



Designation: E1588 – 16a

Standard Practice for Gunshot Residue Analysis by Scanning Electron Microscopy/Energy Dispersive X-Ray Spectrometry¹

This standard is issued under the fixed designation E1588; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ϵ) indicates an editorial change since the last revision or reapproval.

1. Scope

1.1 This practice covers the analysis of gunshot residue (GSR) by scanning electron microscopy/energy-dispersive X-ray spectrometry (SEM/EDS) using manual and automated methods. The analysis may be performed manually, with the operator manipulating the microscope controls and the EDS system software, or in an automated fashion, where some amount of the analysis is controlled by pre-set software functions. This practice refers to the analysis of electron microscopy stubs and does not address sample collection (1).²

1.2 Since software and hardware formats vary among commercial systems, guidelines will be offered in the most general terms possible. For proper terminology and operation, consult the SEM/EDS system manuals for each instrument.

1.3 The values stated in SI units are to be regarded as standard. No other units of measurement are included in this standard.

1.4 This practice offers a set of instructions for performing one or more specific operations. This practice cannot replace knowledge, skill, or ability acquired through appropriate education, training, and experience and should be used in conjunction with sound professional judgment.

1.5 This practice does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user when applying this practice to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.

2. Referenced Documents

2.1 ASTM Standards:³
[E1492 Practice for Receiving, Documenting, Storing, and](#)

¹ This practice is under the jurisdiction of ASTM Committee E30 on Forensic Sciences and is the direct responsibility of Subcommittee E30.01 on Criminalistics.

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² The boldface numbers in parentheses refer to a list of references at the end of this standard.

³ For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

Retrieving Evidence in a Forensic Science Laboratory

3. Terminology

3.1 *Definitions of Terms Specific to This Standard:*

3.1.1 *major, adj*—element whose main peak height is greater than $\frac{1}{3}$ of the peak height of the strongest peak in the spectrum.

Wallace, 1984 (2)

3.1.2 *minor, adj*—element whose main peak height is between $\frac{1}{10}$ and $\frac{1}{3}$ of the peak height of the strongest peak in the spectrum.

Wallace, 1984 (2)

3.1.3 *trace, adj*—element whose main peak height is less than $\frac{1}{10}$ of the peak height of the strongest peak in the spectrum.

Wallace, 1984 (2)

4. Summary of Practice

4.1 From the total population of particles collected, those that are detected by SEM to be within the limits of certain parameters (for example, atomic number, size, or shape) are analyzed by EDS (3-5). Typically, particles composed of high mean atomic number elements are detected by their SEM backscattered electron signals and an EDS spectrum is obtained from each. The EDS spectrum is evaluated for constituent elements that may identify the particle as being consistent with or characteristic of GSR, or both. See Section 9 for discussion on classification of particles.

5. Significance and Use

5.1 This document will be of use to forensic laboratory personnel who are involved in the analysis of GSR samples by SEM/EDS (6).

5.2 SEM/EDS analysis of GSR is a non-destructive method that provides (7, 8) both morphological information and the elemental profiles of individual particles.

5.3 Particle analysis contrasts with bulk sample methods, such as atomic absorption spectrophotometry (AAS) (9), neutron activation analysis (NAA) (10), inductively coupled plasma atomic emission spectrometry (ICP-AES), and inductively coupled plasma mass spectrometry (ICP-MS), where the

sampled material is dissolved or extracted prior to the determination of total element concentrations, thereby sacrificing morphological information and individual particle identification.

5.4 X-ray fluorescence spectrometry (XRF) is a technique that has been used to map the placement and distribution of GSR particles surrounding bullet holes in order to establish shooting distances (11). Unlike the solution-based bulk methods of analysis, XRF is non-destructive; however, XRF still does not provide morphological information and is incapable of individual GSR particle identification.

6. Sample Preparation

6.1 Once the evidence seal is broken, care should be taken so that no object touches the surface of the adhesive SEM/EDS sample collection stub and that the stub is not left uncovered any longer than is reasonable for transfer, mounting, or labeling.

6.2 Label the sample collection stub in such a manner that it is distinguishable from other sample collection stubs without compromising the sample; for example, label the bottom or side of the stub.

6.3 If a non-conductive adhesive was used in the sample collection stub, the sample will need to be coated to increase its electrical conductivity, unless an environmental SEM or variable-pressure/low-vacuum SEM is used for the analysis. Carbon is a common choice of coating material, since it will not interfere with X-ray lines of interest. For high-vacuum SEM, coat the sample sufficiently to eliminate charging of the sample.

6.4 Observe the appropriate procedures for handling and documentation of all submitted samples as described in Practice E1492.

7. Sample Area

7.1 Sample collection stubs for SEMs typically come in one of two diameters: 12.7 mm or 25.4 mm, which yield surface areas of 126.7 mm² and 506.7 mm² respectively.

7.2 Manual analysis of the total surface area of the stub is prohibitively time-consuming. Because the particles are collected onto an adhesive surface in a random manner and the particles do not tend to cluster, it is reasonable to analyze a portion of the stub surface by employing an appropriate sampling and analytical protocol (8, 12).

7.3 Automated SEM/EDS analysis can enable data collection from nearly the entire surface area of the sample collection stub. Due to the disparity between the shape of the sample collection stub (round) and the SEM field of view search area (square or rectangular), analysis of 100 % of the sample collection area may not be possible in some systems.

7.3.1 Analysis of the maximum allowable surface area of the sample is recommended, however, many automated systems can be programmed to terminate the analysis of a stub or series of stubs once a pre-established number of particles with specified classification(s) have been detected. The decision as to how many particles satisfy the requirements of a particular

case is a matter for the analyst to decide but should be subject to guidelines set out in the laboratory's standard operating procedures.

8. Instrument Requirements and Operation

8.1 General:

8.1.1 Most commercial-grade SEM/EDS systems should be adequate for GSR analysis.

8.1.2 Automated data collection of GSR involves some portion of the data collection being controlled by pre-set software functions. The extent to which the SEM and EDS systems communicate and are integrated varies according to the manufacturers involved and the capabilities of the hardware/software architecture.

8.2 Scanning Electron Microscope (SEM):

8.2.1 The SEM, operating in the backscattered electron imaging mode, must be capable of detecting particles down to at least 0.5 µm in diameter.

8.2.2 The SEM must be capable of an accelerating voltage of at least 20 kV.

8.2.3 Automated SEM/EDS systems include: communication and control between the SEM and EDS system, and a motorized stage with automated stage control. The system should have the ability to recall stage locations of particles for verification and software for particle recognition.

8.3 Energy Dispersive Spectrometry (EDS):

8.3.1 The detector's resolution should be better (less) than 150 eV, measured as the full width at half the maximum height of the Mn Ka peak.

8.3.2 At a minimum, the EDS spectrum should be acquired at 20 eV per channel.

8.3.3 Display of the EDS output must encompass the X-ray lines of analytical utility, with a minimum range of 0–15 keV.

8.3.4 Automated systems will also include software capable of acquiring X-ray spectra for a specified collection time or total X-ray counts.

8.3.5 It is recommended that the instrument be capable of recording spectra obtained from the analysis of each particle of interest. At a minimum, an automated system must be capable of storing all of the particle location coordinates.

8.4 Sample Placement:

8.4.1 Record the positions of the stubs (sample and standard/reference stubs) on the SEM stage when the samples are inserted.

8.4.2 If it is anticipated or required that additional analyses will be needed, it is desirable that the stub can be returned to the same orientation as before its removal. This may consist of marking the side of each stub and aligning it with marks on the microscope stage or by having stubs that fit into the stage in only one position (for example, stubs with a pin that is a half-circle in cross section).

8.5 Detection and Calibration:

8.5.1 Particles of GSR are detected by their backscattered electron signal intensity. The absolute signal intensity that a particle produces is related to the electron beam current, mean atomic number, and size of the particle (for particle sizes on the order of the beam diameter). Particles whose mean atomic