



Technical Specification

ISO/TS 15638-26

Intelligent transport systems — Framework for cooperative telematics applications for regulated vehicles (TARV) —

Part 26: Electric vehicle dynamic charging monitoring

*Systèmes intelligents de transport — Cadre pour applications
télématiques collaboratives pour véhicules réglementés
(TARV) —*

*Partie 26: Surveillance de la charge dynamique des véhicules
électriques*

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO document should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

ISO draws attention to the possibility that the implementation of this document may involve the use of (a) patent(s). ISO takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, ISO had not received notice of (a) patent(s) which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at www.iso.org/patents. ISO shall not be held responsible for identifying any or all such patent rights.

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 204, *Intelligent transport systems*.

A list of all parts in the ISO 15638 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

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Introduction

Given the increasing needs related to battery-powered heavy vehicle dynamic charging system developments, the monitoring of powered heavy electric vehicle charging status while on the road should be made available to charging network service providers by using the framework of the ISO 15638 series (TARV) to realize efficient charging services from the fleet energy management viewpoint.

Battery powered heavy electric vehicles generate and feed back power to the charging network when decreasing in speed by using a regeneration braking system (when the battery is fully charged, this energy is transferred to the grid). Such information also needs to be fed back to the charging network service provider for monitoring status for the purpose of fleet energy management.

This document standardizes the conceptual operational framework of the information-collecting service provided by service providers. The ISO 15638 series of TARV application standards are based on a triumvirate of vehicle operators with in-vehicle systems, on-board application service providers and road authority. A new means of energy consumption management and enforcement can be enabled by using this document where authorities require such regulated monitoring for decarbonizing purposes in the transport sector.

Telematic applications need to be able to be integrated into the embedded computing systems available on the market. The need for interoperability of different solutions is also important as several actors with different solutions can be involved in information needs. Securing the data exchanged is also a particularly important point.

This document is intended for unregulated services, but if needed, road authorities or other users can also use this document for the deployment of regulated services.

This document is intended for public road transport, but if needed, private road/property application can be made possible by using this document.

NOTE Regarding European Commission (EC) regulations, ISO 15638-9 already covers provisions consistent with EC 165/2014. This document is complementary to ISO 15638-9, and is therefore consistent with EC 165/2014.

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Intelligent transport systems — Framework for cooperative telematics applications for regulated vehicles (TARV) —

Part 26: Electric vehicle dynamic charging monitoring

1 Scope

This document provides a freight vehicle dynamic charging information collecting service function or application for non-enforcement applications and for regulated application services (RAS). It is intended for the road transport decarbonizing management purposes of regulated commercial freight vehicle movements using battery-powered heavy electric vehicles. This document also specifies the framework for remote energy consumption information collecting for non-enforcement and the conceptual operation of other management purpose applications.

This document is intended to reinforce vehicle energy efficiency for non-enforcement and other purposes by collecting dynamic charging information of battery powered heavy electric vehicles. Collected information can be used for fee collection and energy management purposes, which are outside the scope of this document.

This document is applicable to dynamic charging applications. It is not applicable to information exchange purposes such as charging right and payment authorization.

Static charging information exchange application is standardized by other ISO Technical Committees, such as ISO TC 22, *Road vehicles*, Subcommittee SC 31, *Data communication*. It is not applicable to this document.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 14816:2005, *Road transport and traffic telematics — Automatic vehicle and equipment identification — Numbering and data structure*

ISO 15638-3, *Intelligent transport systems — Framework for collaborative telematics applications for regulated commercial freight vehicles (TARV) — Part 3: Operating requirements, 'Approval Authority' procedures, and enforcement provisions for the providers of regulated services*

ISO/TS 15638-4, *Intelligent transport systems — Framework for cooperative telematics applications for regulated commercial freight vehicles (TARV) — Part 4: System security requirements*

ISO 15638-5, *Intelligent transport systems — Framework for collaborative Telematics Applications for Regulated commercial freight Vehicles (TARV) — Part 5: Generic vehicle information*

ISO 15638-7:2013, *Intelligent transport systems — Framework for collaborative Telematics Applications for Regulated commercial freight Vehicles (TARV) — Part 7: Other applications*

ISO 15638-21, *Intelligent transport systems — Framework for cooperative telematics applications for regulated commercial freight vehicles (TARV) — Part 21: Monitoring of regulated vehicles using roadside sensors and data collected from the vehicle for enforcement and other purposes*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 15638-21 apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

4 Symbols and abbreviated terms

ASD file	application service data file
ASP	application service provider
CALM	communications access for land mobiles
C-ITS	cooperative intelligent transport system
CONOPS	concept of operations
DRD	driver recording device
GNSS	global navigation satellite system
HMC	host management centre
ID	Identity
ITS	intelligent transport system
ITS-S	ITS station
IVS	in-vehicle system
LDM	local dynamic map
LDT	local data tree
QoS	quality of service
RAS	regulated application service
RFID	radio frequency identification
ROAM	regime for open application management
TARV	telematics applications for regulated vehicles

5 General overview and framework

The ISO 15638 series addresses and defines the framework for a range of cooperative telematics applications for regulated vehicles (such as electronic tachograph monitoring, driver work records, emergency messaging/eCall, mass monitoring, 'Mass' information for jurisdictional control and enforcement, speed monitoring, access control, access methods, location monitoring, weigh in motion, freight vehicle stability monitoring, tyre monitoring, overhead clearance etc.). The overall scope includes the concept of operation, legal and regulatory issues, and the generic cooperative ITS service platform. The framework is based on a (multiple) service provider-oriented approach, including provisions for the certification and auditing of service providers.

This document utilizes the framework and architecture for freight vehicle stability monitoring defined in 15638-21. The general conceptual operation description of the roles of the actors in "extended" TARV architecture is also defined in ISO 15638-21.

NOTE The framework defined before the publication of ISO 15638-21 did not include "roadside sensors/VMS/info". The framework is "extended" by ISO 15638-21 to include them.

As a summary, [Figure 1](#) shows the "extended" role model conceptual architecture showing the key actors and their relationships as defined in ISO 15638-21.

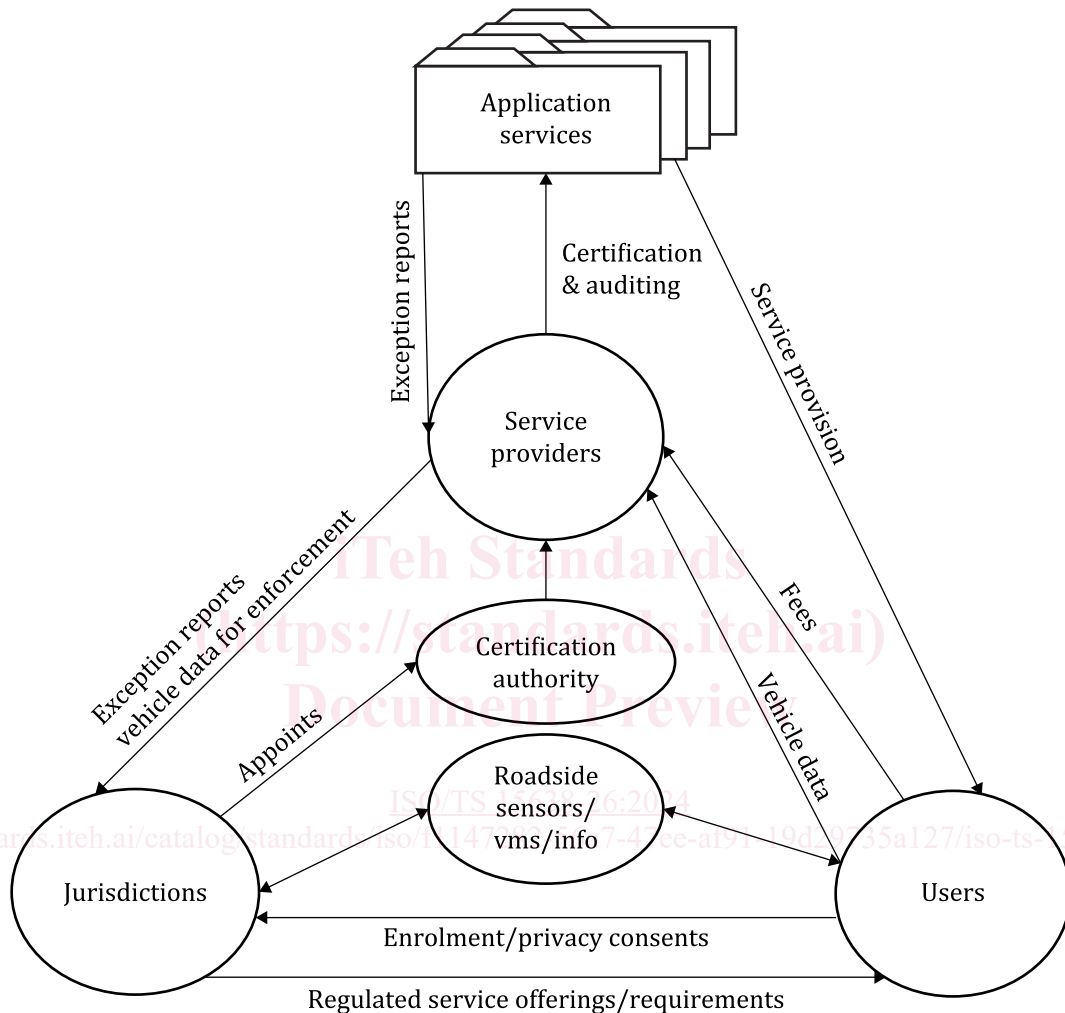


Figure 1 — Extended role model conceptual architecture

This document is intended for an unregulated service provision application for efficient road transport by freight vehicles, achieved through the collection, from the vehicle, of battery-powered electric vehicle energy consumption information. This can include data collection on the dynamic charging and feed back of energy to/from grid provision, for example. [Figure 2](#) shows the architecture from the viewpoint of the provision of an unregulated (commercial) application service, using the common "extended" TARV platform defined in ISO 15638-21.

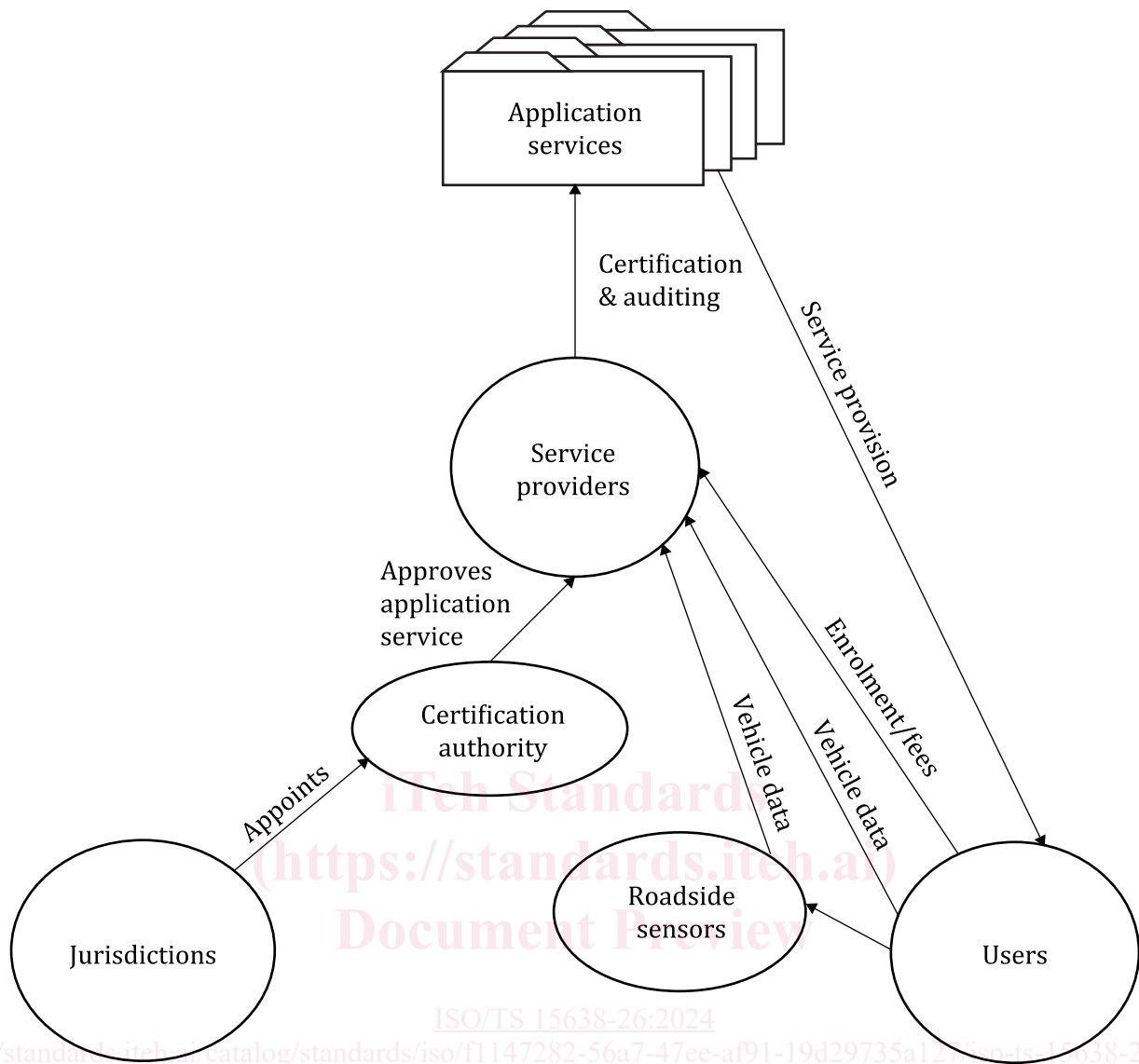


Figure 2 — Role model conceptual architecture for unregulated service provisioning

Freight vehicles are heavy; battery-powered electric vehicles often carry full load cargo in addition to the heavy battery required to cover the necessary driving range between charging. Such vehicle design is not practical. Deploying a dynamic charging system is therefore becoming a practical solution. In such a solution, an energy-providing service provider provides physical dynamic charging facilities and a battery-powered heavy electric vehicle is equipped with energy-receiving devices (contact and/or non-contact type). A fee-collecting service provider collects fees from the user through a service provider collecting dynamic charging data. Information gathering is achieved by using the ISO 15638-21 TARV architecture as shown in [Figure 2](#).

This document enables such data collection in order to achieve efficient freight vehicle road transport realization and efficient freight fleet transport operation of user vehicles, whilst avoiding the generation of carbon or serious global warming incidents on the roadways.

The freight vehicle information (such as dynamic charging status with location) can be obtained from various sources, such as roadside-embedded sensors or freight vehicle on-board equipped sensors. The sensor information is sent to the service provider to realize real-time remote monitoring of freight vehicle status and the service provider provides the efficient road transport status information of that vehicle. By providing the freight vehicle location (GNSS) data to the service provider, the service provider can collect accurate dynamic charging information for that part of the road and for that vehicle (model).

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The service provider provides this application service to/for a user who is an individual or party that enrolls in and operates within an unregulated application service or commercial application service to meet specific aspects of the requirements of a service provider for the operation of the regulated vehicle.

Examples of users are a transport operator, driver, freight owner, etc. Most commonly, the user is the transport operator.

For basic TARV information, refer to ISO 15638-1.

This document defines the basic conceptual operational requirements for this application service.

It is important to note that where a commercial (unregulated) service can be instantiated using only the generic vehicle data specified in ISO 15638-5, no further standardization is required. Where a TARV commercial application is simply instantiated as a commercial application conforming to the requirements of this document, no further standardization is required, so long as conformance to the requirements of this document can be demonstrated.

Service offerings may vary from service provider to service provider. The service provider provides the application service to/for a "user" who is an individual or party that enrolls and contracts to receive the commercial/civic application service.

6 Basic conceptual operational requirement

6.1 General

The basic conceptual framework is shown in [Figure 3](#).

The telematic application generates adequate dynamic charging information for the energy service provider to be able to collect the suitable service fee from users of a dynamic charging system built on the road. This information depends on the physical characteristics of the road and the vehicle weight, including freight goods.

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