon ( $\epsilon$ ) indicates an editorial change since the last revision or reapproval.

### 1. Scope

1.1 This practice covers a procedure for measuring changes in length of threaded fasteners using conventional ultrasonic pulse-echo bolt-measuring instrumentation which has been properly calibrated.

1.2 This procedure is normally intended for metal bolting 0.25 in. (6.4 mm) or more in nominal diameter with effective length-to-diameter ratios of 2:1 or greater.

1.3 *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.*

### 2. Referenced Documents

2.1 *ASTM Standards:*

E 6 Terminology Relating to Methods of Mechanical Testing<sup>2</sup>

E 1316 Terminology for Nondestructive Examinations<sup>3</sup>

E 1544 Practice for Construction of a Stepped Block and Its Use to Estimate Errors Produced by Speed-of-Sound Measurement Systems for Use on Solids<sup>2</sup>

### 3. Terminology

3.1 The definitions in this practice are in accordance with Terminology E 6 and Section I of Terminology E 1316.

3.2 *Definitions of Terms Specific to This Standard:*

3.2.1 *change in length*—physical change in length of a threaded fastener due to a change in tension within the fastener.

3.2.2 *effective length*—the length of a bolt that is responsive to stress.

3.2.2.1 *Discussion*—This quantity lies somewhere between the overall length of the bolt and the grip length. It is usually estimated as the grip length plus one half the thickness of the head and one half the thickness of the nut.

3.2.3 *longitudinal wave*—those waves in which the particle motion of the material is in the same direction as the wave propagation.

3.2.4 *pulse-echo bolt-measuring equipment*—an assembly of ultrasonic instruments designed specifically to measure changes in the lengths of bolts. See Appendix X1.

3.2.5 *reference length*—the ultrasonic time of flight in the test specimen multiplied by a reference propagation velocity.

3.2.6 *reference propagation velocity*—the velocity of propagation of the ultrasonic wavefront in a calibration test block or in the bolts whose changes of length are being measured.

3.2.7 *time of flight*—the measured time interval between the launching of an ultrasonic pulse at the start of a path of travel and the reception of the pulse at the end of the path.

### 4. Summary of Practice

4.1 This practice describes a procedure for determining the change in length of a threaded fastener due to a change in tension in the fastener. Measurements of the ultrasonic time of flight are made before and after the fastener tension is changed, and a calculation of the change in length is made from the change in the time of flight.

4.1.1 Brief bursts of ultrasound (pulses) are generated by applying high-voltage electrical signals to an electroacoustic transducer having a resonant frequency in the 5 to 10-MHz range. The pulses enter the bolt through the transducer/bolt interface, travel to the far end of the bolt, and reflect back (echo) to the transducer. The time of flight required for the signal to make its round-trip is measured electronically. By measuring the change in the time of flight due to a change in tension within the bolt, the equipment can determine the change in the length of the bolt due to the change in tension. Compensation for the direct effect of stress on the propagation velocity in the bolt is automatically done by a computer or microprocessor within the equipment.

<sup>1</sup> This practice is under the jurisdiction of ASTM Committee E28 on Mechanical Testing and is the direct responsibility of Subcommittee E28.13 on Residual Stress Measurement.

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<sup>2</sup> *Annual Book of ASTM Standards*, Vol 03.01.

<sup>3</sup> *Annual Book of ASTM Standards*, Vol 03.03.

4.2 This procedure is used on fasteners as they are tightened within their elastic limits; or on previously tightened fasteners as they are loosened. The latter can have been tightened past yield.

## 5. Significance and Use

5.1 The techniques described provide for the indirect measurement of change in length of a fastener. Such measurements are made from one end of the specimen without requiring access to the rear surface.

5.2 The equipment is field portable and should be used in the manner prescribed by the manufacturer. Common uses include monitoring changes in length of fasteners and as a tool for industrial quality control. Current applications include fasteners used in turbines, petrochemical pressure vessels, aircraft, automotive manufacturing, general bolting within the nuclear industry, structural steel connections, laboratory testing, and so forth.

## 6. Apparatus

6.1 *Pulse-Echo Instrument*—For ultrasonic measurements of the change in length of bolts, any longitudinal-wave pulse-echo ultrasonic instrument capable of reporting calculated changes in length is acceptable provided that its accuracy and precision satisfy the requirements set forth in Annex A1. The major components of suitable instruments are as follows:

6.1.1 *Pulser/transmitter*, a means of generating electrical pulses to excite an acoustic transducer.

6.1.2 *Receiver/detector*, a means of amplifying and detecting the returning back-wall echo.

6.1.3 *Time-base Controller*, a means of measuring changes in ultrasonic time of flight.

6.1.4 *Acoustic Transducer*, a means of sending and receiving ultrasonic waves. Experience has shown that transducers with resonances in the 5 to 10-MHz frequency range are usually satisfactory. In general, select an acoustic transducer having an element of the largest diameter available while not exceeding the minimum body diameter of the bolt.

### 6.2 Other Apparatus:

6.2.1 *Couplant*—For longitudinal pulse-echo measurements, a liquid is required to couple ultrasound between the transducer and the fastener. Of the couplants commonly used, where applicable a 50/50 glycerine/water mix often provides optimal results. Light oil or standard commercially available ultrasonic couplants are also satisfactory.

6.2.2 *Oscilloscope*—For optimal adjustment of the apparatus, the use of an oscilloscope is necessary. The oscilloscope must have two input channels, two traces, external triggering, and a dual time base with delayed sweep capability. Its bandwidth should be at least 35 MHz or its equivalent.

6.2.2.1 Pulse-echo instruments with built-in oscilloscope display capabilities must have sampling speeds equivalent to at least ten times the transducer frequency for satisfactory signal display.

6.2.3 *Standard Reference Blocks*, for periodic recalibration of the pulse-echo instrument.

6.2.3.1 A glass or metallic reference block of known length and appropriate surface roughness, shape, thickness, and parallelism is recommended. Acceptable standards include a glass

block, two metal bars of unequal length, and single bars of known acoustic velocity. The path length of the standard must be determined by a technique of higher accuracy. See Practice E 1544. Calibration of standards should be traceable to NIST.

## 7. Procedure

7.1 The performance of the pulse-echo instrument should be verified or adjusted to a reference standard in accordance with the manufacturer's specifications. See Annex A2.

7.1.1 In noncritical applications, where uncertainties smaller than  $\pm 15\%$  of the change in length are not required, an instrument calibrated on one bolt of a given material can be used on other bolts of the same material but having different shapes.

7.1.2 At the other extreme, if the instrument is to be used on bolts in critical, safety-related applications or where uncertainties of  $\pm 1$  to  $3\%$  are required, or both, consideration should be given to recalibration on a statistically significant sample of each new lot of bolts.

7.2 *Fastener Preparation*—For reliable ultrasonic measurements the fastener must have suitable finish and geometry requirements. One end must be accessible for transducer placement. This end must, for at least the diameter of the transducer, be flat and perpendicular to the axis of the bolt. A machined surface with a finish of 125 RMS or better is recommended, exclusive of indented grade markings. Raised grade markings must be removed. (See Note 1.) If the end is recessed it must have a flat spot face. The reflector end of the fastener must have a flat surface parallel to the other end. The amount of axial runout on the end is dependent on fastener size and the accuracy requirement. An area as small as  $\frac{1}{8}$  in. (3 mm) in diameter may be sufficient. The ends of bolts with through center holes may be prepared adjacent to the holes, with the transducer locations marked.

NOTE 1—Grade markings should not be moved indiscriminately. Documentation of grade marking removals should be created and maintained.

7.3 Measure average fastener temperature within  $1^\circ\text{C}$ , in accordance with instructions in the instrument operating manual.

### 7.4 Transducer Placement:

7.4.1 Apply a suitable acoustic couplant to allow adequate sound transmission. Glycerine or some other high-viscosity couplant is recommended if the fastener has indented grade markings or if its surface has a few pits.

NOTE 2—The coupling surface must be wiped clean each time couplant is applied. The amount of couplant to be used should be sufficient to wet the transducer face but not excessive. Consistent amounts must be used for successive or repetitive readings.

7.4.2 Place the transducer on the flat surface of the bolt to be measured. To minimize possible impact damage to the wear-plate portion of the transducer, it should be set down on its edge and then carefully rotated to a flat position. The transducer is seated by light, back-and-forth finger movements to squeeze out excess couplant and to obtain the shortest, most stable, length display, or the largest echo signal on the oscilloscope. Repeat this process several times to ensure repeatability.