

Synchronous belt drives —

Transmissions synchrones par courroies — Vocabulaire

Vocabulary

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Contents

Forew	ord			iv
1	Scope			
2	Normative references			1
3	Terms and definitions			
	3.1	General		
	3.2	Synchronous belts		2
		3.2.1	General	
		3.2.2	Tooth profile Type of belt drive Structure	4
		3.2.3	Type of belt drive	5
		3.2.4	Structure	5
			Teeth	
	3.3	Pulleys		9
		3.3.1	General	9
		3.3.2	Grooves	
		3.3.3	Groove-generating tools	17
4	Symbols			
Alphabetical index				

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Foreword

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This document was prepared by Technical Committee ISO/TC 41, *Pulleys and belts (including veebelts)*, Subcommittee SC 4, *Synchronous belt drives*.

This fourth edition cancels and replaces the third edition (ISO 5288:2017), of which it constitutes a minor revision. The change is as follows: ISO/FDIS 5288

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Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at <u>www.iso.org/members.html</u>.

Synchronous belt drives — Vocabulary

1 Scope

This document specifies the terms and definitions related to the use of synchronous belt drives for mechanical power transmission and where positive indexing or synchronization is required.

2 Normative references

There are no normative references in this document.

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at https://www.iso.org/obp
- IEC Electropedia: available at https://www.electropedia.org/

3.1 General

3.1.1

synchronous belt drive

system composed of a synchronous belt (3.2.1.1) and at least one synchronous pulley (3.3.1.1)

Note 1 to entry: Synchronized motion and/or power is transmitted through the engagement of teeth on the belt with *grooves* (3.3.2.1) on the pulleys. alog/standards/iso/dbb1d17e-3377-4ac8-bf16-8a619a279a76/iso-fdis-5288

Note 2 to entry: This belt drive has been known in the past by various names such as "timing belt drive", "positive belt drive" or "gear belt drive".

3.1.2 centre distance

С

shortest distance between the axes of two *synchronous pulleys* (3.3.1.1) when the belt is under the prescribed measuring force

Note 1 to entry: See Figure 1.

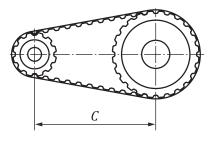


Figure 1

3.1.3 endless synchronous belt drive

synchronous belt drive (3.1.1) with applied endless synchronous belt

Note 1 to entry: See Figure 2.

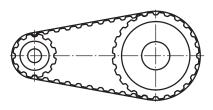


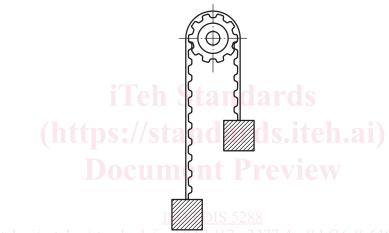
Figure 2

3.1.4

open synchronous belt drive

synchronous belt drive (3.1.1) with applied open synchronous belt

Note 1 to entry: See Figure 3.



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Figure 3

3.2 Synchronous belts

3.2.1 General

3.2.1.1

synchronous belt

belt with transverse teeth of rectangular or curvilinear cross-section extending from the base at regularly spaced intervals

Note 1 to entry: Consult synchronous belt dimensional standards for the full details of belt profiles.

3.2.1.2 tooth pitch

$P_{\rm b}$

linear distance between the axes of two consecutive teeth in a section of belt loaded to the prescribed measuring force

Note 1 to entry: See <u>Figure 4</u>.

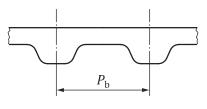


Figure 4

3.2.1.3 pitch line circumferential line in the belt which keeps the same length when the belt is bent perpendicularly to its base

Note 1 to entry: See Figure 5.

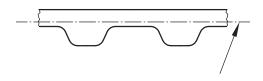
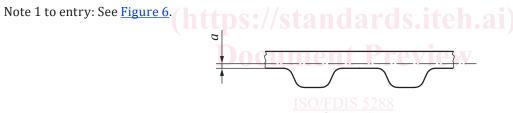


Figure 5

3.2.1.4 pitch line differential

a <belts> radial distance between the *pitch line* (3.2.1.3) and the *root line* (3.2.5.3)



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3.2.1.5 belt pitch length L_p length of the *pitch line* (3.2.1.3) of a belt

3.2.1.6 width b_s transverse dimension of the back of the belt

Note 1 to entry: See Figure 7.

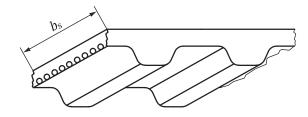
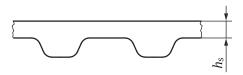
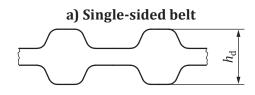


Figure 7

3.2.1.7 height $h_{\rm s}/h_{\rm d}$ total height of a single-sided or double-sided belt

Note 1 to entry: See Figure 8.

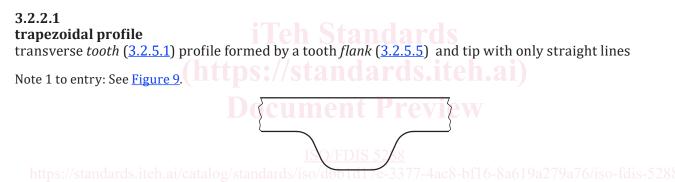




b) Double-sided belt



3.2.2 Tooth profile





3.2.2.2 curvilinear profile

transverse *tooth* (3.2.5.1) profile formed by a tooth *flank* (3.2.5.5) or tip that contains curved lines

Note 1 to entry: See <u>Figure 10</u>.

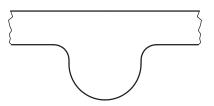


Figure 10

3.2.3 Type of belt drive

3.2.3.1 endless synchronous belt closed synchronous belt (<u>3.2.1.1</u>)

Note 1 to entry: See Figure 11.

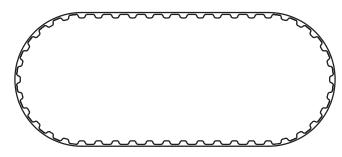
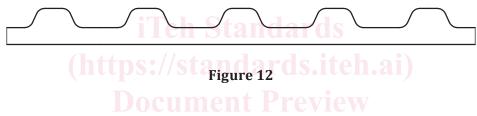


Figure 11

3.2.3.2 open synchronous belt *synchronous belt* (3.2.1.1) with two ends

Note 1 to entry: See Figure 12.



3.2.4 Structure

3.2.4.1

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single-sided synchronous belt g/standards/iso/dbb1d17e-3377-4ac8-bf16-8a619a279a76/iso-fdis-5288 *synchronous belt* (3.2.1.1) with teeth located inside of the *pitch line* (3.2.1.3) at regularly spaced intervals

Note 1 to entry: See Figure 13.

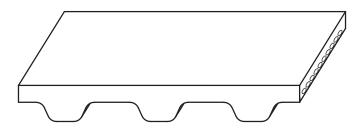
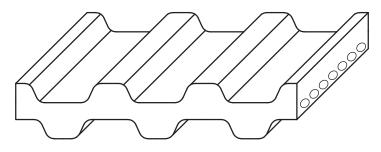


Figure 13

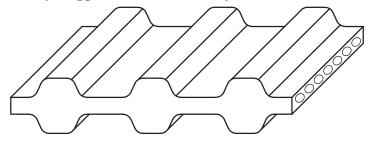
3.2.4.2 double-sided synchronous belt

synchronous belt (3.2.1.1) with teeth located on both sides of the pitch line (3.2.1.3) at regularly spaced intervals

Note 1 to entry: See Figure 14.



a) Staggered double-sided synchronous belt



b) Symmetrical double-sided synchronous belt

Figure 14

3.2.5 Teeth

iTeh Standards

3.2.5.1 tooth

tooth generally transverse element protruding from the root of the belt which have the profile necessary to mesh with the *grooves* (3.3.2.1) in a *synchronous pulley* (3.3.1.1)

Note 1 to entry: See Figure 15.

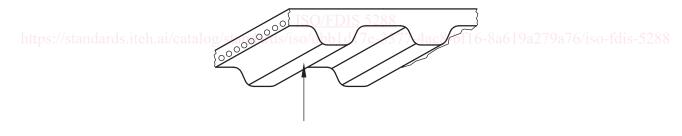


Figure 15

3.2.5.2 tip line line joining the tips of the belt teeth

Note 1 to entry: See Figure 16.

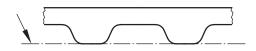


Figure 16

3.2.5.3 root line line joining the roots between the belt teeth

Note 1 to entry: See Figure 17.

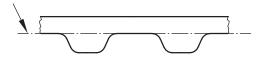


Figure 17

3.2.5.4 tooth height

 h_t distance between the *tip line* (3.2.5.2) and the *root line* (3.2.5.3)

Note 1 to entry: See Figure 18.



Figure 18 Teh Standards

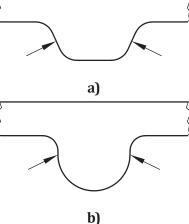
3.2.5.5 flank

area defined by the *width* (3.2.1.6) of the belt *tooth* (3.2.5.1) and the portion of the tooth section contained between the tooth tip radius and the tooth root radius or, if there is no tooth tip radius, contained between the *tip line* (3.2.5.2) and the tooth root radius

Note 1 to entry: See Figure 19.

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...,

Figure 19

3.2.5.6 working flank

<teeth> *flank* (3.2.5.5) of a belt *tooth* (3.2.5.1) in contact with the pulley groove flank when it is transmitting power

Note 1 to entry: See Figure 20.