
**Non-magnetic coatings on magnetic
substrates — Measurement of coating
thickness — Magnetic method**

*Revêtement métalliques non magnétiques sur métal de base
magnétique — Mesurage de l'épaisseur du revêtement — Méthode
magnétique*

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the WTO principles in the Technical Barriers to Trade (TBT) see the following URL: [Foreword - Supplementary information](#)

The committee responsible for this document is ISO/TC 107, *Metallic and other inorganic coatings*.

This third edition cancels and replaces the second edition (ISO 2178:1982), which has been technically revised.

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Non-magnetic coatings on magnetic substrates — Measurement of coating thickness — Magnetic method

1 Scope

This International Standard specifies a method for non-destructive measurements of the thickness of non-magnetizable coatings on magnetizable base metals.

The measurements are tactile and non-destructive on typical coatings. The probe or an instrument with integrated probe is placed directly on the coating to be measured. The coating thickness is displayed on the instrument.

In this International Standard the term “coating” is used for material such as, for example, paints and varnishes, electroplated coatings, enamel coatings, plastic coatings, powder coatings, claddings.

NOTE This method can also be applied to the measurement of magnetizable coatings on non-magnetizable base metals or other materials (see ISO 2361).

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 2064, *Metallic and other inorganic coatings — Definitions and conventions concerning the measurement of thickness*

ISO 4618, *Paints and varnishes — Terms and definitions*

ISO 5725-1:1994, *Accuracy (trueness and precision) of measurement methods and results — Part 1: General principles and definitions*

ISO/IEC Guide 98-3, *Uncertainty of measurement — Part 3: Guide to the expression of uncertainty in measurement (GUM:1995)*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 2064 and ISO 4618 and the following apply.

3.1

adjustment of a measuring system

set of operations carried out on a measuring system so that it provides prescribed indications corresponding to given values of a quantity to be measured

Note 1 to entry: Adjustment of a measuring system can include zero adjustment, offset adjustment, and span adjustment (sometimes called gain adjustment).

Note 2 to entry: Adjustment of a measuring system should not be confused with calibration, which is a prerequisite for adjustment.

Note 3 to entry: After an adjustment of a measuring system, the measuring system shall usually be recalibrated.

Note 4 to entry: Colloquially the term “calibration” is frequently but falsely used instead of the term “adjustment”. In the same way, the terms “verification” and “checking” are often used instead of the correct term “calibration”.

[SOURCE: ISO/IEC Guide 99:2007, 3.11 (also known as “VIM”), modified – Note 4 to entry has been added.]

3.2

calibration

operation that, under specified conditions, in a first step, establishes a relation between the quantity values with measurement uncertainties provided by measurement standards and corresponding indications with associated measurement uncertainties and, in a second step, uses this information to establish a relation to obtain a measurement result from indication

Note 1 to entry: A calibration may be expressed by a statement, calibration function, calibration diagram, calibration curve, or calibration table. In some cases, it may consist of an additive or multiplicative correction of the indication with associated measurement uncertainty.

Note 2 to entry: Calibration should not be confused with adjustment of a measuring system, often mistakenly called “self-calibration”, nor with verification of calibration.

Note 3 to entry: Often, the first step alone in the above definition is perceived as being calibration.

[SOURCE: ISO/IEC Guide 99:2007, 2.39 (also known as “VIM”)]

4 Principle of measurement

4.1 Basic principle of all magnetic measurement methods

The magnetic flux density close to a magnetic field source (permanent magnet or electromagnet) depends on the distance to a magnetizable base metal. This phenomenon is used to determine the thickness of a non-magnetic coating applied to the base metal.

NOTE 1 [Annex A](#) describes the physical background of this effect in more detail.

All the methods covered by this International Standard evaluate the magnetic flux density to determine the thickness of the coating. The strength of the magnetic flux density is converted into corresponding electrical currents, electrical voltages or mechanical forces depending on the method used. The values are either pre-processed by digital means or are directly displayed on a usefully scaled gauge.

NOTE 2 The methods described in [4.3](#) and [4.4](#) can also be combined in one and the same probe with another method, e.g. with the eddy current method according to ISO 2360 or ISO 21968.

[Annex B](#) describes the basic performance requirements for coating thickness gauges based on the magnetic method described in this International Standard.

4.2 Magnetic pull-off method

The magnetic flux density of a permanent magnet and thus the attraction force between a permanent magnet and a magnetizable base metal decreases with increasing distance. In this way, the attraction force is a direct measure for the coating thickness of interest.

Instruments working with the magnetic pull-off method consist of at least three units:

- a permanent magnet;
- a pull-off device with continuously increasing pull-off force;
- a display or scale for the coating thickness, which is calculated from the pull-off force.

The pull-off force can be generated by different types of springs or an electromagnetic device.

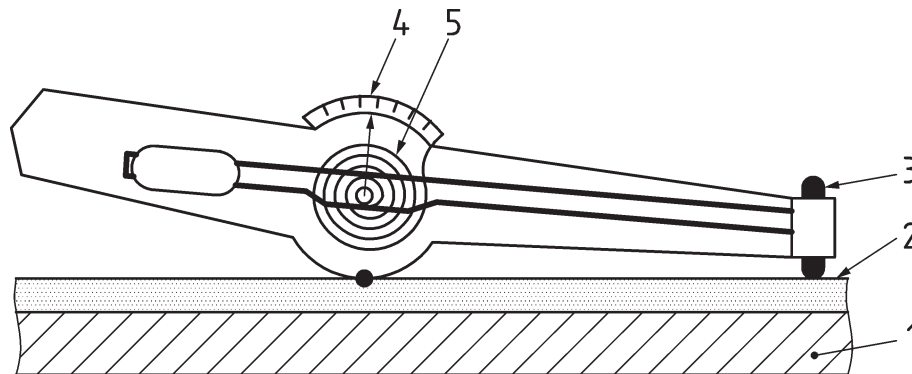
Some instruments are able to compensate the influence of gravity and allow measurements in all positions.

All other instruments may only be used in the position specified by the manufacturer.

The location of measurement shall be clean and free from liquid or pasty coatings. The permanent magnet shall be free from particles.

Electrostatic charging can cause additional forces on the permanent magnet or the measuring system and is therefore to be avoided or shall be discharged before the measurement.

[Figure 1](#) shows a magnetic pull-off gauge.



Key

- 1 base metal
- 2 coating
- 3 magnet
- 4 scale
- 5 spring

Figure 1 — Magnetic pull-off gauge

4.3 Magnetic inductive principle

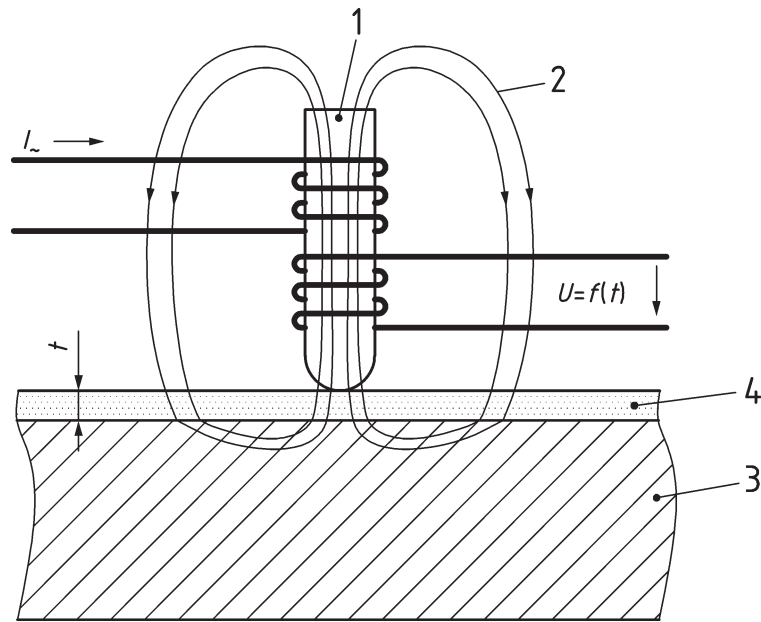
The electrical inductivity of a coil changes when an iron core is inserted into the coil or when an iron object, e.g. a plate, approaches the coil. Therefore, the electrical inductivity can be used as a measure of the distance between the coil and a ferromagnetic substrate or as a measure of the coating thickness, if the coil is placed onto a coated magnetizable base metal.

There are many different electronic methods to evaluate changes of the electrical inductivity or the reaction of a coil system to a ferromagnetic substrate. Magnetic induction probes for thickness measurements of coatings on magnetizable materials can consist of one or more coils. Most often two coils are used (see [Figure 2](#)): the first (primary coil) to generate a low frequency alternating magnetic field and the second (secondary coil) to measure the resulting induced voltage U . If the probe is placed on a coated magnetizable material ($\mu_r > 1$) the magnetic flux density (see [Annex A](#)) and the induced voltage of the secondary coil vary as a function of the coating thickness. The function between the induced voltage and the coating thickness is nonlinear and depends on the permeability μ_r of the base metal. It is usually determined by a calibration. Calibration curves that assign a coating thickness to the induced voltages can be stored in the gauge.

Different designs and geometries of these kind of probes are used. Very often both coils are employed together with a highly magnetizable core in order to increase the sensitivity of the probes and to concentrate the field. In this way, both the coating area, which contributes to the thickness measurement, and the influence of the geometry of the coated component are reduced (see [5.5](#) and [5.6](#)).

On the contrary, a two pole probe (see [Figure 3](#)) has a wide and open field distribution. The two-pole probe has area integrating properties, while a one-pole probe measures locally.

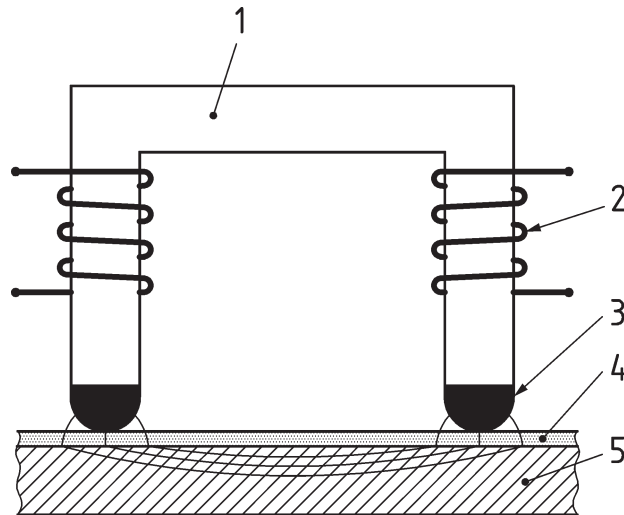
Usually the frequency of the generated field is below the kilohertz range, which avoids eddy current generation if the coatings are conductive. Therefore, both conductive and nonconductive coatings can be measured by means of this principle.



Key

- | | | | |
|---|--|------------|--------------------|
| 1 | iron core of the probe | I_{\sim} | exciting current |
| 2 | low frequency alternating magnetic field | t | coating thickness |
| 3 | steel/iron substrate | $U = f(t)$ | measurement signal |
| 4 | coating | | |

Figure 2 — Schematic of the magnetic induction principle

**Key**

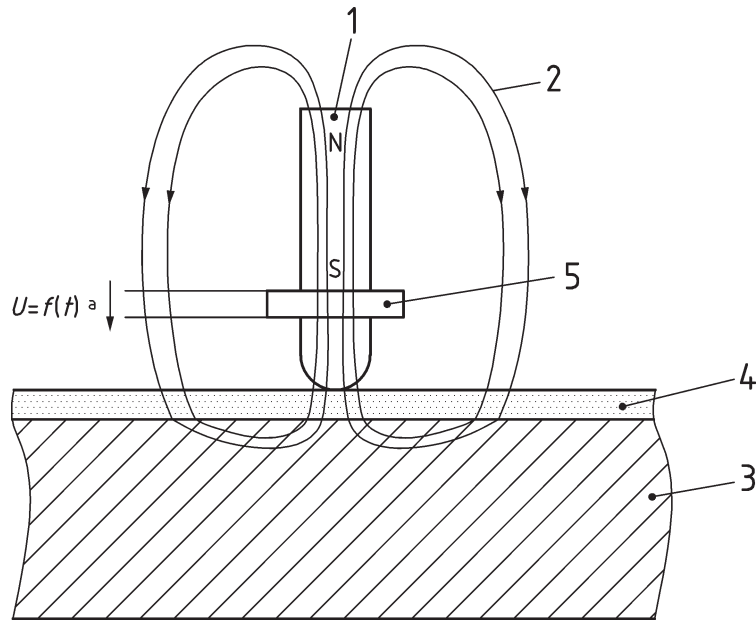
1	iron core of the probe	4	coating
2	coil system	5	base metal
3	probe tip		

Figure 3 — Schematic of a two pole probe**4.4 Magnetic flux gauge**

The magnetic flux density close to a magnet depends on the magnetic properties of the substances in the magnetic field. The magnetic flux density decreases if the fraction of non-magnetizable substances increases relative to magnetizable substances. This fact is used in magnetic flux gauges (see [Figure 4](#)). The coating (4) is non-magnetizable; the base metal (3) is magnetizable. A magnet (1) creates a magnetic field. Its field lines pass through both the coating and the base metal. A magnetic flux detector (5) placed close to the magnet outputs electrical signals, which depends on the coating thickness.

NOTE 1 Magnetic flux detectors are Hall-sensors or magneto resistive sensors.

NOTE 2 The magnet can be a permanent magnet or an electromagnet.



Key

- | | | | |
|---|--|-----|--------------------|
| 1 | permanent magnet | U | output voltage |
| 2 | static magnetic field | a | measurement signal |
| 3 | base metal | | |
| 4 | coating | | |
| 5 | Hall element as magnetic flux detector | | |

Figure 4 — Flux gauge using a Hall probe

The electric signals of the flux detector are further processed by electronic means. The function between flux detector output and the coating thickness is nonlinear and depends on the permeability μ_r of the base metal. It is usually determined by calibration. Calibration curves that assign a coating thickness to the electric detector output can be stored in the gauge.

5 Factors affecting measurement accuracy

5.1 Basic influence of the coating thickness

The sensitivity of a probe, i.e. the measurement effect, decreases with increasing thickness within the measurement range of the probe. In the lower measurement range this measurement uncertainty (in absolute terms) is constant, independent of the coating thickness. The absolute value of this uncertainty depends on the properties of the probe system and the used sample materials, e.g. the homogeneity of the base metal permeability, the base metal roughness and the sample surface roughness. In the upper measurement range of the probe the uncertainty becomes relative to the thickness and is approximately a constant fraction of that thickness.

5.2 Magnetic properties of the base metal

The permeability of the base metal causes the measurement effect of this method.

The relationship between coating thickness and the measured value depends strongly on the permeability of the base metal. Consequently, calibration procedures and measurements shall be made on the same material. Different materials with different permeabilities can cause more or fewer