INTERNATIONAL STANDARD

IEC 61850-7-4

First edition 2003-05

Communication networks and systems in substations –

Part 7-4:

Basic communication structure for substation and feeder equipment – Compatible logical node classes and data classes

5d5-3c7b-481c-9



Publication numbering

As from 1 January 1997 all IEC publications are issued with a designation in the 60000 series. For example, IEC 34-1 is now referred to as IEC 60034-1.

Consolidated editions

The IEC is now publishing consolidated versions of its publications. For example, edition numbers 1.0, 1.1 and 1.2 refer, respectively, to the base publication, the base publication incorporating amendment 1 and the base publication incorporating amendments 1 and 2.

Further information on IEC publications

The technical content of IEC publications is kept under constant review by the IEC, thus ensuring that the content reflects current technology. Information relating to this publication, including its validity, is available in the IEC catalogue of publications (see below) in addition to new editions, amendments and corrigenda. Information on the subjects under consideration and work in progress undertaken by the technical committee which has prepared this publication, as well as the list of publications issued, is also available from the following:

- IEC Web Site (<u>www.iec.ch</u>)
- Catalogue of IEC publications

The on-line catalogue on the IEC web site (http://www.iec.ch/searchpub/cur fut.htm) enables you to search by a variety of criteria including text searches, technical committees and date of publication. On-line information is also available on recently issued publications, withdrawn and replaced publications, as well as corrigenda.

IEC Just Published

This summary of recently issued publications (http://www.iec.ch/online_news/justpub/ip_entry.htm) is also available by email. Please contact the Customer Service Centre (see below) for further information.

Customer Service Centre

of you have any questions regarding this publication or need further assistance, please contact the Customer Service Centre:

Email: <u>sustserv@rec.ch</u> Tel: +41 22 919 02 11 Eax: +41 22 919 03 00

INTERNATIONAL STANDARD

IEC 61850-7-4

First edition 2003-05

Communication networks and systems in substations –

Part 7-4:

Basic communication structure for substation and feeder equipment – Compatible logical node classes and data classes

© IEC 2003 — Copyright - all rights reserved

No part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm, without permission in writing from the publisher.

International Electrotechnical Commission, 3, rue de Varembé, PO Box 131, CH-1211 Geneva 20, Switzerland Telephone: +41 22 919 02 11 Telefax: +41 22 919 03 00 E-mail: inmail@iec.ch Web: www.iec.ch



PRICE CODE



CONTENTS

Normative references	FOI	REWC)RD		6	
2 Normative references 10 3 Terms and definitions 11 4 Abbreviated terms 11 5 Logical node classes 15 5.1 Logical Node groups 15 5.2 Interpretation of Logical Node tables 16 5.3 System Logical NodesLN Group: L 17 5.3.1 Coneral 17 5.3.2 LN: Physical device informationName: LPHD 18 5.3.3 Common Logical Node 18 5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLNO 19 5.4 Logical Nodes for protection functionsLN Group: P 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: RDIF 21 5.4.3 LN: Direction comparisonName: PDIR 22 5.4.4 LN: Directional overpowerName: PDIP 23 5.4.5 LN: Directional overpowerName: PDIP 23 5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of inequencyName: PFRC 24 5.4.8 LN: Hymoric restrainName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.11 LN: Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor restart inhi	INTRODUCTION 8					
3 Terms and definitions	1	Scope			9	
4 Abbreviated terms	2	Normative references			10	
5 Logical Node classes .15 5.1 Logical Node groups .15 5.2 Interpretation of Logical Node tables .16 5.3 System Logical Nodes In Group: L .17 5.3.1 General .17 5.3.2 LN: Physical device informationName: LPHD .18 5.3.3 Common Logical Node .18 5.3.4 LN: Logical node zeroName: LLNO .19 5.4 Logical Nodes for protection functionsLN Group: P .19 5.4.1 Modelling remarks .19 5.4.2 LN: DifferentialName: PDIF .21 5.4.3 LN: Direction comparisonName: PDIR .21 5.4.4 LN: DistanceName: PDIS .22 5.4.5 LN: Directional overpowerName: PDIP .23 5.4.5 LN: Directional overpowerName: PDIP .23 5.4.7 LN: Ratio of change of frequencyName: PDIP .23 5.4.7 LN: Ratio of change of frequencyName: PDIP .23 5.4.8 LN: Harmonic restraintName: PHAR .24 5.4.8 LN: Harmonic r	3	Term	efinitions	11		
5 Logical Node classes .15 5.1 Logical Node groups .15 5.2 Interpretation of Logical Node tables .16 5.3 System Logical Nodes In Group: L .17 5.3.1 General .17 5.3.2 LN: Physical device informationName: LPHD .18 5.3.3 Common Logical Node .18 5.3.4 LN: Logical node zeroName: LLNO .19 5.4 Logical Nodes for protection functionsLN Group: P .19 5.4.1 Modelling remarks .19 5.4.2 LN: DifferentialName: PDIF .21 5.4.3 LN: Direction comparisonName: PDIR .21 5.4.4 LN: DistanceName: PDIS .22 5.4.5 LN: Directional overpowerName: PDIP .23 5.4.5 LN: Directional overpowerName: PDIP .23 5.4.7 LN: Ratio of change of frequencyName: PDIP .23 5.4.7 LN: Ratio of change of frequencyName: PDIP .23 5.4.8 LN: Harmonic restraintName: PHAR .24 5.4.8 LN: Harmonic r	4	Abbre	eviated t	terms	11	
5.1 Logical Node groups 15 5.2 Interpretation of Logical Node tables 16 5.3 System Logical NodesLN Group: L 17 5.3.1 General 17 5.3.2 LN: Physical device informationName: LPHD 18 5.3.2 LN: Physical device informationName: LPHD 18 5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLN0 19 5.4 Logical Nodes for protection functionsLN Group: P 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: PDIF 21 5.4.3 LN: Direction companisonName: PDIR 22 5.4.4 LN: Directional coverpowerName: PDIR 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: PDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHR 24 5.4.10 LN: Instantaneous overcurrentName: PRRI 25 5.4.11	5					
5.2 Interpretation of Logical Node tables 16 5.3 System Logical NodesLN Group: L 17 5.3.1 General 17 5.3.2 LN: Physical device informationName: LPHD 18 5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLN0 19 5.4 Logical Nodes for protection functionsLN Group: P 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: RDIF 21 5.4.3 LN: Direction comparisonName: PDIR 22 5.4.4 LN: DistanceName: PDIS 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional overpowerName: PDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restratifixame: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN) Instantaficous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Transient earth faultName: PTEC 29 5.4.16 L	Ū	•				
5.3 System Logical Nodes N Group: L 17 5.3.1 General 17 5.3.2 LN: Physical device informationName: LPHD 18 5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLN0 19 5.4 Logical Nodes for protection functionsLN Group: P. 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: PDIF 21 5.4.3 LN: Direction comparisonName: PDIR 22 5.4.4 LN: DistanceName: PDIS 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional undernowerName: PDOP 23 5.4.6 LN: Directional undernowerName: PDOP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIGC 25 5.4.11 LN: Motor starting time supervisionName: PMS 26 5.4.12 LN: Motor starting time supervisionName: PMS 26			Internre	etation of Logical Node tables	16	
5.3.1 General 17 5.3.2 LN: Physical device informationName: LPHD 18 5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLN0 19 5.4 Logical Nodes for protection functionsLN Group: P 19 5.4.1 Modelling remarks. 19 5.4.2 LN: DifferentialName; RDIF 21 5.4.3 LN: Direction companisonName: PDIR 22 5.4.4 LN: DistanceName: PDIS 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional undernowerName: PDUP 23 5.4.7 LN: Rate of change of thequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 J.N: Ground detectorName: PHBR 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor starting time supervisionName: PMSS 26 5.4.13 LN: Tyransient earth faultname: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PTEF 29 5.4.19 LN: OverfrequencyName: PTOC 29 5.4.20 LN: UnderrotequencyName: PTOV 30 5.			System	Logical NodesLN Group: L	17	
5.3.2 LN: Physical device informationName: LPHD 18 5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLN0 19 5.4 Logical Nodes for protection functionsLN Group: P 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: RDIF 21 5.4.3 LN: Direction comparisonName: PDIR 22 5.4.4 LN: Directional overpowerName: PDIP 23 5.4.5 LN: Directional undernowen Name: PDIP 23 5.4.6 LN: Directional undernowen Name: PDIP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIOC 25 5.4.11 LN: Motor starting time supervisionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMRI 27 5.4.13 LN: Phase a			5.3.1	General	17	
5.3.3 Common Logical Node 18 5.3.4 LN: Logical node zeroName: LLN0 19 5.4 Logical Nodes for protection functionsLN Group: P 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName; RDIF 21 5.4.3 LN: Direction companisonName: PDIR 22 5.4.4 LN: DistanceName: PDIS 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: PDIP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIOC 25 5.4.11 LN: Motor setarting time supervisionName: PMS 26 5.4.12 LN: Motor setarting time supervisionName: PMS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Transient earth faultName: PTEF 29 5.4.16 LN: Underrection schemeName: PTOF 30			5.3.2	LN: Physical device informationName: LPHD.	18	
5.4 Logical Nodes for protection functionsLN Group: P. 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: RDIF 21 5.4.3 LN: Direction comparisonName: PDIR 22 5.4.4 LN: DistanceName: PDIS 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: PDOP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor starting time supervisionName: PMSS 26 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Thermal overloadName: PTTR 31 5.4.22 LN: UndercurrentName: PTUC 32 <td></td> <td></td> <td>5.3.3</td> <td>Common Logical Node</td> <td>18</td>			5.3.3	Common Logical Node	18	
5.4 Logical Nodes for protection functionsLN Group: P. 19 5.4.1 Modelling remarks 19 5.4.2 LN: DifferentialName: RDIF 21 5.4.3 LN: Direction comparisonName: PDIR 22 5.4.4 LN: DistanceName: PDIS 22 5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: PDOP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor starting time supervisionName: PMSS 26 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Thermal overloadName: PTTR 31 5.4.22 LN: UndercurrentName: PTUC 32 <td></td> <td></td> <td>5.3.4</td> <td>LN: Logical node zeroName: LLN0</td> <td>19</td>			5.3.4	LN: Logical node zeroName: LLN0	19	
5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOF 30 5.4.20 LN: OverfrequencyName: PTOF 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN:		5.4	Logical	Nodes for protection functionsLN Group: P	19	
5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOF 30 5.4.20 LN: OverfrequencyName: PTOF 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN:			5.4.1	Modelling remarks	19	
5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOF 30 5.4.20 LN: OverfrequencyName: PTOF 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN:			5.4.2	LN: DifferentialName: RDIF	21	
5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOF 30 5.4.20 LN: OverfrequencyName: PTOF 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN:			5.4.3	LN: Direction comparisonName: PDIR	22	
5.4.5 LN: Directional overpowerName: PDOP 23 5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOF 30 5.4.20 LN: OverfrequencyName: PTOF 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN:			5.4.4	LN: DistanceName: PDIS	22	
5.4.6 LN: Directional underpowerName: RDUP 23 5.4.7 LN: Rate of change of frequencyName: PFRC 24 5.4.8 LN: Harmonic restraintName: PHAR 24 5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIOC 25 5.4.11 LN: Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.20 LN: OverfrequencyName: PTOF 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: Underpower factorName: PUPF 33 5.4.25 LN: UnderfrequencyName:			5.4.5	LN: Directional overpowerName: PDOP	23	
5.4.8 LN: Harmonic restraintName; PHAR 24 5.4.9 LN: Ground detectorName; PHIZ 25 5.4.10 LN) Instantaneous overcurrentName; PIOC 25 5.4.11 LN: Motor restart inhibitionName; PMRI 25 5.4.12 LN: Motor starting time supervisionName; PMSS 26 5.4.13 LN: Over power factorName; POPF 26 5.4.14 LN: Phase angle measuringName; PPAM 27 5.4.15 LN: Protection schemeName; PSCH 27 5.4.16 LN: Sensitive directional earthfaultName; PSDE 28 5.4.17 LN: Transient earth faultName; PTEF 29 5.4.18 LN: Time overcurrentName; PTOC 29 5.4.19 LN: OverroltageName; PTOV 30 5.4.20 LN: OvervoltageName; PTOV 30 5.4.21 LN: Thermal overloadName; PTTR 31 5.4.22 LN: UndercurrentName; PTUC 32 5.4.24 LN: Underpower factorName; PUPF 33 5.4.25 LN: UnderfrequencyName; PTUF 33 5.4.26 LN: Voltage controlled time overcurrentName; PVOC 34			5.4.6	LN: Directional underpowerName: RDUP	23	
5.4.9 LN: Ground detectorName: PHIZ 25 5.4.10 LN: Instantaneous overcurrentName: PIOC 25 5.4.11 LN: Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: UndercurrentName: PTUC 32 5.4.23 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			5.4.7			
5.4.10 LN Instantaneous overcurrentName: PIOC 25 5.4.11 LN: Motor restart inhibitionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34						
5.4.11 LN Motor starting time supervisionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			5.4.9	LN: Ground detectorName: PHIZ	25	
5.4.11 LN Motor starting time supervisionName: PMRI 25 5.4.12 LN: Motor starting time supervisionName: PMSS 26 5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			5.4.10	LN Instantaneous overcurrentName: PIOC	25	
5.4.13 LN: Over power factorName: POPF 26 5.4.14 LN: Phase angle measuringName: PPAM 27 5.4.15 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: UnderfrequencyName: PTUF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			5.4.11	LN: Motor restart inhibitionName: PMRI	25	
5.4 14 LN Phase angle measuringName: PPAM 27 5.4 15 LN: Protection schemeName: PSCH 27 5.4 16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34						
5.4.16 LN: Protection schemeName: PSCH 27 5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34						
5.4.16 LN: Sensitive directional earthfaultName: PSDE 28 5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			^ \			
5.4.17 LN: Transient earth faultName: PTEF 29 5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34		<	. \ \			
5.4.18 LN: Time overcurrentName: PTOC 29 5.4.19 LN: OverfrequencyName: PTOF 30 5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			_	\ •		
5.4.19 LN: OverfrequencyName: PTOF305.4.20 LN: OvervoltageName: PTOV305.4.21 LN: Protection trip conditioningName: PTRC305.4.22 LN: Thermal overloadName: PTTR315.4.23 LN: UndercurrentName: PTUC325.4.24 LN: UndervoltageName: PTUV325.4.25 LN: Underpower factorName: PUPF335.4.26 LN: UnderfrequencyName: PTUF335.4.27 LN: Voltage controlled time overcurrentName: PVOC34						
5.4.20 LN: OvervoltageName: PTOV 30 5.4.21 LN: Protection trip conditioningName: PTRC 30 5.4.22 LN: Thermal overloadName: PTTR 31 5.4.23 LN: UndercurrentName: PTUC 32 5.4.24 LN: UndervoltageName: PTUV 32 5.4.25 LN: Underpower factorName: PUPF 33 5.4.26 LN: UnderfrequencyName: PTUF 33 5.4.27 LN: Voltage controlled time overcurrentName: PVOC 34			-		-	
5.4.21 LN: Protection trip conditioningName: PTRC						
5.4.22 LN: Thermal overloadName: PTTR315.4.23 LN: UndercurrentName: PTUC325.4.24 LN: UndervoltageName: PTUV325.4.25 LN: Underpower factorName: PUPF335.4.26 LN: UnderfrequencyName: PTUF335.4.27 LN: Voltage controlled time overcurrentName: PVOC34						
5.4.23 LN: UndercurrentName: PTUC325.4.24 LN: UndervoltageName: PTUV325.4.25 LN: Underpower factorName: PUPF335.4.26 LN: UnderfrequencyName: PTUF335.4.27 LN: Voltage controlled time overcurrentName: PVOC34				•		
5.4.24 LN: UndervoltageName: PTUV						
5.4.25 LN: Underpower factorName: PUPF						
5.4.26 LN: UnderfrequencyName: PTUF				-		
5.4.27 LN: Voltage controlled time overcurrentName: PVOC34				•		
6 4 333 Bit Malta man Habiana (11/11)						
5.4.28 LN: Volts per HzName: PVPH				·		

5.5	Logical	Nodes for protection related functionsLN Group: R	35
	5.5.1	Modelling Remarks	35
	5.5.2	LN: Disturbance recorder functionName: RDRE	36
	5.5.3	LN: Disturbance recorder channel analogueName: RADR	37
	5.5.4	LN: Disturbance recorder channel binaryName: RBDR	37
	5.5.5	LN: Disturbance record handlingName: RDRS	38
	5.5.6	LN: Breaker failureName: RBRF	38
	5.5.7	LN: Directional elementName: RDIR	38
	5.5.8	LN: Fault locatorName: RFLO	
	5.5.9	LN: Power swing detection/blockingName: RPSB	
	5.5.10	LN: AutoreclosingName: RREC	40
	5.5.11	LN: Synchronism-check or synchronisingName: RSYN	41
5.6	Logical	Nodes for controlLN Group: C	42
	5.6.1	Modelling remarks	42
	5.6.2	LN: Alarm handlingName: CALH	42
	5.6.3	LN: Cooling group controlName: CCGR	42
	5.6.4	LN: InterlockingName: CILO	43
	5.6.5	LN: Point-on-wave switchingName: CPOW	43
	5.6.6	LN: Switch controllerName: CSWI	44
5.7	Logical	nodes for generic referencesLN Group: G	44
	5.7.1	LN: Generic automatic process control Name: GAPC	44
	5.7.2	LN: Generic process I/OName: GGIO	
	5.7.3	LN: Generic security application Name: GSAL	45
5.8	Logical	Nodes for interfacing and archiving N Group: I	
	5.8.1	LN: ArchivingName: IARC	46
	5.8.2	LN: Human machine interfaceName: IHMI	46
		LN: Telecontrol interfaceName: ITCI	
	5.8.4	LN Telemonitoring interfaceName: ITMI	47_4_200
5.9	Logical	Nodes for automatic controlLN Group: A	47
	5.9.1	Modelling remarks	47
	5.9.2	LN: Neutral current regulatorName: ANCR	
	5.9 3	LN. Reactive power controlName: ARCO	48
	5.9.4		
	5.9.5	LN: Voltage controlName: AVCO	49
5.10	Logical	Nodes for metering and measurementLN Group: M	50
	5.10.1	Modelling remarks	50
	5.10.2	LN: Differential measurementsName: MDIF	50
	5.10.3	LN: Harmonics or interharmonicsName: MHAI	51
	5.10.4	LN: Non phase related harmonics or interharmonicsName: MHAN	52
	5.10.5	LN: MeteringName: MMTR	54
	5.10.6	LN: Non phase related MeasurementName: MMXN	54
	5.10.7	LN: MeasurementName: MMXU	55
	5.10.8	LN: Sequence and imbalanceName: MSQI	55
	5.10.9	LN: Metering StatisticsName: MSTA	56
5.11	Logical	Nodes for sensors and monitoringLN Group: S	57
	5.11.1	Modelling remarks	57
	5.11.2	LN: Monitoring and diagnostics for arcsName: SARC	57
	5.11.3	LN: Insulation medium supervision (gas)Name: SIMG	57

	5.11.4 Liv. insulation medium supervision (liquid)Name. ShviL	50
	5.11.5 LN: Monitoring and diagnostics for partial dischargesName: SPDC	
5.12	2 Logical Nodes for switchgearLN Group: X	
	5.12.1 LN: Circuit breakerName: XCBR	
	5.12.2 LN: Circuit switchName: XSWI	
5.13	B Logical Nodes for instrument transformersLN Group: T	
	5.13.1 LN: Current transformerName: TCTR	
	5.13.2 LN: Voltage transformerName: TVTR	
5.14	Logical Nodes for power transformersLN Group: Y	
	5.14.1 LN: Earth fault neutralizer (Petersen coil)Name: YEFN	
	5.14.2 LN: Tap changerName: YLTC	62
	5.14.3 LN: Power shuntName: YPSH	
	5.14.4 LN: Power transformerName: YPTR	
5.15	5 Logical Nodes for further power system equipmentLN Group: Z	
	5.15.1 LN: Auxiliary networkName: ZAXN	
	5.15.2 LN: BatteryName: ZBAT	
	5.15.3 LN: BushingName: ZBSH	
	5.15.5 LN: Capacitor bankName: ZCAP	
	5.15.6 LN: ConverterName: ZCON	
	5.15.7 LN: GeneratorName: ZGEN	00
	5.15.9 LN: Power overhead ineName: ZLW	
	5.15.10LN: MotorName: ZMOT	67
	5.15.11LN: ReactorName: ZREA	67
	5.15.12LN: Rotating reactive componentName: ZRRC	
	5.15.13 LN: Surge arrestorName: ZSAR	
	5.15.14LN Tryristor controlled frequency converterName: ZTCF	
	5.15.15 LN. Thyristor controlled reactive componentName: ZTCR	
6 Data	a name semantics	
Annex A	(normative) Extension rules	91
	use of Logical Nodes and Data and its extensions	
	1 Basic rules	
	tiple instances of LN classes for dedicated and complex functions	
	1 Example for time overcurrent	
	2 Example for Distance	
	3 Example for Power transformer	
	4 Example for Auxiliary network cialisation of Data by use of the number extension	
	es for names of new Logical Nodes	
	mples for new LNs	
	1 New LN "Automatic door entrance control"	
	2 New LN "Fire protection"	
	es for names of new Data	
	mple for new Data	
A.8 Rule	es for new Common Data Classes (CDC)	94

Annex B (informative) Modelling examples95	
B.1 PTEF and PSDE95	
B.2 PSCH and PTRC96	
B.3 MDIF and PDIF97	
B.4 RDRE and Disturbance Recorder98	
B.5 PTRC	
B.6 PDIR 100	
B.7 RREC101	
B.8 PDIS 102	
Annex C (informative) Relationship between this standard and IEC 61850-5104	
Figure 1 – Overview of this standard	
Figure 2 – LN Relationships	
Figure B.1 – Fault current I_F in a compensated network with earth fault95	
Figure B.2 – Use of PSCH and PTRC96	
Figure B.3 – Use of MDIF and PDIF	
Figure B.4 – Modelling of Disturbance Recorder	
Figure B.5 – Examples for allocation of Logical Nodes to IEDs	
Figure B.6 – Use of PDIR	
Figure B.7 – Use of RREC	
Table 1 – List of Logical Node Groups	
Table 2 – Interpretation of Vogical Node tables	
Table 3 – Relation between IEC 61850-5 and IEC 61850-7-4 (this standard) for protection LNs	
Table 4 – Relation between IEC 61850 5 and IEC 61850-7-4 for protection related LNs35	
Table 5 – Relation between IEC 61850-5 and IEC 61850-7-4 for control LNs42	
Table 6 – Relation between IEC 61850-5 and IEC 61850-7-4 for automatic control LNs47	
Table 7 Relation between IEC 61850-5 and IEC 61850-7-4 for metering and measurement LNs	
Table 8 – Relation between IEC 61850-5 and IEC 61850-7-4 for sensors	
and monitoring LNs	
Table 9 – Description of Data69	
Table C.1 – Relationship between IEC 61850-5 and this standard for some miscellaneous LNs	

INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMUNICATION NETWORKS AND SYSTEMS IN SUBSTATIONS -

Part 7-4: Basic communication structure for substation and feeder equipment – Compatible logical node classes and data classes

FOREWORD

- 1) The IEC (International Electrotechnical Commission) is a worldwide organization for standardization comprising all national electrotechnical committees (IEC National Committees). The object of the IEC is to promote international co-operation on all questions concerning standardization in the electrical and electronic fields. To this end and in addition to other activities, the IEC publishes International Standards. Their preparation is entrusted to technical committees; any IEC National Committee interested in the subject dealt with may participate in this preparatory work. International, governmental and non-governmental organizations liaising with the IEC also participate in this preparation. The IEC collaborates closely with the International Organization for Standardization (ISO) in accordance with conditions determined by agreement between the two organizations.
- 2) The formal decisions or agreements of the IEC on technical matters express, as nearly as possible, an international consensus of opinion on the relevant subjects since each technical committee has representation from all interested National Committees.
- 3) The documents produced have the form of recommendations for international use and are published in the form of standards, technical specifications, technical reports or guides and they are accepted by the National Committees in that sense.
- 4) In order to promote international unification, IEC National Committees undertake to apply IEC International Standards transparently to the maximum extent possible in their national and regional standards. Any divergence between the IEC Standard and the corresponding national or regional standard shall be clearly indicated in the latter.
- 5) The IEC provides no marking procedure to indicate its approval and cannot be rendered responsible for any equipment declared to be in conformity with one of its standards.
- 6) Attention is drawn to the possibility that some of the elements of this International Standard may be the subject of patent rights. The JEC shall not be held responsible for identifying any or all such patent rights.

International Standard IEC 61850-7-4 has been prepared by IEC technical committee 57: Power system control and associated communications.

The text of this standard is based on the following documents:

	FDIS	Report on voting
$\setminus \setminus \setminus$	57/622/FDIS	57/640/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

IEC 61850 consists of the following parts, under the general title *Communication networks* and systems in substations:

- Part 1: Introduction and overview
- Part 2: Glossary 1
- Part 3: General requirements
- Part 4: System and project management
- Part 5: Communication requirements for functions and device models ²
- Part 6: Configuration description language for communication in electrical substations related to IEDs ¹
- Part 7-1: Basic communication structure for substation and feeder equipment Principles and models
- Part 7-2: Basic communication structure for substation and feeder equipment Abstract communication service interface (ACSI)
- Part 7-3: Basic communication structure for substation and feeder equipment Common data classes
- Part 7-4: Basic communication structure for substation and feeder equipment Compatible logical node classes and data classes
- Part 8-1: Specific communication service mapping (SCSM) Mappings to MMS (ISO/IEC 9506-1 and ISO/IEC 9506-2) and to ISO/IEC 8802-3
- Part 9-1: Specific communication service mapping (SCSM) Sampled values over serial unidirectional multidrop point to point link
- Part 9-2: Specific communication service mapping (SCSM) Sampled values over ISO/IEC 8802-3 1
- Part 10: Conformance testing

The content of this part of (EC 61850 is based on existing or emerging standards and applications. In particular the definitions are based upon:

- the specific data types defined in IEC 60870-5-101 and IEC 60870-5-103;
- the common class definitions from the Utility Communication Architecture 2.0: Generic Object Models for Substation and Feeder Equipment (GOMSFE) (IEEE TR 1550);
- CIGRE Report 34-03, Communication requirements in terms of data flow within substations, December 1996.

The committee has decided that the contents of this publication will remain unchanged until 2005. At this date, the publication will be

- · reconfirmed:
- · withdrawn;
- · replaced by a revised edition, or
- · amended.

¹ Under consideration.

² To be published.

INTRODUCTION

This part of IEC 61850 is a part of set of specifications (IEC 61850). IEC 61850 defines a substation communication architecture. This architecture has been chosen to provide abstract definitions of classes and services such that the specifications are independent of specific protocol stacks, implementations, and operating systems. The mapping of these abstract classes and services to communication stacks is outside the scope of IEC 61850-7-x and may be found in IEC 61850-8-x and in IEC 61850-9-x.

IEC 61850-7-1 gives an overview of this communication architecture. IEC 61850-7-3 defines common attribute types and common data classes related to substation applications. The attributes of the common data classes may be accessed using services defined in IEC 61850-7-2. These common data classes are used in this part to define the compatible data classes.

To reach interoperability, all data in the data model need a strong definition with regard to syntax and semantics. The semantics of the data is mainly provided by names assigned to logical nodes and data they contain, as defined in this part. Interoperability is easiest if as much as possible of the data are defined as mandatory. Because of different philosophies and technical features, settings were declared as optional in this edition of the standard. After some experience has been gained with this standard, this decision may be reviewed in an amendment or in the next revision of this part.

It should be noted that data with full semantics is only one of the elements required to achieve interoperability. Since data and services are hosted by devices (IED), a proper device model is needed along with compatible, domain specific services (see IEC 61850-7-2).

The compatible logical node name and data name definitions found in this part and the associated semantics are fixed. The syntax of the type definitions of all data classes are abstract definitions provided in IEC 61850-7-2 and IEC 61850-7-3. Not all features of logical nodes are listed in this part for example data sets and logs are covered in IEC 61850-7-2.

https://standards.iteh.aiv.vol.v.tandards/nc/3.vtb6d5-3c7b-481c-9e57-646c27808884/iec-61850-7-4-2003

COMMUNICATION NETWORKS AND SYSTEMS IN SUBSTATIONS -

Part 7-4: Basic communication structure for substation and feeder equipment – Compatible logical node classes and data classes

1 Scope

This part of IEC 61850 specifies the information model of devices and functions related to substation applications. In particular, it specifies the compatible logical node names and data names for communication between Intelligent Electronic Devices (IED). This includes the relationship between Logical Nodes and Data.

The Logical Node Names and Data Names defined in this document are part of the class model introduced in IEC 61850-7-1 and defined in IEC 61850-7-2. The names defined in this document are used to build the hierarchical object references applied for communicating with IEDs in substations and on distribution feeders. The naming conventions of IEC 61850-7-2 are applied in this part.

To avoid private, incompatible extension rules this part specifies normative naming rules for multiple instances and private extensions of Logical Node (LN) Classes and Data Names.

In Annex A, all rules are given (making use of examples) for:

- multiple instances of logical node classes by use of a LN instance identification (ID);
- multiple instances of data by use of a data instance ID;
- selecting data not included in LN out of the complete data name set;
- creating new logical node classes and data names.

In Annex B, examples are given for:

- the use of Logical Nodes in complex situations like line protection schemes;
- multiple instances of Logical Nodes with different levels of functionality.

This part does not provide tutorial material. It is recommended those parts IEC 61850-5 and IEC 61850-7.1 be read first, in conjunction with IEC 61850-7-3, and IEC 61850-7-2. This part does not discuss implementation issues. The relationship between this standard and IEC 61850-5 is outlined in Annex C.

This standard is applicable to describe device models and functions of substation and feeder equipment. The concepts defined in this standard may also be applied to describe device models and functions for:

- substation to substation information exchange,
- substation to control centre information exchange,
- power plant to control centre information exchange,
- information exchange for distributed generation,
- information exchange for distributed automation, or
- information exchange for metering.

Figure 1 provides a general overview of this document.

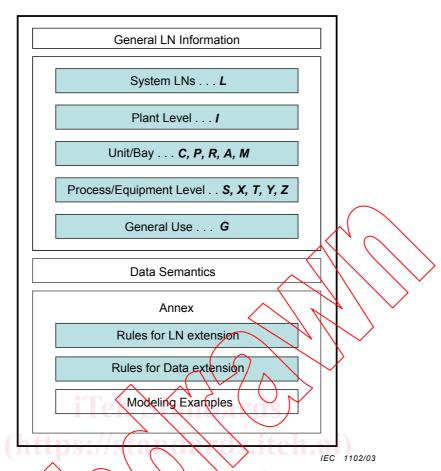


Figure 1 - Overview of this standard

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60255-24, Electrical relays – Part 24: Common format for transient data exchange (COMTRADE) for power systems

IEC 61000-4-7, Electromagnetic compatibility (EMC) – Part 4: Testing and measurement techniques – Section 7: General guide on harmonics and interharmonics measurements and instrumentation for power supply systems and equipment connected thereto

IEC 61850-2, Communication networks and system in substations – Part 2: Glossary 3

IEC 61850-5, Communication networks and systems in substations – Part 5: Communication requirements for functions and devices models

IEC 61850-7-1, Communication networks and systems in substations – Part 7-1: Basic communication structure for substation and feeder equipment – Principles and models

IEC 61850-7-2, Communication networks and systems in substations – Part 7-2: Basic communication structure for substation and feeder equipment – Abstract communication service interface (ACSI)

³ To be published.

IEC 61850-7-3, Communication networks and systems in substations – Part 7-3: Basic communication structure for substation and feeder equipment – Common data classes

IEEE 519:1992, IEEE Recommended Practises and Requirements for Harmonic Control in Electrical Power Systems

IEEE 1459:2000, IEEE Trial Use Standard Definitions for the Measurement of Electric Power Quantities Under Sinusoidal, Nonsinusoidal, Balanced or Unbalanced Conditions

IEEE C37.2:1996, Electrical Power System Device Function Numbers and Contact Designation

3 Terms and definitions

For the purpose of this international standard the terms and definitions given in VEC 61850-24 and IEC 61850-7-2 apply.

4 Abbreviated terms

The following terms are used to build concatenated Data Names. For example, ChNum is constructed by using two terms "Ch" which stands for "Channel" and "Mum" which stands for "Number". Thus the concatenated name represents a "channel number".

Term	Description	Term	Description
Α	Current	СВ	Circuit Breaker
Acs	Access	CDC	Common Data Class
ACSI	Abstract Communication Service Interface	CE	Cooling Equipment
Acu	Acoustic	Cf	Crest factor
Age	Ageing	Cfg	Configuration
Alm	Alarm	cG ⁰⁰³	Core Ground
standards.i Amp	Current non phase related	Ch Ch	c57-646c27808884/iec-61850-7-4-200
An	Analogue	Cha	Charger
Ang	Angle	Chg	Change
Auth	Authorisation	Chk	Check
Auto	Automatic	Chr	Characteristic
Aux	Auxiliary	Cir	Circulating
Av	Average	Clc	Calculate
В	Bushing	Clk	Clock, clockwise
Bat	Battery	CIs	Close
Beh	Behaviour	Cnt	Counter
Bin	Binary	Col	Coil
Blk	Block, blocked	Cor	Correction
Bnd	Band	Crd	Coordination
Во	Bottom	Crv	Curve
Сар	Capability	СТ	Current Transducer
Capac	Capacitance	Ctl	Control
Car	Carrier	Ctr	Center

⁴ Under consideration.

Term	Description	Term	Description
Сус	Cycle	Gri	Grid
Dea	Dead	Н	Harmonics (phase related)
Dea	Density	H ₂	Hydrogen
Det	Detected		Water
DExt	De-excitation	H ₂ O	
		На	Harmonics (non phase related)
Diag	Diagnostics	Hi	High, highest
Dif	Differential, difference	HP	Hot point
Dir	Direction	Hz	Frequency
Dis	Distance	IEEE	Institute of Electrical and Electronic Engineers
DI	Delay	Imb	Imbalance
DIt	Delete	Imp	Impedance non phase related
Dmd	Demand	In '	Input
Dn	Down	Ina	Unactivity
DPCSO	Double point controllable status output	Incr	Increment
DQ0	Direct, Quadrature, and zero axis quantities	Ind	Vindication
Drag	Drag hand	Jigh	Inhibit
Drv	Drive	Jans (Insulation
DS	Device State	Int 2 CO	Integer
Dsch	Discharge	ISCSQ	Integer status controllable status output
Dur	Duration	km	Kilometre
EC	Earth Coil		Lower
EE	External Equipment	LD	Logical Device
EF	Earth Fault	LDC	Line Drop Compensation
Ena 1 1	Enabled	LDCR	Line Drop Compensation Resistance
ständards.i Eq	Equalization Equal	LDCX	Line Drop Compensation Reactance
Ev	Evaluation	LDCZ	Line Drop Compensation Impedance
	External		Light Emitting Diode
Exc	Exceeded		Length
Exc Excl	Exclusion	Len Lev	Level
	\		
Ext	Excitation	Lg	Lag
FA	Fault Arc	Lim	Limit
Fact	Factor	Lin	Line
Fan	Fan	Liv	Live
Flt	Fault	LN	Logical Node
Flw	Flow	Lo	Low
FPF	Forward Power Flow	LO	Lockout
Fu	Fuse	Loc	Local
Fwd	Forward	Lod	Load, loading
Gen	General	Lok	Locked
Gn	Generator	Los	Loss
Gnd	Ground	Lst	List
Gr	Group	LTC	Load Tap Changer
Grd	Guard	m	minutes