



**International
Standard**

ISO 31657-3

**Plain bearings — Hydrodynamic
plain journal bearings under
steady-state conditions —**

**Part 3:
Characteristic values for calculation
of tilting pad journal bearings**

**First edition
2025-10**

iTeh Standards
(<https://standards.iteh.ai>)
Document Preview

ISO 31657-3:2025

<https://standards.iteh.ai/catalog/standards/iso/833c2adb-a2d9-486a-a53b-2bfl30ee2697/iso-31657-3-2025>

iTeh Standards
(<https://standards.iteh.ai>)
Document Preview

ISO 31657-3:2025

<https://standards.iteh.ai/catalog/standards/iso/833c2adb-a2d9-486a-a53b-2bfl30ee2697/iso-31657-3-2025>



COPYRIGHT PROTECTED DOCUMENT

© ISO 2025

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office
CP 401 • Ch. de Blandonnet 8
CH-1214 Vernier, Geneva
Phone: +41 22 749 01 11
Email: copyright@iso.org
Website: www.iso.org

Published in Switzerland

Contents

	Page
Foreword	iv
1 Scope	1
2 Normative references	1
3 Terms and definitions	1
4 Characteristic values for calculation of multi-lobed journal bearings	1
4.1 General.....	1
4.2 Tilting-pad journal bearings with four tilting pads.....	4
4.3 Tilting-pad journal bearings with five tilting pads.....	39
Annex A (informative) Characteristic curves for tilting-pad bearings with five pads	62
Bibliography	73

iTeh Standards
(<https://standards.iteh.ai>)
Document Preview

[ISO 31657-3:2025](https://standards.iteh.ai/catalog/standards/iso/833c2adb-a2d9-486a-a53b-2bfl30ee2697/iso-31657-3-2025)

<https://standards.iteh.ai/catalog/standards/iso/833c2adb-a2d9-486a-a53b-2bfl30ee2697/iso-31657-3-2025>

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

ISO draws attention to the possibility that the implementation of this document may involve the use of (a) patent(s). ISO takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, ISO had not received notice of (a) patent(s) which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at www.iso.org/patents. ISO shall not be held responsible for identifying any or all such patent rights.

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 123, *Plain bearings*, Subcommittee SC 8, *Calculation methods for plain bearings and their applications*.

This first edition of ISO 31657-3 cancels and replaces ISO/TS 31657-3:2020, which has been technically revised.

The main changes are as follows:

- the title has been modified;
- [Figure 1](#) has been updated.

A list of all parts in the ISO 31657 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Plain bearings — Hydrodynamic plain journal bearings under steady-state conditions —

Part 3: Characteristic values for calculation of tilting pad journal bearings

1 Scope

This document specifies the characteristic values for selected tilting-pad journal bearings with four or five centrally or eccentrically supported tilting pads, and with angular spans of pad sliding surfaces of $\Omega = 80^\circ$, 60° and 45° .

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 31657-1:2025, *Plain bearings — Hydrodynamic plain journal bearings under steady-state conditions — Part 1: Calculation of multi-lobed and tilting pad journal bearings*

3 Terms and definitions

No terms and definitions are listed in this document.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

4 Characteristic values for calculation of multi-lobed journal bearings

4.1 General

The characteristic values plotted and listed in this clause are required for the operationally safe design of hydrodynamic tilting-pad journal bearings in accordance with ISO 31657-1. They are based on the presumptions and boundary conditions indicated there and only apply to stationary operating states. The symbols used shall be in accordance with ISO 31657-1:2025, Table 1; calculation examples are also given in ISO 31657-1:2025, Annex A.

The calculation method described in ISO 31657-1 can also be used for other tilting-pad journal bearing designs, if the numerical solutions of the basic equations are available in the same manner for these designs.

NOTE Equivalent calculation procedures exist that enable operating conditions to be estimated and checked against acceptable conditions. Another calculation procedure is equally admissible.

The characteristic values for symmetrically loaded tilting-pad journal bearings with four and five centrally (relative angular distance between leading edge and pivot position of pad $\Omega_F^* = 0,5$) or eccentrically ($\Omega_F^* = 0,6$) supported tilting pads are indicated.

The characteristic values were calculated for the geometrical parameters summarised in [Figure 1](#) (angular spans of pad sliding surface Ω , angular coordinates of pivot position of pad $\phi_{F,1}$, profile factors K_p , bearing width ratios B^*) in the operating range $0,02 \leq h_{\min}^* \leq 1$. The following (dimensionless) characteristic values are individually listed from [Tables 1](#) to [56](#):

a) Static characteristic values

The Sommerfeld number is given as [Formula \(1\)](#):

$$So = \frac{F \cdot \psi_{\text{eff}}^2}{B \cdot D \cdot \eta_{\text{eff}} \cdot \omega} \quad (1)$$

The relative eccentricity is given as [Formula \(2\)](#):

$$\varepsilon = \frac{e}{C_{R,\text{eff}}} \quad (2)$$

Attitude angle β in °C.

For the product of maximum lubricant film pressure parameter and Sommerfeld number, see [Formula \(3\)](#):

$$p_{\max}^* \cdot So = \frac{p_{\max} \cdot \psi_{\text{eff}}^2}{\eta_{\text{eff}} \cdot \omega} \quad (3)$$

For the minimum relative lubricant film thickness, see [Formula \(4\)](#):

$$h_{\min}^* = \frac{h_{\min}}{C_{R,\text{eff}}} \quad (4)$$

For the friction force parameter, see [Formula \(5\)](#):

$$F_f^* = \frac{f}{\psi_{\text{eff}}} \cdot So \quad (5)$$

For the lubricant flow rate parameter due to hydrodynamic pressure build-up, see [Formula \(6\)](#):

$$Q_3^* = \frac{Q_3}{Q_0} \quad (6)$$

For the lubricant flow rate parameter due to supply pressure, see [Formula \(7\)](#):

$$Q_p^* = \frac{Q_p}{P_{\text{en}}^* \cdot Q_0} \quad (7)$$

For the lubricant flow rate parameter at the exit of the lubricant gap, see [Formula \(8\)](#):

$$Q_2^* = \frac{Q_2}{Q_0} \quad (8)$$

For non-dimensional difference between maximum temperature of lubricant film and lubricant temperature in the lubricant pocket, see [Formula \(9\)](#):

$$\Delta T_{\max}^* = \frac{\rho \cdot c_p \cdot \psi_{\text{eff}}}{\bar{p} \cdot f} \cdot \Delta T_{\max} \quad (9)$$

b) Dynamic characteristic values

For non-dimensional lubricant film stiffness coefficients, see [Formula \(10\)](#):

$$c_{i,k}^* = \frac{\psi_{\text{eff}}^3}{2 \cdot B \cdot \eta_{\text{eff}} \cdot \omega} \cdot c_{i,k} \quad (i, k = 1, 2) \quad (10)$$

For non-dimensional lubricant film damping coefficients, see [Formula \(11\)](#):

$$d_{i,k}^* = \frac{\psi_{\text{eff}}^3}{2 \cdot B \cdot \eta_{\text{eff}} \cdot \omega} \cdot \omega \cdot d_{i,k} \quad (i, k = 1, 2) \quad (11)$$

For some selected tilting-pad journal bearings ($\Omega_F^* = 0,6$, $\Omega = 45^\circ$, $\varphi_{F,1} = 36^\circ$), these characteristic values are shown graphically as a function of the Sommerfeld number, So , and the profile factor, K_p in [Annex A, Figures A.1 to A.11](#).

iTeh Standards (<https://standards.itih.ai>) Document Preview

[ISO 31657-3:2025](#)

<https://standards.itih.ai/catalog/standards/iso/833c2adb-a2d9-486a-a53b-2bfl30ee2697/iso-31657-3-2025>