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Standard Practice for Determining Data Criteria and Processing for Liquid Drop Size Analysis1

This standard is issued under the fixed designation E799; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ε) indicates an editorial change since the last revision or reapproval.

1. Scope

1.1 This practice gives procedures for determining appropriate sample size, size class widths, characteristic drop sizes, and dispersion measure of drop size distribution. The accuracy of and correction procedures for measurements of drops using particular equipment are not part of this practice. Attention is drawn to the types of sampling (spatial, flux-sensitive, or neither) with a note on conversion required (methods not specified). The data are assumed to be counts by drop size. The drop size is assumed to be the diameter of a sphere of equivalent volume.

1.2 The values stated in SI units are to be regarded as standard. No other units of measurement are included in this standard.

1.3 The analysis applies to all liquid drop distributions except where specific restrictions are stated.

1.4 *This international standard was developed in accordance with internationally recognized principles on standard-* intervals of time. Example in the Decision on Principles for the collection for a per *ization established in the Decision on Principles for the Development of International Standards, Guides and Recommendations issued by the World Trade Organization Technical Barriers to Trade (TBT) Committee.*

2. Referenced Documents

2.1 *ASTM Standards:*²

E1296 [Terminology for Liquid Particle Statistics](https://doi.org/10.1520/E1296) (Withdrawn 1997 ³

2.2 *ISO Standards:*⁴ 13320–1 Particle Size Analysis-Laser Diffraction Methods

9276–1 Representation of Results of Particle Size Analysis-Graphical Representation

9272–2 Calculation of Average Particle Sizes/Diameters and Moments from Particle Size Distribution

3. Terminology

3.1 *Definitions of Terms Specific to This Standard:*

3.1.1 *spatial, adj—*describes the observation or measurement of drops contained in a volume of space during such short intervals of time that the contents of the volume observed do not change during any single observation. Examples of spatial sampling are single flash photography or laser holography. Any sum of such photographs would also constitute spatial sampling. A spatial set of data is proportional to concentration: number per unit volume.

3.1.2 *flux-sensitive, adj—*describes the observation of measurement of the traffic of drops through a fixed area during
and was developed in accorintervals of time. Examples of flux-sensitive sampling are the collection for a period of time on a stationary slide or in a sampling cell, or the measurement of drops passing through a plane (gate) with a shadowing on photodiodes or by using ASTM E799-03 capacitance changes. An example that may be characterized as https://standards.iteh.ai/catalog/standards/sist/f46f7c93-edc**neither_flux-sensitive nor spatial is a collection on a slide** moving so that there is measurable settling of drops on the slide in addition to the collection by the motion of the slide through the swept volume. Optical scattering devices sensing continuously may be difficult to identify as flux-sensitive, spatial, or neither due to instantaneous sampling of the sensors and the measurable accumulation and relaxation time of the sensors. For widely spaced particles sampling may resemble temporal and for closely spaced particles it may resemble spatial. A flux-sensitive set of data is proportional to flux density: number per (unit area \times unit time).

> 3.1.3 *representative, adj—*indicates that sufficient data have been obtained to make the effect of random fluctuations acceptably small. For temporal observations this requires sufficient time duration or sufficient total of time durations. For spatial observations this requires a sufficient number of observations. A spatial sample of one flash photograph is usually not representative since the drop population distribution fluctuates with time. 1000 such photographs exhibiting no correlation with the fluctuations would most probably be representative. A temporal sample observed over a total of periods of time that

¹ This practice is under the jurisdiction of ASTM Committee [E29](http://www.astm.org/COMMIT/COMMITTEE/E29.htm) on Particle and Spray Characterization and is the direct responsibility of Subcommittee [E29.02](http://www.astm.org/COMMIT/SUBCOMMIT/E2902.htm) on Non-Sieving Methods.

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² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

³ The last approved version of this historical standard is referenced on www.astm.org.

⁴ Available from American National Standards Institute (ANSI), 25 W. 43rd St., 4th Floor, New York, NY 10036, http://www.ansi.org.

is long compared to the time lapse between extreme fluctuations would most probably be representative.

3.1.4 *local, adj—*indicates observations of a very small part (volume or area) of a larger region of concern.

3.2 *Symbols—Representative Diameters:*

3.2.1 (\overline{D}_{pq}) is defined to be such that:⁵

$$
\bar{D}_{pq}^{(p-q)} = \frac{\sum_{i} D_{i}^{p}}{\sum_{i} D_{i}^{q}}
$$
\n(1)

where:

 \overline{D} = the overbar in \overline{D} designates an averaging process, $(p - q) p > q$ = the algebraic power of \overline{D}_{pq} ,
p and *q* = the integers 1, 2, 3 or 4, $=$ the integers 1, 2, 3 or 4, D_i = the diameter of the ith drop, and
 \sum_i = the summation of D_i^p or D_i^q , re \sum_i = the summation of *D*_i^{*p*} or *D*_i^{*q*}, representing all drops in the sample. $0 = p$ and $q =$ values 0, 1, 2, 3, or 4.

 $\sum_i D_i^0$ is the total number of drops in the sample, and some of the more common representative diameters are:

- \overline{D}_{10} = linear (arithmetic) mean diameter,
- \bar{D}_{20} = surface area mean diameter,

 \bar{D}_{30} = volume mean diameter,

- \overline{D}_{32} = volume/surface mean diameter (Sauter), and
- D_{32} = volume/surface mean diameter (Sauter), and D_{RR} = Rosin
 \bar{D}_{43} = mean diameter over volume (De Broukere or Herdan).

See Table 1 for numerical examples.

3.2.2 D_{Nf} , D_{Lf} , D_{Af} , and D_{Vf} are diameters such that the fraction, *f*, of the total number, length of diameters, surface area, and volume of drops, respectively, contain precisely all of the drops of smaller diameter. Some examples are:

- $D_{N0.5}$ = number median diameter,
 $D_{L0.5}$ = length median diameter,
- $D_{L0.5}$ = length median diameter,
 $D_{A0.5}$ = surface area median diam
-
- $D_{A0.5}$ = surface area median diameter,
 $D_{V0.5}$ = volume median diameter, and
- $D_{\text{V0.5}}^{100}$ = volume median diameter, and
 $D_{\text{V0.9}}$ = drop diameter such that 90 % $=$ drop diameter such that 90 % of the total liquid volume is in drops of smaller diameter.

See Table 2 for numerical examples. 3.2.3

$$
\log(\bar{D}_{gm}) = \sum_{i} \log(D_{i})/n \tag{2}
$$

where:

 $n =$ number of drops, $\bar{D}_{\rho m}$ = the geometric mean diameter 3.2.4

$$
D_{RR} = D_{VF} \tag{3}
$$

where:

 $f = 1 - 1/e \approx 0.6321$, and

 D_{RR} = Rosin-Rammler Diameter fitting the Rosin-Rammler distribution factor (see Terminology [E1296\)](#page-0-0).

3.2.5 D_{kub} = upper-boundary diameter of drops in the *k*th size class.

3.2.6 D_{k1b} = lower-boundary diameter of drops in the *k*th

$$
\frac{340.5}{37729} = 0.009 \text{ Relative Span} = (D_{V0.9} - D_{V0.5})/D_{V0.5} = (3900 - 14200)/2530 = 0.98
$$

Less than 1 %, adequate sample size Adequate class sizes Adequate class sizes Adequate class sizes

348.5

 $\frac{669}{2676+3345}$ \times 0.21826 = 0.024

A The individual entries are the values for each κ as used in 5.2.1 (Eq 1) for summing by size class.

³ in size class divided by SUM *Di* ³ in entire sample.