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**Rubber — Determination of viscosity  
and stress relaxation using a rotorless  
sealed shear rheometer**

*Caoutchouc — Détermination de la viscosité et de la relaxation  
de contrainte au moyen d'un rhéomètre à cisaillement sans rotor  
étanche*

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## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO document should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see [www.iso.org/directives](http://www.iso.org/directives)).

ISO draws attention to the possibility that the implementation of this document may involve the use of (a) patent(s). ISO takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, ISO had not received notice of (a) patent(s) which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at [www.iso.org/patents](http://www.iso.org/patents). ISO shall not be held responsible for identifying any or all such patent rights.

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For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see [www.iso.org/iso/foreword.html](http://www.iso.org/iso/foreword.html).

This document was prepared by Technical Committee ISO/TC 45, *Rubber and rubber products*, Subcommittee SC 2, *Testing and analysis*.

This second edition cancels and replaces the first edition (ISO 13145:2012), of which it constitutes a minor revision. The changes are as follows:

- the reference ISO 18899 has been updated with the latest edition.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at [www.iso.org/members.html](http://www.iso.org/members.html).

## Introduction

The rheological properties of rubbers are related to their structural characteristics and will influence the behaviour of the rubber during processing and the performance of the final product.

For these reasons, the industrial environment requires instruments that can quickly and easily evaluate the rheological properties.

As a consequence, this standard test method was formulated using a rotorless sealed shear rheometer for rheological evaluation under defined conditions.

This test can be an alternative to the Mooney viscometer, still used as standard in many parts of the rubber industry to measure Mooney viscosity (according to ISO 289-1). The defined conditions have been selected to provide a shear rate range similar to that used for Mooney viscosity and a good repeatability level.

This test procedure is performed over a short time and preferably in the automatic mode to optimize test efficiency.

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# Rubber — Determination of viscosity and stress relaxation using a rotorless sealed shear rheometer

**WARNING** — Persons using this document should be familiar with normal laboratory practice. This document does not purport to address all of the safety problems, if any, associated with its use. It is the responsibility of the user to establish appropriate safety and health practices and to ensure compliance with any national regulatory conditions.

## 1 Scope

This document describes a method for the determination of the viscosity and stress relaxation of raw or compounded rubber under specified conditions.

The viscosity determination consists of a constant strain, temperature and frequency test in which the elastic and the loss components of the complex shear modulus can be determined.

The determination of stress relaxation consists of a constant static strain and temperature test in which the torque decrease can be determined.

## 2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 1382, *Rubber — Vocabulary*

ISO 13145:2023

<https://standards.iteh.ai/catalog/standards/sist/eb20df59-0e9f-423d-abbc-f4ae80cdab66/iso-18899-2013>, *Rubber — Guide to the calibration of test equipment*

## 3 Terms and definitions

For the purpose of this document, the terms and definitions given in ISO 1382 and the following apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

— ISO Online browsing platform: available at <https://www.iso.org/obp>

— IEC Electropedia: available at <https://www.electropedia.org/>

### 3.1

#### rotorless sealed shear rheometer

device consisting of two dies forming a temperature-controlled cavity, one of which is moved relative to the other to apply a stress or strain to the test piece

### 3.2

#### sinusoidal strain

$\gamma(t)$

strain produced by the oscillation of the die constituting the test cavity

Note 1 to entry: It is given by the expression  $\gamma(t) = \gamma_0 \sin(\omega t)$ , where  $\gamma_0$  is the maximum amplitude of the applied strain.

**3.3**  
**loss angle**  
 $\delta$

phase angle between the stress and the strain

Note 1 to entry: This is a measure of the presence and extent of viscous behaviour in a material. For viscoelastic materials, the phase angle can assume a value between  $0^\circ$  and  $90^\circ$ .  $90^\circ$  is an ideal Newtonian liquid.

**3.4**  
**complex torque**  
 $S^*$

torque measured by the machine due to application of sinusoidal strain

Note 1 to entry: The complex torque is a vector which can be represented by a complex number, viz  $S^* = S' + iS''$ .

**3.5**  
**elastic torque**  
 $S'$

component of torque that is in phase with the imposed sinusoidal strain

Note 1 to entry: It is given by the equation  $S' = |S^*|\cos\delta$ .

**3.6**  
**loss torque**  
 $S''$

component of torque that is in quadrature with the imposed sinusoidal strain

Note 1 to entry: It is given by the equation  $S'' = |S^*|\sin\delta$ .

**3.7**  
**complex shear modulus**  
 $G^*$

ratio of the shear stress to the shear strain, where each is a vector which can be represented by a complex number

Note 1 to entry: It is given by the equation  $G^* = G' + iG''$ .

Note 2 to entry: The complex shear modulus is determined by dividing the complex torque  $S^*$  by the applied strain and multiplying by a geometric factor related to the cavity shape.

**3.8**  
**elastic shear modulus**  
 $G'$

component of the applied shear stress that is in phase with the shear strain, divided by the strain

Note 1 to entry: It is given by the equation  $G' = |G^*|\cos\delta$ .

**3.9**  
**loss shear modulus**  
 $G''$

component of the applied shear stress which is in quadrature with the shear strain, divided by the strain

Note 1 to entry: It is given by the equation  $G'' = |G^*|\sin\delta$ .

**3.10**  
**tangent of the loss angle**  
 $\tan\delta$

ratio of the loss modulus to the elastic modulus



## 4 Principle

The torque generated in a test piece contained in a heated sealed cavity formed by two dies, one of which can be oscillated through a small amplitude, is measured.

## 5 Apparatus

### 5.1 General

A rotorless sealed shear rheometer consists of two dies that are heated and closed, under a specified force, to form a sealed test cavity that contains the test piece. One of the dies oscillates, and a measuring system records the torque required to produce the relative movement. The elastic torque  $S'$  and the loss torque  $S''$  produced in a test piece by the strain due to the oscillation of the die can be measured at specified conditions of temperature, frequency and amplitude.

The general arrangement of a rotorless sealed shear rheometer is shown in [Figure 1](#), including typical machine dimensions.

### 5.2 Die cavity

The dies shall be manufactured from a stiff material. The surface of the dies shall be treated to minimize the effect of test piece contamination if protective or carrying film are not used and shall be hard enough to prevent wear. A minimum Rockwell hardness of 50 HRC, or equivalent, is recommended. The tolerances necessary on the dimensions of the dies depend on the particular design, but as a general guide the dimensions of the cavity should be controlled to  $\pm 0,2\%$ .

The top and bottom surfaces of the cavity shall have a pattern of grooves of dimensions sufficient to prevent slippage of the rubber test piece.

Holes shall be provided in both the upper and lower dies to accommodate temperature sensors. The positions of the sensors relative to the cavity shall be controlled to ensure a reproducible response.

A seal of suitable low, constant friction shall be provided to prevent material leaking from the cavity.

Suitable means shall be employed, by design of the dies or otherwise, to apply pressure to the test piece throughout the test to minimize slippage between the disc and the rubber.

### 5.3 Die closure

The dies shall be closed and held closed during the test by, for example, a pneumatic cylinder.

The closing force required depends on the clearance area; as a general guide, a minimum of 7 kN is recommended. The contact of the die cavity edges shall be such as to form a perfectly sealed cavity.

### 5.4 Movement

The moving part in a rotorless instrument is one of the dies. The dies are usually biconical to produce a substantially uniform shear rate, and this shape is useful to make the test piece loading and unloading stages easier. The drive linkage shall be sufficiently stiff to prevent significant deformation.

A torsional oscillating movement shall be applied to one of the dies (typically the lower in the cavity) by means of a motor.

The frequency of oscillation can be varied according to the instrument specification, but in this International Standard a single frequency is selected.

The oscillation amplitude  $\theta$  may be varied according to the deformation required. The maximum amplitude of the applied strain  $y_0$  is calculated considering the oscillation angle used in the test and the die geometry (conical). It is given by the expression

$$y_0 = \theta/\varphi$$

where  $\varphi$  is the characteristic angle of the conical die.

Generally, greater sensitivity can be obtained with larger amplitudes, but the amplitude that can be used in practice is restricted by the possibility of slippage between the test piece and the die surface.

### 5.5 Heating and temperature control

The heating and temperature control system shall be capable of producing a reproducible and evenly distributed temperature in the dies and shall permit fast and reproducible temperature recovery after insertion of the test piece.

The temperature-measuring system shall enable the temperature to be measured to a resolution of  $\pm 0,1$  °C over the range from 60 °C to 200 °C. The temperature controllers shall enable the temperature of the dies to be controlled to an accuracy of  $\pm 0,3$  °C in the steady state.

### 5.6 Torque-measuring system

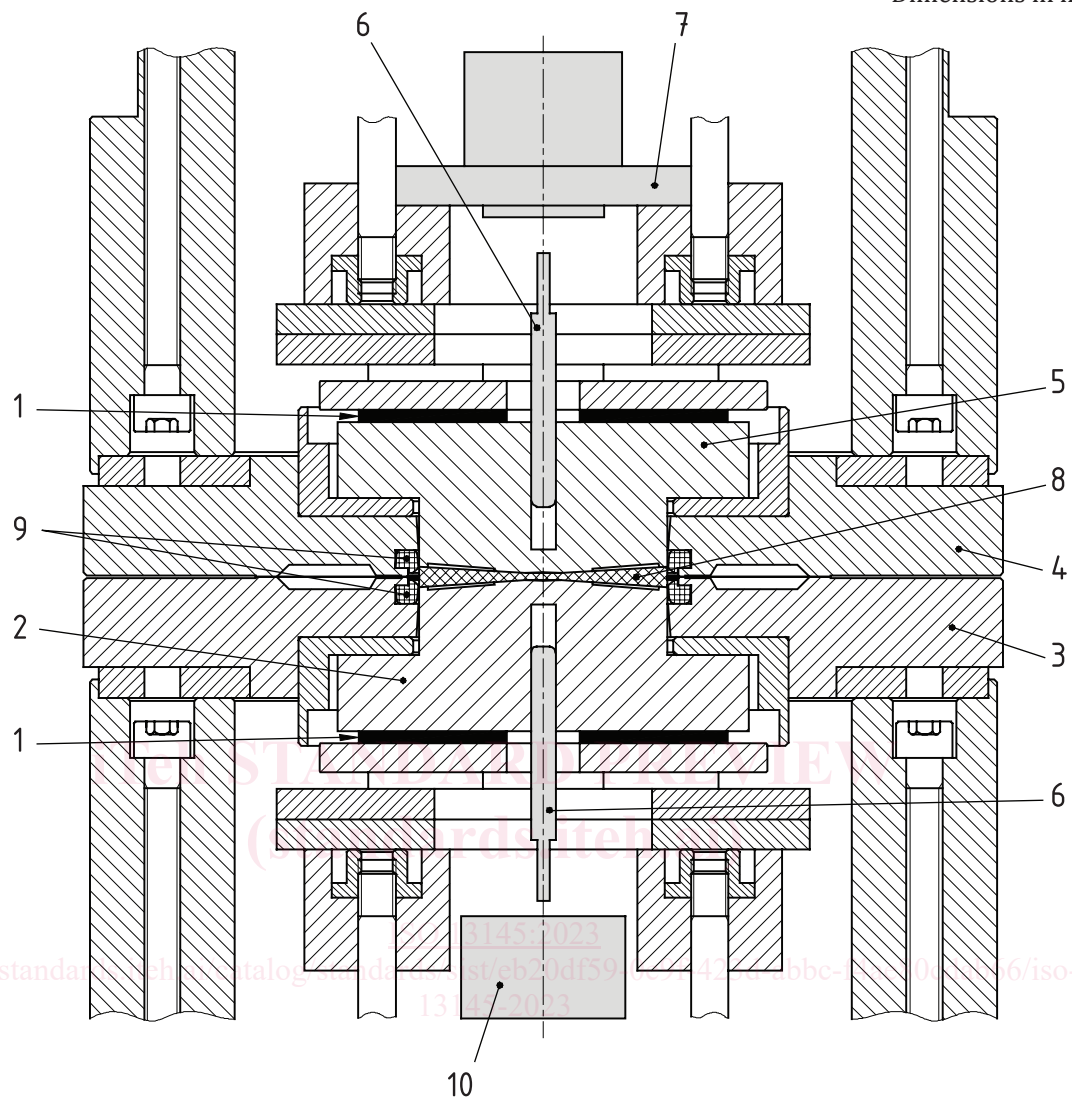
A suitable transducer shall be provided which is capable of measuring the force or torque with an accuracy of  $\pm 1$  %.

A recorder shall be provided to continuously monitor force or torque. It shall have a response time for full-scale deflection equal to or below 1 s.

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Dimensions in millimetres



a) Measurement principle