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3691

INTERNATIONAL ORGANIZATION FOR STANDARDIZATION MEX CHAPODHAR OPPAHUSALUR TO CTAHDAPTUSALUMOORGANISATION INTERNATIONALE DE NORMALISATION

Powered industrial trucks - Safety code

Chariots automoteurs - Code de sécurité

Second edition - 1980-11-15

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FOREWORD

ISO (the International Organization for Standardization) is a worldwide federation of national standards institutes (ISO member bodies). The work of developing International Standards is carried out through ISO technical committees. Every member body interested in a subject for which a technical committee has been set up has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work.

Draft International Standards adopted by the technical committees are circulated to the member bodies for approval before their acceptance as International Standards by the ISO Council.

International Standard ISO 3691 was developed by Technical Committee ISO/TC 110, Industrial trucks.

This second edition incorporates Addendum 1-1978 and draft Addendum 2, which were circulated to the member bodies in January 1977 and October 1978 respectively. It cancels and replaces the first edition, i.e. ISO 3691-1977.

The second edition has been approved in its entirety by the member bodies of the following countries :

Austria	Netherlands	Sweden
Belgium	Poland	Switzerland
Czechoslovakia	Romania	USA
France	South Africa, Rep. of	USSR
India	Spain	Yugoslavia

Addendum 1-1978 was approved by the member bodies of the following additional countries :

Brazil	Germany, F.R. (S1	tan New Zealand teh.ai)
Bulgaria	Italy	Turkey
Denmark	Japan Karra Bap of	SIST ISO 3691:1999
Finland	Korea, Rep. of https://standards.iteh.	ai/catalog/standards/sist/c5581a9b-1775-46ae-ba87-

Draft Addendum 2 was approved by the member bodies of the following additional countries :

> Denmark Japan Mexico United Kingdom

The member bodies of the following countries expressed disapproval of the first edition of ISO 3691 or of the Addenda 1 and 2, circulated in 1975 :

> Germany, F.R. Japan New Zealand United Kingdom

The member bodies of the following countries expressed disapproval of Addendum 1-1978 :

Australia United Kingdom

The member bodies of the following countries expressed disapproval of draft Addendum 2 :

> Australia Germany, F.R. New Zealand

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Powered industrial trucks - Safety code

SECTION ONE : GENERAL

1 SCOPE AND FIELD OF APPLICATION

This International Standard specifies the safety requirements for the manufacture, application, operation and maintenance of powered industrial trucks.

The term "powered industrial trucks" applies to mobile, power-driven vehicles used to carry, push, pull, lift, stack or tier any type of load, as described in clause 3.

The word "shall" is to be understood as expressing a mandatory requirement and the word "should" as expressing a recommended requirement.

2 REFERENCES

ISO 5767, Industrial trucks operating in special condition of stacking with mast tilted forward – Stability tests.²⁾ ISO 6055, High-lift rider trucks – Overhead guards –

Specification and testing.

ISO 6292/1, Powered industrial trucks – Brake performance – Part 1 : High-lift, low-lift and non-lifting.²⁾

ISO 6500, Powered industrial trucks – Service brakes – Component strength-performance requirements.

3 NOMENCLATURE, CLASSIFICATION AND DEFI-NITIONS

ISO 1074, Counterbalanced lift trucks Stability Basic 3.1 The classification and nomenclature for powered industrial trucks are given in ISO 5053/1. The definitions will be covered in an International Standard currently under study.

rating.

ISO 1214/1, Powered industrial trucks Parameters for sist Standard, 7 the 4 following definitions and classifications designation of rated capacity and capacity — Part 1- Powered iso-36 apply 99

ISO 2330, Fork lift trucks – Fork arms – Technical characteristics and testing.

ISO 3184, Reach and straddle fork lift trucks – Stability tests.

ISO 3287, Powered industrial trucks – Control symbols.²⁾

ISO 5053/1, Powered industrial trucks – Terminology – Part 1 : Classification and nomenclature.²⁾

ISO 5766, Pallet-stackers and high-lift platform trucks – Stability tests.²⁾

3.2.1 low-lift truck : A self-loading truck equipped with an elevating mechanism designed to raise the load to a height just sufficient to permit horizontal movement.

3.2.2 high-lift truck : Either a self-loading truck equipped with an elevating mechanism designed to permit stacking and tiering or an order-picker truck (whether self-loading or not) equipped with a similar elevating mechanism.

NOTE – Sub-clauses 3.2.1 and 3.2.2 are presented for use pending the publication of the International Standard currently under study for the definitions of powered industrial trucks.

SECTION TWO : FOR THE MANUFACTURER OF POWERED INDUSTRIAL TRUCKS

4 RATED CAPACITY (Capacité nominale)

The manufacturer's rated capacity of a powered industrial platform or lift truck is the maximum load, established by the manufacturer, that a given truck is capable of transport-

ing or lifting in normal operation under conditions as set forth in 4.1 to 4.5, based on the strength of the various components of the truck and, when applicable, also based on the stability requirements and tests as set forth in clause 6 of this International Standard.

¹⁾ At present at the stage of draft. (Revision of ISO/R 1214-1971)

²⁾ At present at the stage of draft.

Alternative capacity ratings may also be established.

The loads shall be expressed in kilograms (kg) and the dimensions in metres (m) or millimetres (mm) in countries using the International System of Units (SI).

The loads shall be expressed in pounds (lb) and the dimensions in inches (in) in countries using the Imperial System.

The rated capacity of a towing tractor corresponds to the maximum draw-bar pull, established by the manufacturer, that the tractor is capable of developing in normal operation under specified conditions.

4.1 Fixed-platform trucks

The rated capacity of a fixed-platform truck is the maximum load, established by the manufacturer, uniformly distributed over the load-carrying platform, which the truck is capable of transporting under normal conditions of operation.

4.2 High-lift trucks

4.2.1 Counterbalanced fork lift trucks Teh STAND

"Nominal rating" of ISO 1084. The rated capacity of a counterbalanced fork lift truck is as **O** defined in clause 2 of ISO/R 1214.

The designation of the rated capacity shall correspond sports The rated capacity of a removable attachment is the the capacities, defined as a function of the maximum lifte/stan maximum load at a specified load centre distance, establishheight E of the truck, as stated in clause 3 of ISO/R 1214,731031

The standard load centre distances shall be as defined in clause 4 of ISO/R 1214.

4.2.2 Reach and straddle trucks

The rated capacity of a reach truck or of a straddle fork lift truck is the maximum load, established by the manufacturer, which it is capable of transporting and lifting at a distance D measured between the load centre of gravity and the front face of the shank of the fork, with vertical mast and horizontal fork, and for an elevation of 3,3 m (130 in).

The distance D shall be 400, 500 or 600 mm for trucks delivered in countries using the International System of Units (SI), and 16, 20 or 24 in in countries using the Imperial System.

NOTE - The above text is valid until a new International Standard defining the rated capacity of these trucks is available.

4.2.3 Pallet-stacker and high-lift platform trucks

The rated capacity of a pallet-stacker or high-lift platform truck is the maximum load, established by the manufacturer, which it is capable of transporting and lifting at a distance D measured between the load centre of gravity and the front face of the shank of the fork or abutment of the platform and for an elevation of 2,5 m (100 in) for trucks

having a width over the fork arms or platform up to and including 690 mm (27 in) and for an elevation of 3,3 m (130 in) for trucks having a width over the fork arms or platform greater than 690 mm (27 in).

The distance D shall be 400, 500 or 600 mm for trucks delivered in countries using the International System of Units (SI), and 16, 20 or 24 in in countries using the Imperial System.

NOTE - The above text is valid until a new International Standard defining the rated capacity of these trucks is available.

4.2.4 Order-picker trucks

4.2.5 Side-loading fork lift trucks

4.3 Low-lift trucks (pallet, stillage and platform)

The rated capacity of a low-lift truck is the uniformly distributed load, established by the manufacturer, which it is capable of transporting.

4.4 Tractors

This term applies to industrial tractors defined in clause 2 of ISO 1084.

The nominal capacity of a tractor is defined in clause 3,

4.5 Removable attachments

ed by its manufacturer, that the attachment is capable of handling in normal operation under specified conditions.

5 INFORMATION PLATES

5.1 Powered industrial trucks

Every powered industrial truck shall bear a durable identification plate, permanently attached in a prominent position, which shall indicate the condition of the truck when delivered from the manufacturer and give the following information in indelible characters :

5.1.1 Engine trucks

a) name of truck manufacturer (and importer, if required) and also, if desired, the manufacturer's trademark;

- b) type;
- c) production or serial number;

d) unladen weight in working condition, without removable attachments but complete with fork arms in the case of a fork-lift truck;

e) capacity at maximum elevation.

5.1.2 Electric trucks

a) name of truck manufacturer (and importer, if required) and also, if desired, the manufacturer's trademark:

b) type;

c) production or serial number;

d) unladen weight in working condition, without removable attachments but complete with fork arms in the case of fork lift trucks:

e) capacity at maximum elevation;

- f) weight of unladen truck without battery;
- g) minimum and maximum allowable battery weight;

h) nominal battery voltage for which the truck system is arranged.

5.1.3 Trucks with front end attachments

In addition to the information listed in either 5.1.1 or 5.1.2, the identification plate shall also bear the following information .

a) type of attachment:

b) weight of unladen Itruck in working condition RD PREVIEW

- without fork arms but fitted with the attachment;
- c) capacity of the truck and attachment combinations at maximum elevation.

NOTES

s rated 03b/stot 1 It is also permissible to indicate the manufacturer's ra capacity on the plate.

2 The load capacity may be indicated on a separate plate, if desired.

3 When a truck or attachment is imported by a person other than the original manufacturer, it is the responsibility of the importer to affix an additional plate bearing his name as well as the requirements of 5.1.1, 5.1.2 and 5.1.3.

5.2 Removable attachments

Every removable attachment shall carry a separate identification plate giving the following information :

a) name of attachment manufacturer (and importer if required);

- b) type;
- c) production or serial number;
- d) weight of the attachment and distance of its centre of gravity from the attachment mounting face;
- e) rated capacity of the attachment.
- NOTE The following warning shall be added :

"WARNING. Actual load may be restricted by reference to the capacity of the truck."

5.3 Batteries for electric trucks

The traction batteries shall carry an identification plate showing :

a) name of battery manufacturer;

- b) type;
- c) serial number;
- d) nominal voltage:
- e) capacity in ampere hours at the 5-hour rate:
- f) weight, in working order with removable container (and ballast) if used.

Alternatively, the battery weight may be stamped on the removable container (and ballast) near the lifting means.

5.4 Special use

If a truck is to be operated under conditions other than the normal working conditions, it shall bear a durable plate, in a prominent position, giving the following information :

a) designation of the special condition(s) of use;

b) capacity for each one of the special conditions of use.

6 STABILITY - REQUIREMENTS AND TESTS

Powered industrial trucks shall meet the requirements for stability when tested in accordance with the relevant ISO publications referred in 6.1 to 6.7. The tests set forth in these publications are intended to ensure that high-lift industrial⁹ trucks have satisfactory stability characteristics when properly operated under normal operating conditions. The tests are to be carried out by the manufacturer on prototype trucks which are fully representative of series production trucks.

6.1 Counterbalanced trucks

See ISO 1074.

6.2 Reach (retractable mast or forks) and straddle fork lift trucks (pedestrian and rider controlled)

See ISO 3184.

6.3 Pallet-stacker and high-lift platform trucks (pedestrian and rider controlled)

See ISO 5766.

6.4 Order-picker trucks

An International Standard is currently under study.

6.5 Side-loading fork lift trucks

An International Standard is currently under study.

6.6 Rough terrain trucks

An International Standard is currently under study.

6.7 Trucks operating in the special condition of stacking with the mast tilted forward

See ISO 5767.

NOTE — When available, references to the relevant ISO publication concerning additional stability tests will be added.

7 BRAKE PERFORMANCE

The brakes fitted on a powered industrial truck or tractor shall meet the performance requirements set forth in ISO 6292/1 and ISO 6500.

8 DIRECTION OF TRAVEL – CONTROLS

8.1 General

The best controls are those which most closely agree with DARD PREV natural human instinct. Such controls are sometimes called "directional" where control movement is in the same acc. Shunting tractor direction as the desired movement of the truck or accessory. Some controls such as "forward" and "reverse" are obvious and easy to make "directional".

Other control movements are less obviously directional and standards/sist/c55 call for a thorough study and/or testing to determine the 103b/sist-iso-3691 most natural human reaction. Recommendations for preferred motions and placement of controls are intended to establish uniform practices in this area.

Still other controls involve no element of "naturalness", and the naming then has to be done on an arbitrary basis. The arbitrary method should be used only after a thorough study reveals no natural tendency or ease for a given type of direction of control. Such arbitrarily named controls would be one of the greatest areas for lack of uniformity unless co-ordinated by some standards-making body.

8.2 Front-end and forward directions of travel

8.2.1 Front end of a truck

The front end of a truck is the end nearest the arrow in figures 1 to 18.

8.2.2 Rear end, left-hand, and right-hand side of a truck

The rear end, left-hand, and right-hand side of a truck are in conformity with the definition given in 8.2.1.

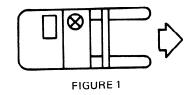
8.2.3 Forward direction of travel

The forward direction of travel is the direction indicated by the arrow in figures 1 to 18. All sketches show plan views of trucks.

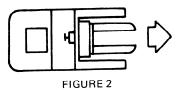
8.2.3.1 SIT-ON TRUCKS

8.2.3.1.1 Trucks where the load is leading when the truck travels in the forward direction

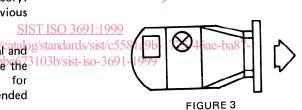
a) Counterbalanced fork lift truck



b) Straddle or reach (with retractable mast or fork) truck

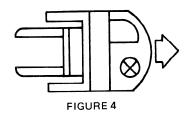


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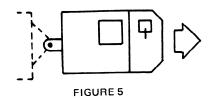


8.2.3.1.2 Trucks where the load is trailing when the truck travels in the forward direction

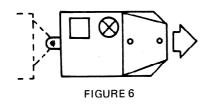
a) Straddle or reach (with retractable mast or fork) truck where the operator is seated sideways



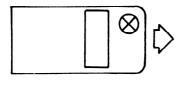
b) Towing tractor - Front-end control



c) Towing tractor - Rear-end control



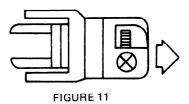
d) Fixed-platform truck





8.2.3.2.2.2 Trucks where the load is trailing when the truck travels in the forward direction

a) Straddle or reach truck (with retractable mast or fork), with the operator standing sideways



b) High-lift or low-lift platform truck



8.2.3.2.2 End control

c) Fixed-platform truck

- **8.2.3.2.2.1** Trucks where the load is leading when the truck travels in the forward direction
 - a) Counterbalanced fork lift truck

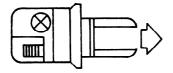
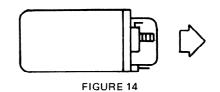


FIGURE 9

b) Straddle or reach (with retractable mast or fork) truck





d) Order-picker truck

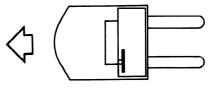
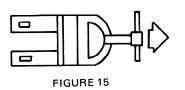


FIGURE 14 a)

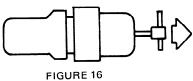
8.2.3.3 PEDESTRIAN-CONTROLLED TRUCKS

Trucks where the load is trailing when the truck travels in the forward direction

a) Pallet truck



b) High-lift or low-lift platform truck



c) Counterbalanced fork lift truck

d) Where a steering hand wheel and knob are used, either the configuration shall be of a design which will minimize the hazard from a spinning hand wheel due to road reaction feedback, or the steering mechanism shall be of a type which prevents road reactions from causing the steering hand wheel to spin.

e) It is recommended that steering knobs, when used, be of a type which is engaged by the operator's hand from the top, and within the periphery of the steering hand wheel.

8.3.1.1 STEERING WHEELS

8.3.1.1 On all trucks on which the operator faces in the normal line of travel and which are steered by means of a steering wheel (horizontal, inclined or vertical), a clockwise rotation of the steering wheel shall steer the truck to the right in the forward direction of travel.



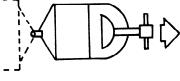


FIGURE 18

8.3 Steering controls

8.3.1 Steering - Rider trucks

a) All steering controls shall be confined within the plan view outline of the truck, or guarded to prevent injury to the operator during movement of the controls when passing obstacles, walls, columns, etc.

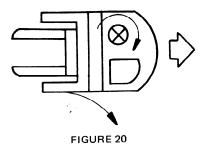
b) Where steering must be accomplished with one hand, steering knobs are necessary for safe operation. Steering knobs, when used, shall be mounted within the periphery of the steering handwheel and provision shall be made to prevent injury to the operator's hand.

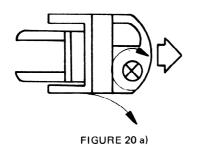
c) When conditions of use would result in steering shocks being generated, the transmission of such shocks to the steering hand wheel shall be limited to the extent necessary to avoid injury to the driver's hand or arm.

NOTE - Considerable numbers of trucks of models 8.2.3.1.2 a) and 8.2.3.2.2 have been built with a steering reverse of the above standard. Such trucks may still be operated, provided that the function and mode of operation of the controls is clearly indicated.

FIGURE 19 a)

8.3.1.1.2 On all trucks on which the operator faces at a right angle to the normal line of travel and which are steered by means of a steering wheel (horizontal, inclined or vertical), a clockwise rotation of the steering wheel shall steer the truck clockwise when the truck is travelling with the load trailing. (See the note in 8.3.1.1.1, which also applies in this case.)

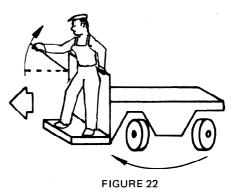




8.3.1.2 TILLERS

8.3.1.2.1 *Tillers operating in a horizontal plane*

On trucks steered by a tiller which moves in the horizontal plane and which in the neutral position is parallel to the longitudinal axis of the truck, or on trucks steered by a tiller which rotates on a shaft parallel to the longitudinal axis of the truck and which in the neutral position stands upright, when the driver is facing in the direction of travel, movement of the tiller to his right shall steer the truck to his right. direction of travel (figure 22). (See the note in 8.3.1.1.1, which also applies in this case.)



8.3.2 Steering handle – Motorized hand and hand/rider trucks

8.3.2.1 The handle on the tongue shall be provided with suitable means to protect the operator's hand against injury from swinging doors, walls, columns, etc.

8.3.2.2 Motorized hand/rider trucks employing a steering tongue control which extends beyond the confines of the truck shall steer as follows :

ICATCS.I With the walking operator facing in the direction of travel, with the load trailing, clockwise movement of the steering tongue shall steer the truck clockwise. SIST ISO 3691:1999

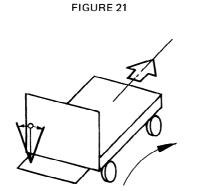
hai/catalog/standards/sistWiths the riding operator facing in the direction of travel, bbc673103b/sist-iso-3with the load trailing, clockwise movement of the steering tongue shall steer the truck clockwise.

8.3.3 Pivoting steering controls

On trucks which are steered by means of a pivoting control operated by foot (figure 23) or by hand (figure 24), a clockwise rotation of this control, looking in the forward direction of travel, shall steer the truck to the right.



FIGURE 23



https

FIGURE 21 a)

8.3.1.2.2 Tillers operating in a vertical plane

On stand-on lift platform trucks (8.2.3.2.2.2 b)) and fixedplatform trucks (8.2.3.2.2.2 c)) which are steered by means of a tiller situated on the right of the operator and operating in a vertical plane, raising the tiller (clockwise rotating) shall steer the truck to the right in the forward