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## Road vehicles — Local Interconnect Network (LIN) —

### Part 3: Protocol specification

Véhicules ~~routier~~routiers — Réseau Internet ~~Local~~local (LIN) —

Partie 3: Spécification du protocole

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## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see [www.iso.org/directives](http://www.iso.org/directives)).

ISO draws attention to the possibility that the implementation of this document may involve the use of (a) patent(s). ISO takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, ISO had ~~not~~ received notice of (a) patent(s) which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at [www.iso.org/patents](http://www.iso.org/patents). ISO shall not be held responsible for identifying any or all such patent rights.

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see [www.iso.org/iso/foreword.html](http://www.iso.org/iso/foreword.html).

This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 31, *Data communication*.

This second edition cancels and replaces the first edition (ISO 17987-3:2016), which has been technically revised.

The main changes are as follows:

- ~~—~~ master and slave terms used for the LIN node types in ISO 17987:2016 (all parts) are replaced within this document with inclusive language terms commander and responder. This also applies for abbreviations and file formats NCF and LDF;
- ~~—~~ auto addressing added;
- ~~—~~ editorial updates.

A list of all parts in the ISO 17987 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at [www.iso.org/members.html](http://www.iso.org/members.html).

## Introduction

The LIN protocol as proposed is an automotive focused low speed UART-based network (Universal Asynchronous Receiver Transmitter). Some of the key characteristics of the LIN protocol are signal-based communication, schedule table-based frame transfer, commander/responder communication with error detection, node configuration and diagnostic service communication.

The LIN protocol is for low-cost automotive control applications as, for example, door module and air conditioning systems (see also history described in Annex BAnnex B). It serves as a communication infrastructure for low-speed control applications in vehicles by providing the following:

- ~~—~~signal-based communication to exchange information between applications in different nodes;
- ~~—~~bit rate support from 1 kbit/s to 20 kbit/s;
- ~~—~~deterministic schedule table-based frame communication;
- ~~—~~network management that wakes up and puts the LIN cluster into sleep mode in a controlled manner;
- ~~—~~status management that provides error handling and error signalling;
- ~~—~~transport layer that allows large amount of data to be transmitted (such as diagnostic services);
- ~~—~~specification of how to handle diagnostic services;
- ~~—~~electrical physical layer specifications;
- ~~—~~node description language describing properties of responder nodes;
- ~~—~~network description file describing behaviour of communication;
- ~~—~~application ~~programmer's~~programming interface.

The ISO 17987 series is based on the open systems interconnection (OSI) basic reference model as specified in ISO/IEC 7498-1 which structures communication systems into seven layers.

The OSI model structures data communication into seven layers called (top down) application layer (layer 7), presentation layer, session layer, transport layer, network layer, data link layer and physical layer (layer 1). A subset of these layers is used in the ISO 17987 series.

The ISO 17987 series distinguish between the services provided by a layer to the layer above it and the protocol used by the layer to send a message between the peer entities of that layer. The reason for this distinction is to make the services, especially the application layer services and the transport layer services, reusable also for other types of networks than LIN. In this way, the protocol is hidden from the service user and it is possible to change the protocol if special system requirements demand it.

The ISO 17987 series provides all documents and references required to support the implementation of the requirements related to.

- ~~—~~ISO 17987-1: provides an overview of the ISO 17987 series and structure along with the use case definitions and a common set of resources (definitions, references) for use by all subsequent parts.
- ~~—~~ISO 17987-2: specifies the requirements related to the transport protocol and the network layer requirements to transport the PDU of a message between LIN nodes.

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- ISO 17987-3 (this document): specifies the requirements for implementations of the LIN protocol on the logical level of abstraction. Hardware related properties are hidden in the defined constraints.
- ISO 17987-4: specifies the requirements for implementations of active hardware components which are necessary to interconnect the protocol implementation.
- ISO/TR 17987-5: specifies the LIN API (Application ProgrammersProgramming Interface) and the node configuration and identification services. The node configuration and identification services are specified in the API and define how a responder node is configured and how a responder node uses the identification service.
- ISO 17987-6: specifies tests to check the conformance of the LIN protocol implementation according to ISO 17987-2 and ISO 17987-3. This comprises tests for the data link layer, the network layer and the transport layer.
- ISO 17987-7: specifies tests to check the conformance of the LIN electrical physical layer implementation (logical level of abstraction) according to ISO 17987-4.

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# Road vehicles — Local Interconnect Network (LIN) —

## Part 3: Protocol specification

### 1 Scope

This document specifies the LIN protocol including the signal management, frame transfer, schedule table handling, task behaviour, status management, and commander and responder node. It contains also OSI layer 5 properties according to ISO 14229-7 UDSONLIN-based node configuration and identification services (SID: B0<sub>16</sub> to B8<sub>16</sub>) belonging to the core protocol specification.

A node (normally a commander node) that is connected to more than one LIN network is handled by higher layers (i.e. the application) not within the scope of this document.

### 2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 17987-1, *Road vehicles — Local Interconnect Network (LIN) — Part 1: General information and use case definition*

ISO 17987-2:—<sup>1)</sup>, *Road vehicles — Local Interconnect Network (LIN) — Part 2: Transport protocol and network layer services*

ISO/PRF 17987-3  
ISO 17987-4:—<sup>2)</sup>, *Road vehicles — Local Interconnect Network (LIN) — Part 4: Electrical Physical Layer physical layer (EPL) specification 12 V/24 V*

### 3 Terms, definitions, symbols and abbreviated terms

#### 3.1 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 17987-1 and the following apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

<sup>1)</sup>

<sup>1)</sup> Under preparation. Stage at the time of publication: ISO/FDIS 17987-2:2025.

<sup>2)</sup> Under preparation. Stage at the time of publication: ISO/FDIS 17987-4:2025.