

# INTERNATIONAL STANDARD

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**Touch and interactive displays -  
Part 12-10: Measurement methods of touch displays - Touch and electrical  
performance**

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IEC Secretariat  
3, rue de Varembeé  
CH-1211 Geneva 20  
Switzerland

Tel.: +41 22 919 02 11  
[info@iec.ch](mailto:info@iec.ch)  
[www.iec.ch](http://www.iec.ch)

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**Touch and interactive displays -  
Part 12-10: Measurement methods of touch displays -  
Touch and electrical performance**

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IEC 62908-12-10 has been prepared by IEC technical committee 110: Electronic displays. It is an International Standard.

This third edition cancels and replaces the second edition published in 2023. This edition constitutes a technical revision.

This edition includes the following significant technical changes with respect to the previous edition:

- a) added principle of force sensitive touch sensor module and force-output characteristics measurement;
- b) added required equipment for force-output characteristic measurement of force sensitive touch sensor module;
- c) added test method for force-output characteristics measurement.

The text of this International Standard is based on the following documents:

Draft	Report on voting
110/1757/CDV	110/1794A/RVC

Full information on the voting for its approval can be found in the report on voting indicated in the above table.

The language used for the development of this International Standard is English.

This document was drafted in accordance with ISO/IEC Directives, Part 2, and developed in accordance with ISO/IEC Directives, Part 1 and ISO/IEC Directives, IEC Supplement, available at [www.iec.ch/members\\_experts/refdocs](http://www.iec.ch/members_experts/refdocs). The main document types developed by IEC are described in greater detail at [www.iec.ch/publications](http://www.iec.ch/publications).

A list of all parts in the IEC 62908 series, published under the general title *Touch and interactive displays*, can be found on the IEC website.

The committee has decided that the contents of this document will remain unchanged until the stability date indicated on the IEC website under [webstore.iec.ch](http://webstore.iec.ch) in the data related to the specific document. At this date, the document will be

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## 1 Scope

This part of IEC 62908 specifies the standard measuring conditions and measurement methods for determining touch and hovering performance of a touch sensor module. This document is applicable to touch sensor modules, whereas the structural relationship between touch sensor, touch controller, touch sensor module, display panel, touch display panel, and touch display module is defined in IEC 62908-1-2.

## 2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60068-1, *Environmental testing - Part 1: General and guidance*

IEC 62908-1-2, *Touch and interactive displays - Part 1-2: Generic - Terminology and letter symbols*

## 3 Terms and definitions

For the purposes of this document, the terms and definitions given in IEC 60068-1 and IEC 62908-1-2 apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- IEC Electropedia: available at <https://www.electropedia.org/>
- ISO Online browsing platform: available at <https://www.iso.org/obp>

## 4 Measuring conditions

### 4.1 Standard measuring environmental conditions

Measurements shall be carried out under the standard environmental conditions:

- temperature: 25 °C ± 3 °C,
- relative humidity: 25 % RH to 85 % RH,
- atmospheric pressure: 86 kPa to 106 kPa.

When different environmental conditions are used, they shall be noted in the measurement report.

### 4.2 Standard atmospheric conditions for reference measurements and tests

If the parameters to be measured depend on temperature, pressure and humidity, and their dependence on temperature, pressure and humidity is unknown, the atmospheres to be specified shall be selected from the values shown in Table 1. The selected values shall be noted in the relevant specifications.

**Table 1 – Standard conditions for reference measurements and tests**

Temperature <sup>a</sup> °C	Relative humidity <sup>a, b</sup> % RH	Air pressure <sup>a</sup> kPa
(20, 25, 30, and 35) ± 3	45 to 75	86 to 106
<sup>a</sup> Including extreme values.		
<sup>b</sup> Absolute humidity ≤ 22 g/m <sup>3</sup> .		

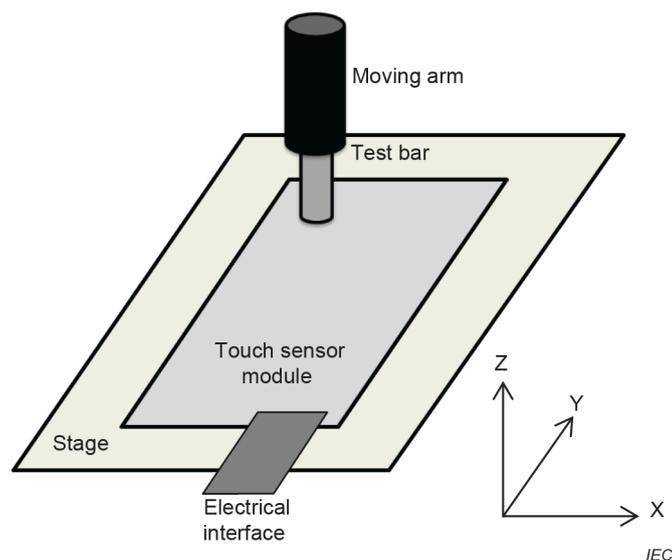
### 4.3 Standard positioning equipment and setup

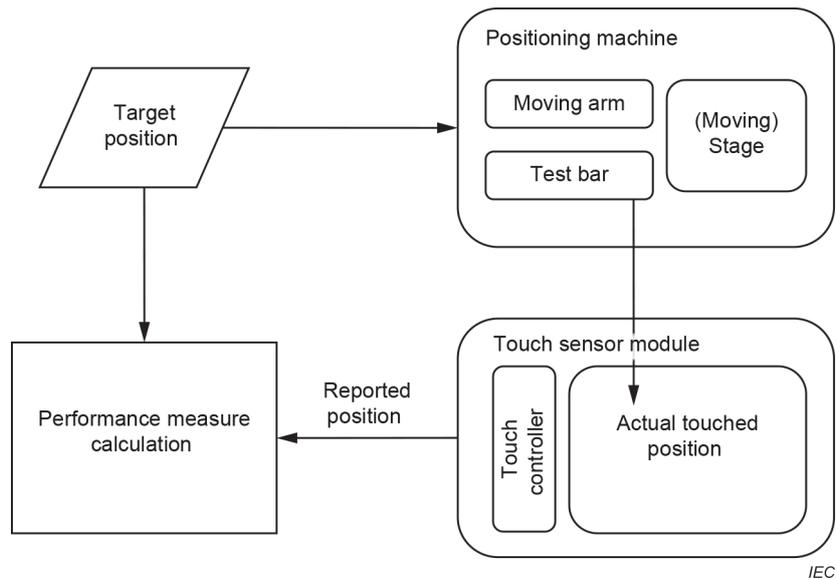
The standard positioning equipment for touch performance shall be the positioning machine equipped with a test bar, a moving arm, and a stage onto which the touch sensor module is placed, as shown in Figure 1. The positioning machine shall move its arm and stage to place the test bar on or over the touch sensor module.

There are three types of positions associated with a given test: target, actual and reported positions. The target position is a desired measurement location in physical space referenced to a fixed datum on or over the touch sensor module surface. The actual position is the actual location of contact or hovering during test, referenced to the same fixed datum, which can differ from the target position due to test bar placement error. The reported position is the location reported by the touch controller.

As shown in Figure 2, the reported positions from the touch controller are analysed to define performance measures with respect to the target positions.

The touch sensor module and the stage shall be aligned correctly while setting up the measurement equipment, because a misalignment between them can introduce coordinate shifts or rotation between the actual touch positions and target positions; each positioning machine has its inherent accuracy, which means that an actual touched position does not coincide with its target position. The performance measurements based on the target positions can include errors due to the accuracy of the positioning machine. The touch sensor module under test shall be attached to the stage and connected to the electrical interface. The test bar of the selected diameter shall be attached to the moving arm. In case of measurement of the pen touch performance, instead of the test bar, a selected touch pen (stylus pen) shall be attached to the moving arm.

**Figure 1 – Composition of test equipment**

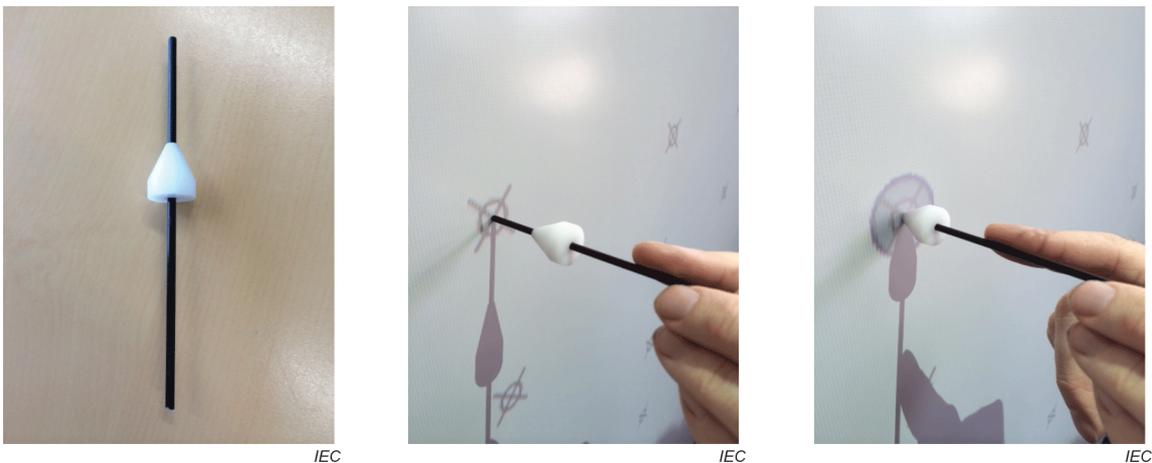


**Figure 2 – Concept of performance measurement**

#### 4.4 Human operator alternative to standard positioning equipment

Under certain circumstances, for example if the display under test is too large for suitable positioning equipment to be available, a suitably designed test arm may be manually positioned to enable completion of a subset of the tests described in this document. In this situation, it is important to design the test arm carefully to minimise the reasonable achievable error between actual and target positions when conducting measurements. An example of such a test arm can consist of a rod with a sliding tip (Figure 3, left), whose materials are chosen so that contact between the rod and the display does not trigger a touch event (Figure 3, middle), whereas contact between the sliding tip and the display does trigger a touch event (Figure 3, right). Such a test arm can be placed accurately and reliably by the human operator with the sliding tip away from the display, subsequent to which a measurement can be made by sliding the tip into contact with the display.

The human operator alternative is not recommended for hovering performance measurements because it is difficult to ensure the accuracy of positions, including the height.



**Figure 3 – Example of manual test tool (left), positioning without triggering a touch event (middle) and recording a touch event (right)**

#### 4.5 Test bar and touch pen

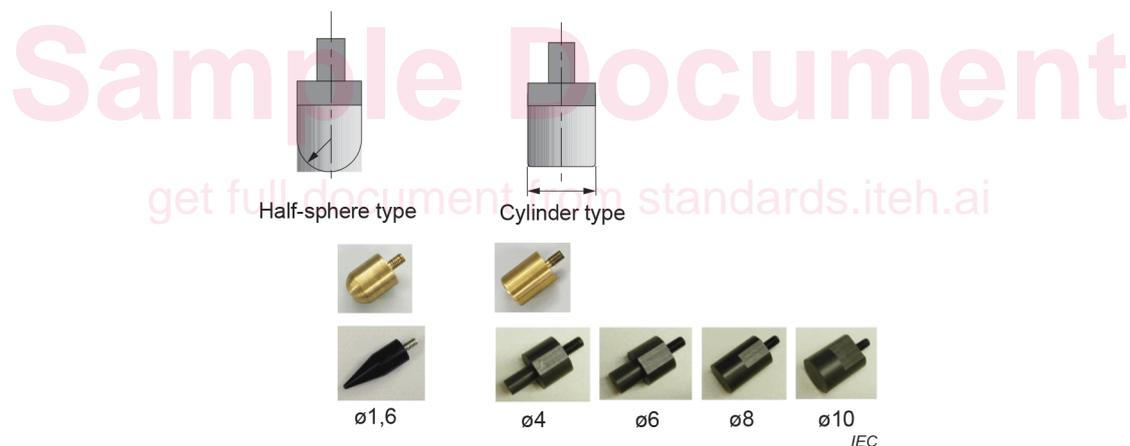
The parameters of the test bar shall be size, shape, and material. Examples of suitable sizes and shapes of the test bar are shown in Figure 4. The material of the test bars should be brass or conductive polyamide resin. The electrical resistivity of the test bars should be greater than  $10^2 \Omega \text{ cm}$  and less than  $10^4 \Omega \text{ cm}$ , and the hardness should be greater than R119. The material parameters for the test bar shall be appropriately chosen given the device category under test.

When the touch sensor module is a capacitive touch system, the test bar shall be electrically conductive and shall additionally be grounded in order to avoid potential performance degradation due to electrical noise, unless otherwise stated. A test bar may have an insulating layer on the base to model the effect of a gloved finger.

For reflection-based optical systems, the reflectivity of the contact end of the test bar shall be chosen to be spectrally representative of human skin.

In all cases, the appropriate properties (including size, shape and material) of the test bar shall be reported.

In case of measurement of the pen touch performance, the selected touch pen shall be applied instead of the test bar. The touch pen corresponding to the touch sensor module shall be selected, because there are several types of touch pens (see IEC TR 62908-1-3). The information of the selected touch pen and related properties (i.e. tilt angle of touch pen, pressure of touch pen, etc.) shall be reported.



NOTE  $\varnothing$  (test bar diameter) = 1,6 mm, 4 mm, 6 mm, 8 mm, or 10 mm.

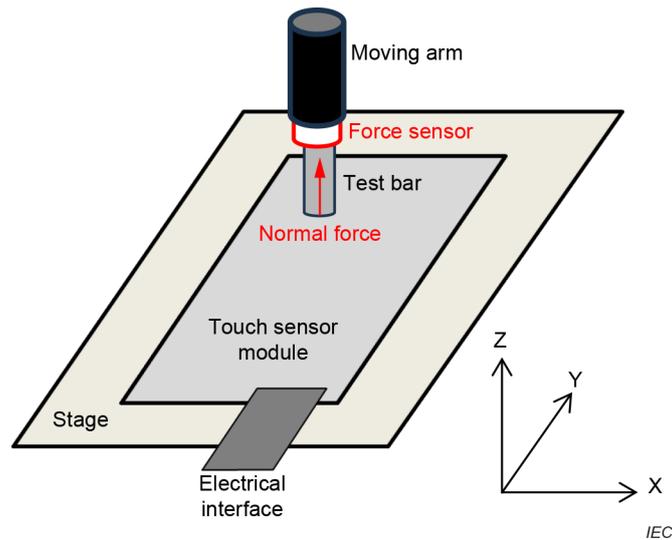
**Figure 4 – Examples of test bars**

#### 4.6 Equipment for measurement of force-output characteristics

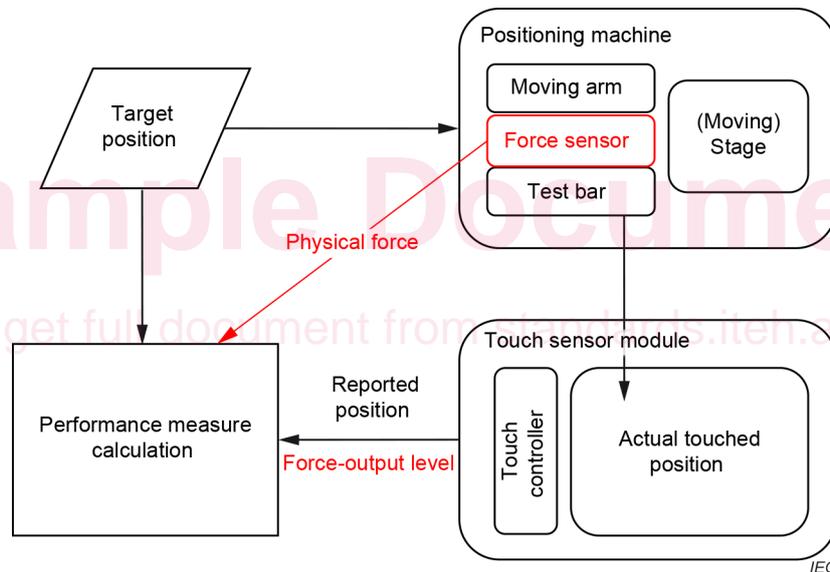
To measure the force-output characteristics of a force sensitive touch sensor modules, the positioning machine shall be equipped with a force sensor as shown in Figure 5 to detect physical force applied to the touch sensor module by measuring normal force from the touch sensor module. The resolution of the force sensor shall be smaller than 0,01 N or 1 gf (see ISO 7500-1).

The positioning machine shall move its moving arm in the direction vertically to the touch sensor module to vary the force applied to the touch sensor module. Then the physical force indicated by the force sensor and the force-output level, which is an output digital value from the touch sensor module, are used for the force-output characteristics test (see Figure 6).

NOTE According to the industry terminology, "force-output level" is also known as "pressure" or "pressure level".



**Figure 5 – Force sensor added to Figure 1 (in red) for measurement of force-output characteristics of a force sensitive touch sensor module**



**Figure 6 – Block diagram showing functions and data added to Figure 2 (in red) for force-output characteristics measurement**

## 5 Touch performance measurement methods

### 5.1 General

Fundamental touch performance measurement methods are described in Clause 5. They shall be applied during the characterization of a touch sensor module to provide a good user experience (see Annex A regarding electrical performance measurement methods of touch sensors.)

### 5.2 Accuracy test

#### 5.2.1 Purpose

The purpose of this test is to measure the ability of touch sensors and modules to indicate how close touch positions are reported relative to their target positions.

## 5.2.2 Test procedure

### 5.2.2.1 General

For the accuracy measurement, one of the following two methods can be selected. The first method is a straightforward method to evaluate the distance between each target point and its corresponding reported point. The second method is an indirect method where target grid points are estimated from reported points. This method can tolerate coordinate shifts which are caused by a misalignment between the touch sensor module and the stage while setting up the measurement equipment.

### 5.2.2.2 Method 1

The active area is defined as the area where touch is recognized. The centre area is defined as the rest of the active area without the edge area as shown in Figure 7. The edge area is defined as an area corresponding to the width ( $W$ ) of the edge of the active area. The origin and axis direction shall be defined.

The touch sensor module under test shall be attached to the stage and connected to the electrical interface. The test bar of the selected diameter size, shape and material shall be attached to the moving arm. For a precise measurement of the accuracy, the test equipment should be set up properly. The measurement points in the test grid are evenly spaced along both X and Y axes, away from the origin and spanning the whole active area of the touch sensor panel as shown in Figure 8.

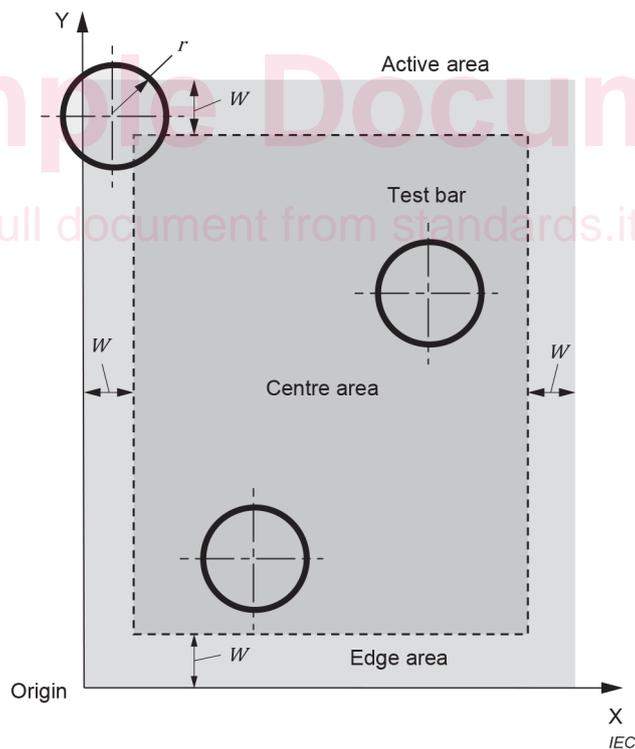
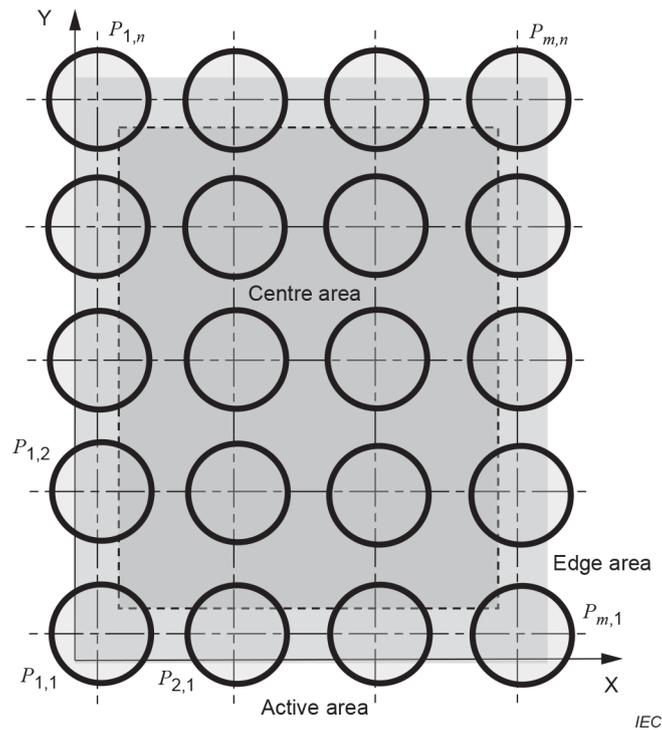


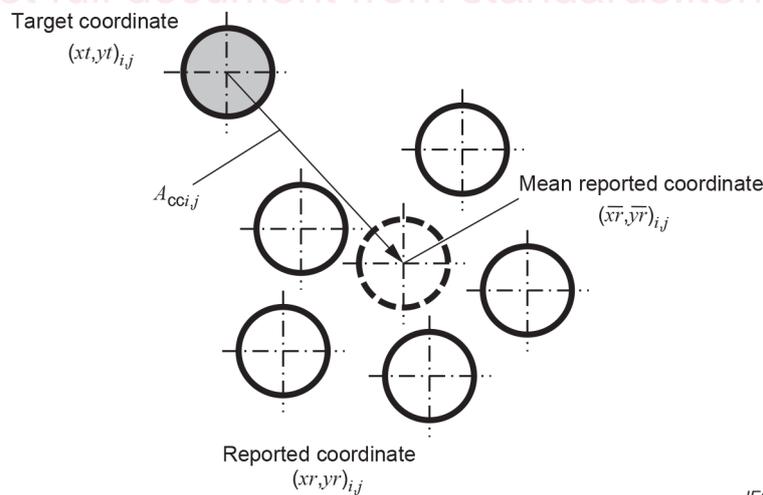
Figure 7 – Location of edge area and centre area



NOTE  $m, n$  correspond to the number of points in the X and Y directions.

**Figure 8 – Point grid**

At each target grid point  $(i, j)$ , lift the test bar down and up, and collect the touch reports  $p$  times. As shown in Figure 9, the accuracy is defined as the distance between the target coordinate and the mean reported coordinate.



**Figure 9 – Accuracy definition**

In the centre area, calculate the accuracy, that is, the maximum of accuracy, the standard deviation of accuracy and the average of accuracy, as shown in Formula (1) to Formula (5). In the edge area, the accuracy is calculated in the same manner.